

PRICE OF ANARCHY

$$PoA = \frac{\max_{a \text{ equilibrium}} \sum c_i(a)}{\min_a \sum c_i(a)}$$

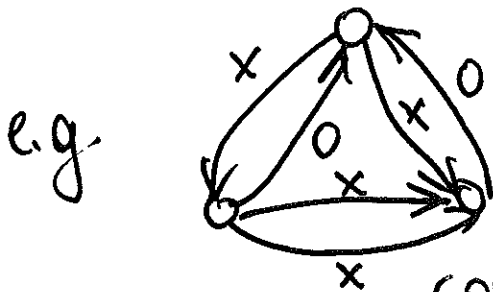
Assume minimization problem

objective = sum of agents' objectives

- Q: • what equilibrium? (Nash, later, correlated, max)
- why unweighted sum (context often supports it)
 - why didn't economists study it?

(Atomic) Congestion Game

- 4 flows
- 1: $a \rightarrow b$
 - 2: $a \rightarrow c$
 - 3: $b \rightarrow c$
 - 4: $c \rightarrow b$



congestion fn $x : (1, 2, 3, 4)$

pure Nash eq. exists: potential fn

$$\Phi(a) = \sum_e \sum_{j=1}^{f_e(a)} c_e(y_j)$$

choice of paths resulting in flow $f(a)$

Potential game

Note: $\Phi(a) - \Phi(a') = c_i(a) - c_i(a')$

flow after defection of $i \Rightarrow$ pure Nash eq always exists!

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Example has two ^{pure} Nash eq.

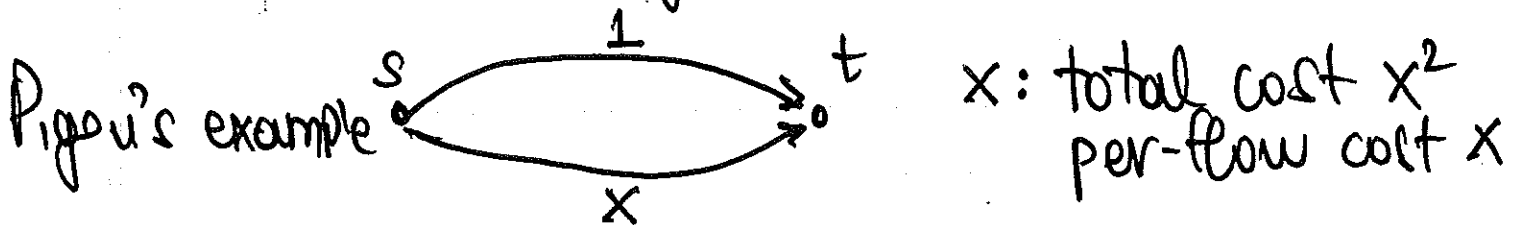
Single hop $\rightarrow \sum_i c_i \cdot (a_i) = 4$

Double hop \rightarrow = 10
(also a Nash eq!)

PoA = 2.5. This is worst possible!
(see below)

Note: It does make sense to want to optimize unweighted sum of time wanted, energy, etc.

Non-atomic flow: A large population of agents of total volume 1 want to go from s to t
continuum of agents / drivers

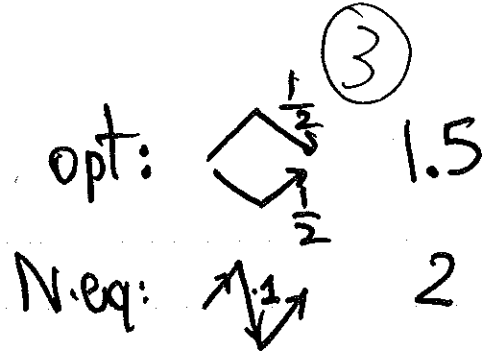
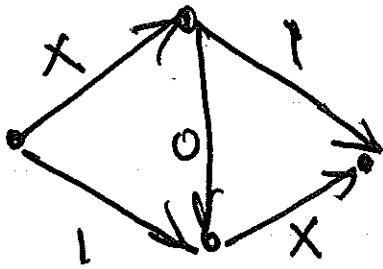


Only Nash eq:  cost 1

optimum?  $\min 1-f+f^2 \Rightarrow f = \frac{1}{2}$

PoA = $\frac{3}{4}$. Worst possible!
cost = $\frac{3}{4}$

Braess's Paradox



p.o.A = $\frac{4}{3}$ coincidence?

