

# Accelerating Mesoscale Molecular Simulation using CUDA and MPI

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CS267 poster / talk  
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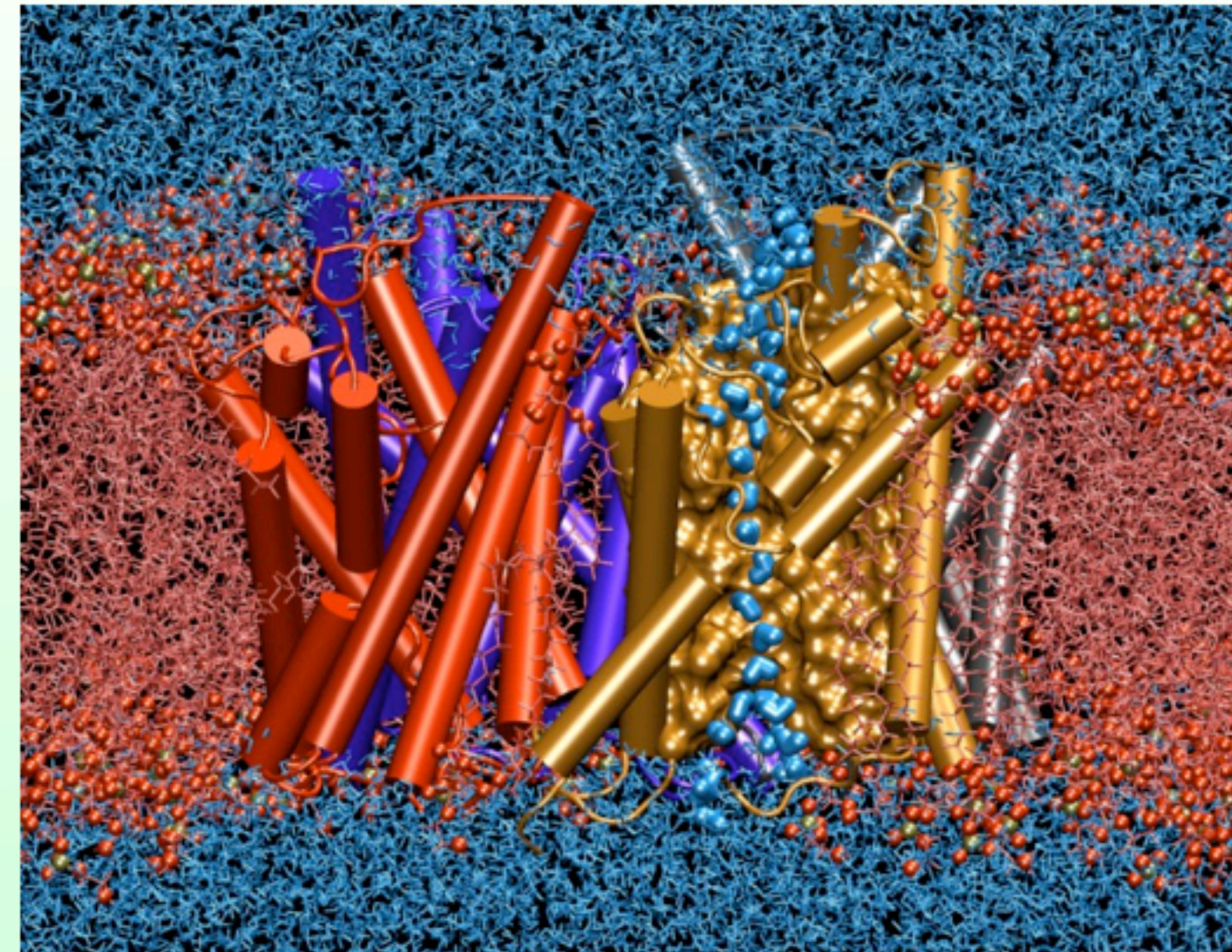
# Molecular dynamics (MD): Intrinsic strengths and weaknesses

## Strengths

- All-atom representation gives high chemical detail.
- Quantitative information (in physical units) can be gathered about a system.
- Many standard tools (including parallel ones) have been refined over the course of many years.

## Weaknesses

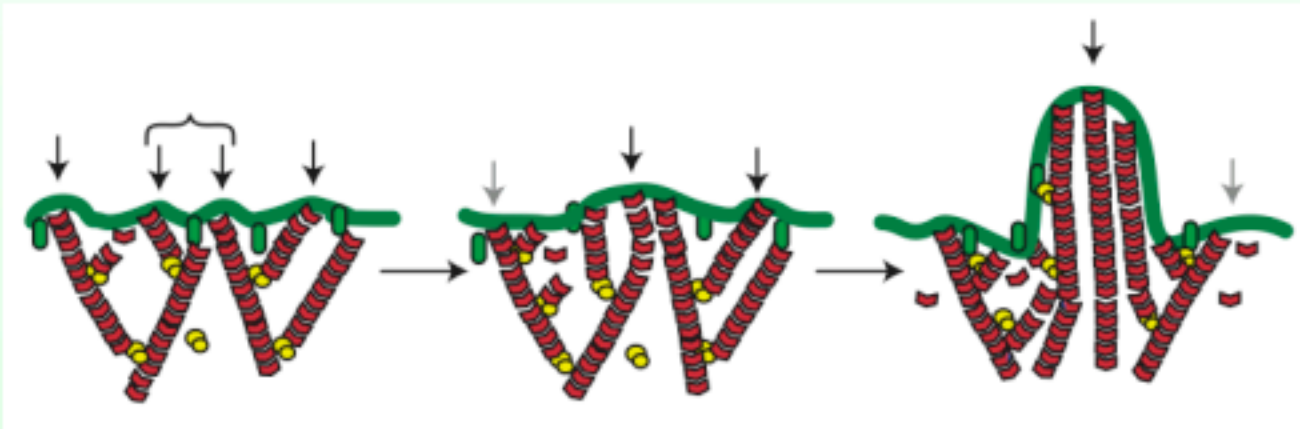
- Despite much progress, this method is still **prohibitively slow** to address many outstanding research questions. (e.g., large scale processes that happen on the order of milliseconds and involve millions of atoms).



