## CS 294-5: Statistical Natural Language Processing



Speech Recognition II Lecture 21: 11/29/05

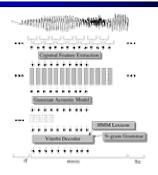
Slides directly from Dan Jurafsky, indirectly many others

## The Noisy Channel Model

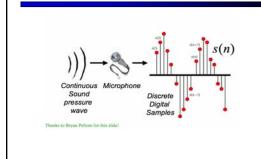


- Search through space of all possible sentences.
- Pick the one that is most probable given the waveform.

## Speech Recognition Architecture

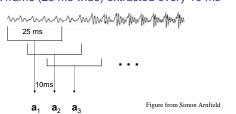


## **Digitizing Speech**



## Frame Extraction

A frame (25 ms wide) extracted every 10 ms

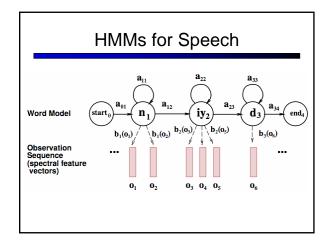


## Mel Freq. Cepstral Coefficients

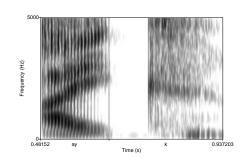
- Do FFT to get spectral information
  - Like the spectrogram/spectrum we saw earlier
- Apply Mel scaling
  - Linear below 1kHz, log above, equal samples above and below 1kHz
  - Models human ear; more sensitivity in lower freqs
- Plus Discrete Cosine Transformation

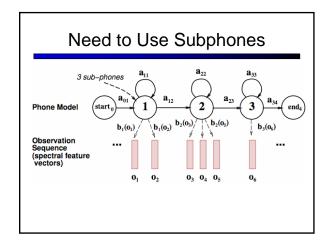
## Final Feature Vector

- 39 (real) features per 10 ms frame:
  - 12 MFCC features
  - 12 Delta MFCC features
  - 12 Delta Delta MFCC features
  - 1 (log) frame energy
  - 1 Delta (log) frame energy
  - 1 Delta Delta (log frame energy)
- So each frame is represented by a 39D vector

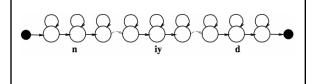


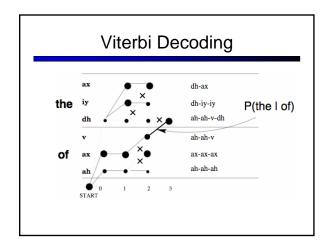
## Phones Aren't Homogeneous





## A Word with Subphones





## 

### HMMs for Continuous Observations?

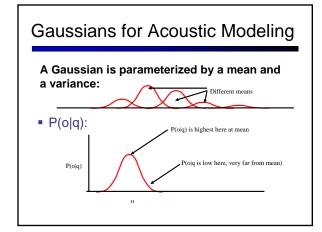
- Before: discrete, finite set of observations
- Now: spectral feature vectors are real-valued!
- Solution 1: discretization
- Solution 2: continuous emissions models
  - Gaussians
  - Multivariate Gaussians
  - Mixtures of Multivariate Gaussians
- A state is progressively:
  - Context independent subphone (~3 per phone)
  - Context dependent phone (=triphones)
  - State-tying of CD phone

## Vector Quantization Idea: discretization Map MFCC vectors onto discrete symbols Compute probabilities just by counting This is called Vector Quantization or VQ Not used for ASR anymore; too simple Useful to consider as a starting point

## Gaussian Emissions

- VQ is insufficient for real ASR
- Instead: Assume the possible values of the observation vectors are normally distributed.
- Represent the observation likelihood function as a Gaussian with mean  $\mu_i$  and variance  $\sigma_i^2$

$$f(x \mid \mu, \sigma) = \frac{1}{\sigma \sqrt{2\pi}} \exp(-\frac{(x - \mu)^2}{2\sigma^2})$$



## Multivariate Gaussians

Instead of a single mean μ and variance σ:

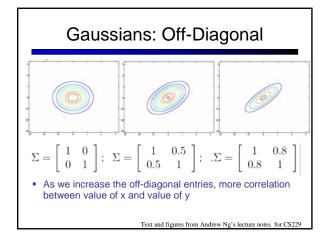
$$f(x \mid \mu, \sigma) = \frac{1}{\sigma \sqrt{2\pi}} \exp(-\frac{(x - \mu)^2}{2\sigma^2})$$

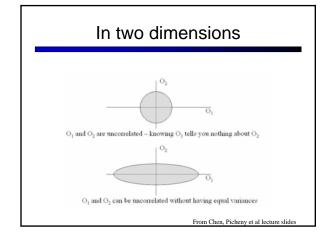
• Vector of means  $\mu$  and covariance matrix  $\Sigma$ 

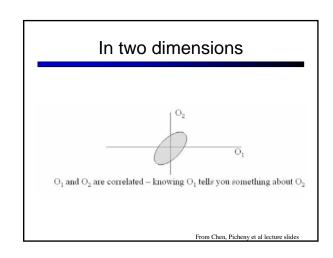
$$f(x \mid \mu, \Sigma) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu)^{T} \Sigma^{-1}(x - \mu)\right)$$

- Usually assume diagonal covariance
  - This isn't very true for FFT features, but is fine for MFCC features

# Gaussian Intuitions: Size of $\Sigma$ • $\mu = [0\ 0]$ $\mu = [0\ 0]$ $\mu = [0\ 0]$ • $\Sigma = 1$ $\Sigma = 0.61$ $\Sigma = 21$ • As $\Sigma$ becomes larger, Gaussian becomes more spread out; as $\Sigma$ becomes smaller, Gaussian more compressed







# But we're not there yet Single Gaussian may do a bad job of modeling distribution in any dimension: Bad News!!! Solution: Mixtures of Gaussians Figure from Chen, Picheney et al slides

## ■ M mixtures of Gaussians: $f(x \mid \mu_{jk}, \Sigma_{jk}) = \sum_{k=1}^{M} c_{jk} N(x, \mu_{jk}, \Sigma_{jk})$ $b_{j}(o_{t}) = \sum_{k=1}^{M} c_{jk} N(o_{t}, \mu_{jk}, \Sigma_{jk})$ ■ For diagonal covariance: $b_{j}(o_{t}) = \sum_{k=1}^{M} \frac{c_{jk}}{2\pi^{\frac{D}{2}} \prod_{j \neq k}^{D} \sigma_{jkd}^{2}} \exp(-\frac{1}{2} \sum_{d=1}^{D} \frac{(x_{jkd} - \mu_{jkd})^{2}}{\sigma_{jkd}^{2}})$

Mixtures of Gaussians

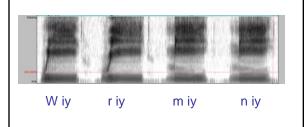
### **GMMs**

- Summary: each state has a likelihood function parameterized by:
  - M Mixture weights
  - M Mean Vectors of dimensionality D
  - Fither
    - M Covariance Matrices of DxD
  - Or more likely
    - M Diagonal Covariance Matrices of DxD which is equivalent to
    - M Variance Vectors of dimensionality D

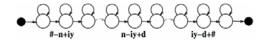
## **Training Mixture Models**

- Forced Alignment
  - Computing the "Viterbi path" over the training data is called "forced alignment"
  - We know which word string to assign to each observation sequence.
  - We just don't know the state sequence.
  - So we constrain the path to go through the correct words
  - And otherwise do normal Viterbi
- Result: state sequence!

## Modeling phonetic context



## "Need" with triphone models

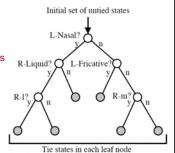


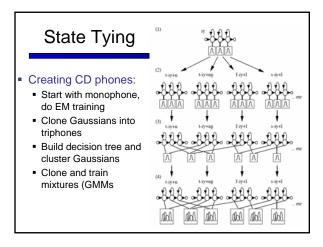
### Implications of Cross-Word Triphones

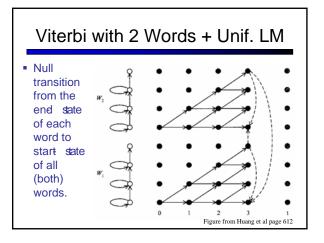
- Possible triphones: 50x50x50=125,000
- How many triphone types actually occur?
- 20K word WSJ Task (from Bryan Pellom)
  - Word-internal models: need 14,300 triphones
  - Cross-word models: need 54,400 triphones
  - But in training data only 22,800 triphones occur!
- Need to generalize models.