What do we know about optimum and Nash eq. flows in such networks?

various kinds of costs

$C_e(x) = x \cdot c_e(x)$ (assume increasing) cost per unit of flow

$C_e^*(x) = C_e'(x) = c_e(x) + x \cdot c_e'(x)$ cost (convex) marginal cost

Thm A Nash eq. flow is optimum flow in the C_e^* that it creates. That is, all used paths have equal C_e^* length, all unused ones worse.

In Pigeon, Braess: x^* (eq) Nash equalizes path lengths.

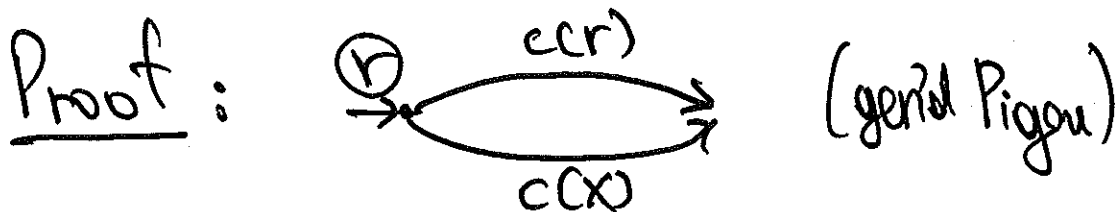
Thm Equilibrium flow iff global minimum of $\sum_e \int_0^{f_e(x)} c_e(x) dx = \Phi(x)$

Proof: $x \cdot c_e(x) \iff \int_0^{f_e(x)} c_e(x) dx$

Cor: Equilibrium exists, its cost is unique (because cost is convex comb.)

Notice immediately: for some fixed class of congestion fns

$$PoA \geq B = \max_{c \in \mathcal{C}; x, r \geq 0} \frac{c(r)}{x \cdot c(x) + (K-x) \cdot c(r)}$$



Note: for $\mathcal{C} = \{ax+b : a, b \geq 0\}$, $B = \frac{4}{3}$ (b?)

$$B \geq \frac{f^* c(f^*)}{\hat{f} c(\hat{f}) + (f^* - \hat{f}) c(\hat{f})} \quad \left[\begin{array}{l} \text{set } r = f^* = \text{eq} \\ \hat{f} = \text{opt} \end{array} \right]$$

or
$$\hat{f} c(\hat{f}) + \underbrace{c(f^*)(f^* - \hat{f})}_{\leq 0} \geq \frac{1}{B} (f^*) f^*$$