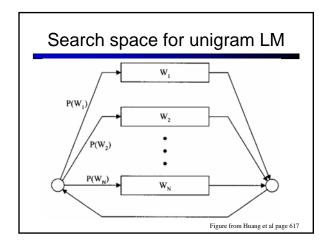
## State Tying / Clustering

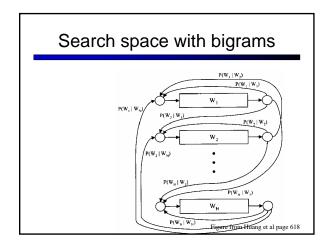
- [Young, Odell, Woodland 1994]
- How do we decide which triphones to cluster together?
- Use phonetic features (or 'broad phonetic classes')
  - Stop
  - NasalFricative
  - Sibilant
  - SibilarVowel
  - Vowellateral











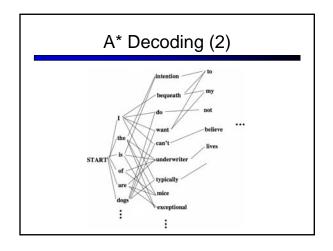
## Speeding things up

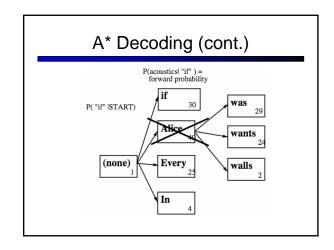
- Viterbi is O(N<sup>2</sup>T), where N is total number of HMM states, and T is length
- This is too large for real-time search
- A ton of work in ASR search is just to make search faster:
  - Beam search (pruning)
  - Fast match
  - Tree based lexicons

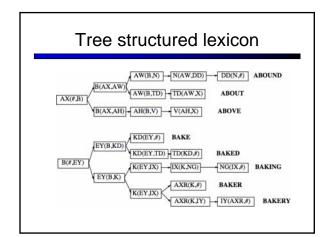
## Beam Search

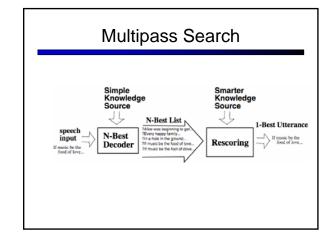
- Most common strategy (still!)
- Just like earlier in the term
- Instead of retaining all candidates at every time frame
  - Use a threshold T to keep subset
  - At each time t

    - Identify state with lowest cost D<sub>min</sub>
       Each state with cost > D<sub>min</sub>+ T is discarded ("pruned") before moving on to time t+1
- Empirically, beam size of 5-10% of search space
- 90-95% of HMM states don't have to be considered
- Vast savings in time

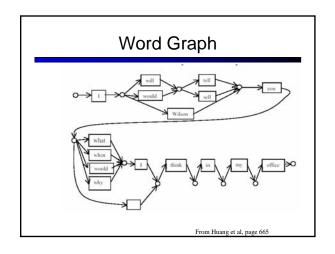








# N-best list 1. I will tell you would I think in my office 2. I will tell you what I think in my office 3. I will tell you when I think in my office 4. I would sell you would I think in my office 5. I would sell you what I think in my office 6. I would sell you when I think in my office 7. I will tell you would I think in my office 8. I will tell you why I think in my office 9. I will tell you what I think on my office 10. I Wilson you I think on my office



## One-pass vs. multipass

- Potential problems with multipass
  - Can't use for real-time (need end of sentence)
    - (But can keep successive passes really fast)
  - Each pass can introduce inadmissible pruning
    - (But one-pass does the same w/beam pruning and fastmatch)
- · Why multipass
  - Very expensive KSs. (NL parsing,higher-order n-gram, etc)
    Spoken language understanding: N-best perfect interface

  - Research: N-best list very powerful offline tools for algorithm development
  - N-best lists needed for discriminant training (MMIE, MCE) to get rival hypotheses