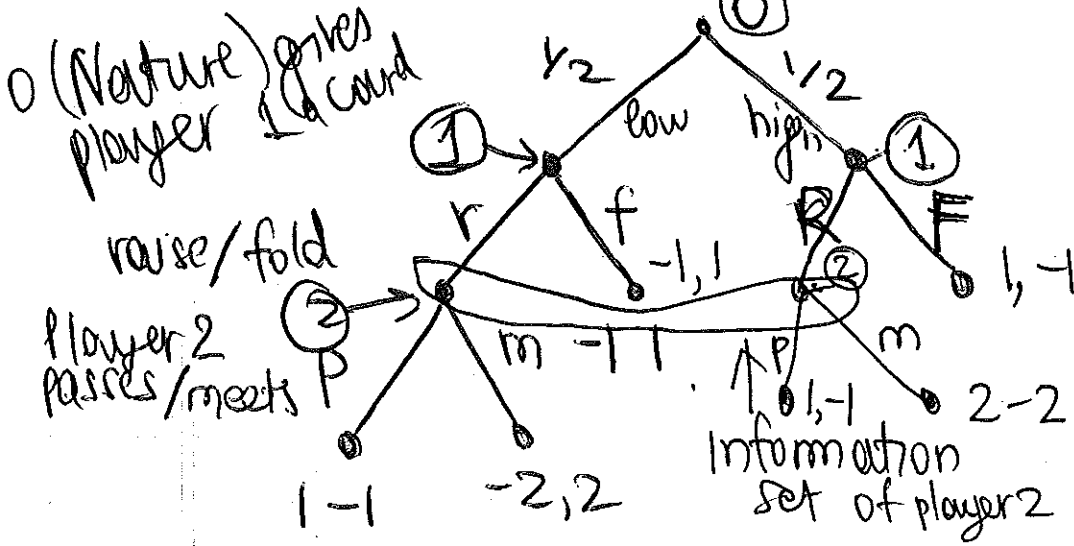
because f^* is eq. QED

$\therefore B = PoA!$

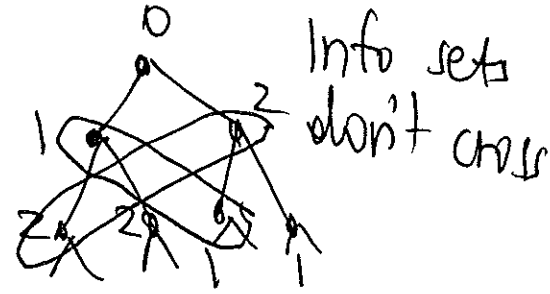
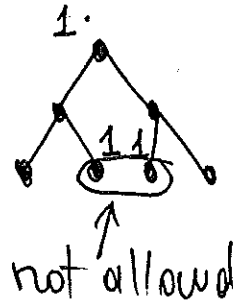
Amazing fact: PoA is determined by the class \mathcal{C} , not by the network. Always attained at the trivial network!

EXTENSIVE FORM GAMES

(We must include chess in our games...)



Important restrictions on the trees: Perfect & info sets: recall



Can be reduced to the table form. But there are issues the reduction is exponential in general. And Nash eq. is too good here!

	m	p
f	0,0	0,0
r	$-\frac{1}{2}, \frac{1}{2}$	1,-1
F	$\frac{1}{2}, -\frac{1}{2}$	0,0
R	0,0	1,-1

What is a mixed strategy?

Q: Can you see why we can go the other way?
table form \rightarrow extensive form

- \rightarrow mixing all rows/w/ (exponential)
- \rightarrow behavioral (mix at each info set)
- \rightarrow sequence trick (von Stengel, Kohler)

Sequence trick [Kohler + von Stengel 93]

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Notation H_i info sets for player i
 $h \in H_i$ has A_h (available actions)
 next: $H_i \times A_h \rightarrow H_i \cup \{\text{leaves}\}$

this is the "tree" valid because of perfect recall (depending on i)
 Assign probabilities to the h 's (prob of getting there)

for the topmost $h \in H_i$, $x_i(h) = \text{const}$ (depends on player i)

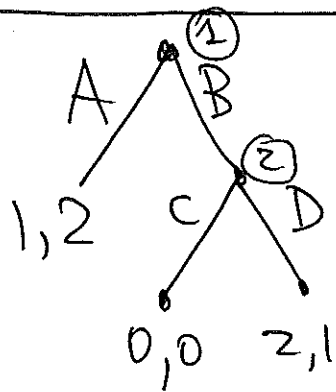
$$x_i(h) = \sum_{a \in A_h} x_i(\text{next}(h, a)) \quad [\text{linear!!}]$$

We can now write the expected payoff of a mixed action profile:

$$E[u_i] = \sum_{l \in \text{Leaves}} u_i(l) \prod_{l=1}^n x_i(l)$$

Now we can solve by LP zero-sum two-person games... (like poker!)

Nash is no good!



	C	D
A	(1, 2)	1, 2
B	0, 0	(2, 1)

Two Nash eq
 Upper-left is "empty threat!"

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Solution: Subgame ^{Perfect} Nash eq.

Subgame: ~~General~~ subtree closed under info sets

SpNash: A Nash eq. that is also a Nash eq when restricted to any subgame

No info sets: Nash eq. can be computed easily, and is subgame perfect; by DP from the leaves up (backward induction or Zermelo's algorithm).

Info sets: Same idea. Compute Nash eq. of subtrees bottom up. Replace subtrees by payoffs of Nash eq. on a leaf. Continue.

Another solution Trembling hand Nash eq.

A Nash eq x such that there is a sequence (x_j) of ϵ -fully mixed "Nash eq" (all strategies best responses under the constraints $x_i \geq \epsilon^i > 0$), such that $x_j \rightarrow x$.

Algorithm? Conjecture: Find ϵ -fully mixed Nash eq with $\epsilon_i = 2^{-n^2}$. Round down/up

Third fix Sequential Equilibrium / Game theorists consider it the "final" solution concept

For every info set a set of "beliefs" β_h and a (behavioral) mixed strategy x_h . β_h is a distribution over all paths to h ("how did I get here?"). x_h should be best response assuming β .

Furthermore: Sequence of (x^j, β^j) such that $x^j \rightarrow x, \beta^j \rightarrow \beta, x^j$ fully mixed, β^j derived from x^j via Bayes rule...

Algorithm ? Open

Bayesian Games

- player i : actions A_i
- types T_i
- utility $u_i: \prod_j A_j \times \prod_j T_j \rightarrow \mathbb{R}$
- prior: $\pi_i \in \Delta \prod_j T_j$

Example: Vickrey auction!

Reduce to table form: $B_i: T_i \rightarrow A_i$, action set, payoffs
 $u_i(b_1..b_n) = E_{\pi_i} [u_i(b_j(t_j), t_j, j=1..n)]$

Theorem In Vickrey, $b_i =$ the identity function is dominant.

Harsanyi's Theorem (justification of mixed Nash eq)

For almost all games G there is a sequence of Bayesian games G_j such that $G_j \rightarrow G$ and the equilibria of G_j converge to the equilibrium of G
 payoffs of \hat{G} : $u_{ij} + \epsilon_{ij}^k \leftarrow$ (perturbed)

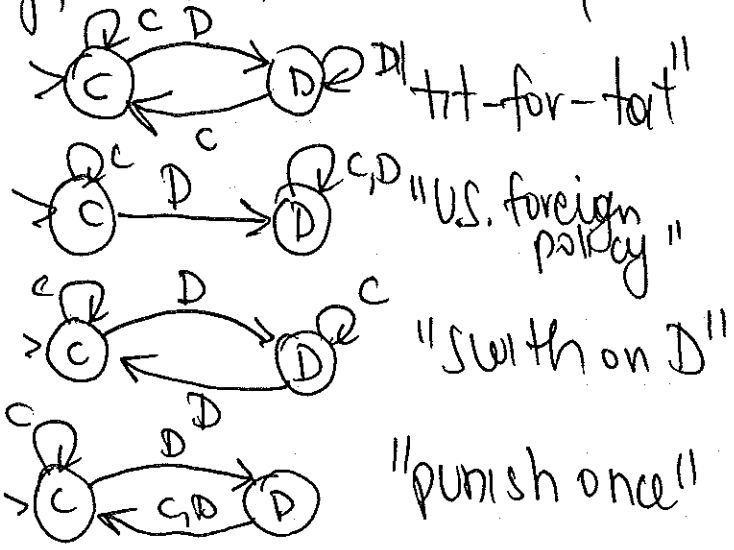
Another special case: Repeated Games

Repeat Prisoner's Dilemma n times!

Fact: Defect n times is the only Nash eq (backwards induction)

One path taken in the 1980's-1990's: Assume players are limited. eg, automata with few states!

2 states: 4 possible strategies undominated



$< n$ states: collaborate possible, not enough states to count to n & start backwards induction...

$\geq 2^n$ states D-D (enough states to run the DP algorithm - too smart for their own good)

poly(n) complicated collaboration... [Pap. + Kuhnatakis, Stoc 94]

Infinite repetition $\hat{A}_i = \left(\bigcup_{t=0}^{\infty} A^t \rightarrow A_i \right)$

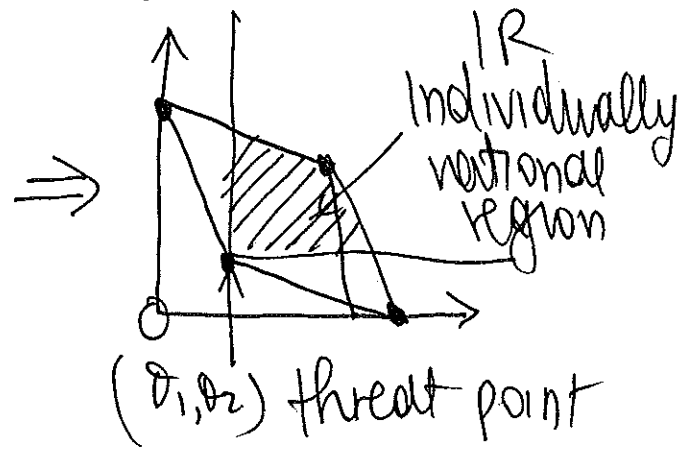
$$u_i(t) = \sum_{t=1}^{\infty} u_i(a(t)) \cdot (1-\delta)^t$$
 defines $a(t)$
 \uparrow discount factor.

look at your history of all players, decide what to do next.

Important Insight: The Folk Theorem (Shapley, Aumann, Maskin ~1970's-80's)

PD

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$$d_i = \min_{a_{-i}} \max_{a_i} u_i(a) \text{ in one-shot game}$$

Thm Any rational ($= P/q$) point in $\mathbb{R} \geq 0$ can be realized by repeated play (including C-C in PD). (R)

Proof: Realize it by periodic play. If anybody defects, the rest will punish him!

(Objection: not subgame perfect. Subgame perfect version: punish n times, if anybody defects from that punish them n^2 times, etc.)

for two players can be realized.

(because $\theta_1 = \min \max (-B, B)$)

But > 2 players? [turns out that computing θ_i is NP-hard...]

Thm Finding an eq. in repeated game (i.e., any point in $\mathbb{R} \dots$) is on hand as in ~~the~~ one-shot games

Proof. Take k -player game G . Create $(k+1)$ -player game \tilde{G} with player $k+1$ (the "kibitzer"). $A_{k+1} = \{(y, a) : a \in A_j\}$

$$u_i(a, (y, b)) = \begin{cases} 0 & \text{if } i \neq k+1, j \\ u_j(b, a_{-i}) - u_j(a) & \text{if } i = k+1 \\ u_j(a) - u_j(b, a_{-i}) & \text{if } i = j \end{cases}$$

\uparrow player $i \leq k \in A_j$

At equilibrium, k players will play a Nash eq. of the one-shot game...

Coalitional Games

$[n]$ players. $v: 2^{[n]} \rightarrow \mathbb{R}^+$
 $v[S]$: the worth of coalition S .
assumptions $v(\emptyset) = 0, \sum_{S \in \pi} v(S) \leq v([n])$
partition of $[n]$

In games, atom of behavior = action of player
Here, what a coalition does

Basic question: How do the n players split $v([n])$?

One solution concept: the core
Imputation: x_i with $\sum x_i = v([n])$
or payoff profile
feasible S -feasible: $\sum x_i = v(S)$

x is in the core iff there is no "defection", coalition S and S -feasible y s.t. $y_i > x_i \forall i \in S$.

Ex 1 $v([3]) = 1, v(S) = \alpha$ if $|S|=2, v(S) = 0$ if $|S| \leq 1$.

Ex 2 How should n cities split road maintenance costs?

Ex 3 Voting $v(S) = \begin{cases} 0 \\ < 1 \end{cases}$ either core = \emptyset or there is a veto player!

Ex 4 Game G , n players. Define $v(S) = \min_{T \supset S} \max_S \sum_{i \in S} u_i$
the bottom-line total utility players in S can guarantee for themselves

Ex 5 A trip to n destinations. How do you apportion the airfare to the n hosts?

Shapley value

$$s_i = \frac{1}{n!} \sum_{\pi \in S_n} v(\{j: \pi(j) \leq \pi(i)\}) - v(\{j: \pi(j) < \pi(i)\})$$

Thm. If the core is nonempty, $s \in \text{core}$

Thm s is the unique value satisfying the balanced contributions property:

$$s_i([n]) - s_i([n] - \{j\}) = s_j([n]) - s_j([n] - \{i\})$$

Also: Symmetry, additivity, dummy player