Membrane-bound aquaporin (i.e., water channel)  
timescale:  $10^{-9}$  seconds

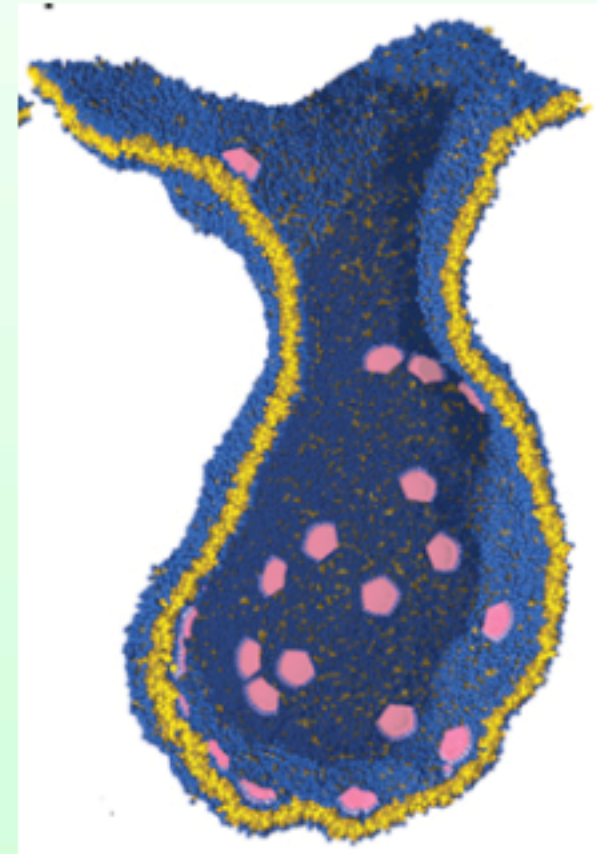
# Many important processes occur at long time- and length-scales

actin-based motility  
 $10^{-3} - 10^{-1}$  seconds



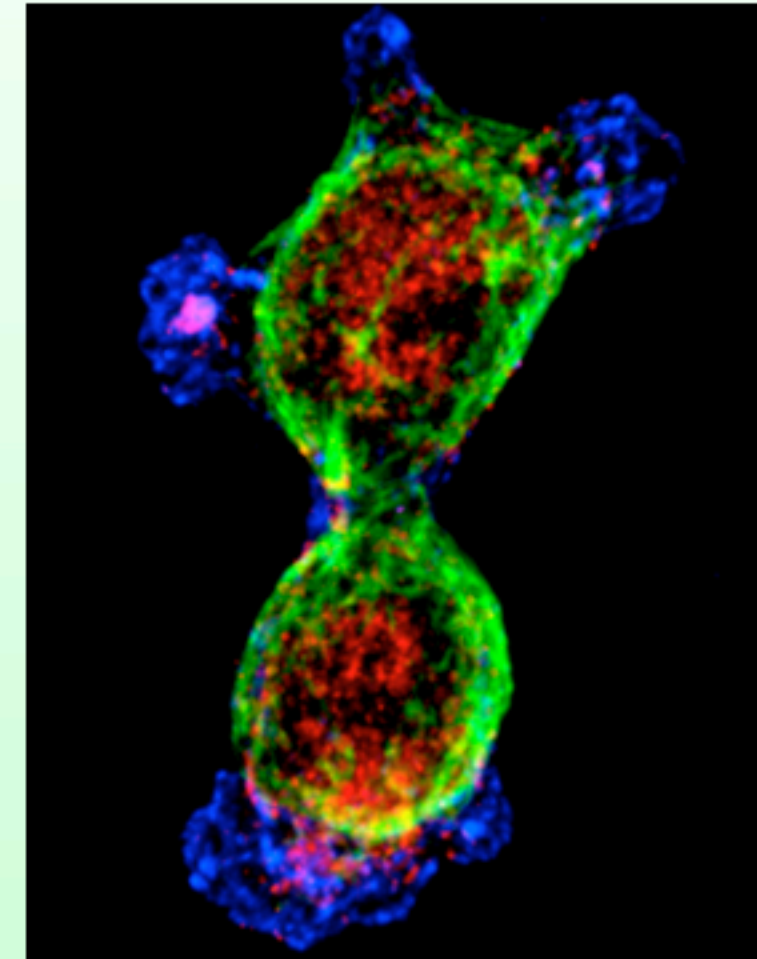
Liu A, Richmond D, Maibaum L, Pronk S, Geissler PL, Fletcher D. *Nature Physics*, 4 (2008)

endocytosis  
 $10^{-3} - 10^0$  seconds



Reynwar BJ, Illya G, Harmandaris VA, Müller MM, Kremer K, Deserno M. *Nature*. 2007 May 24.

cytokinesis  
 $> 10^0$  seconds



Pellinen T *et al.* *Dev Cell*. 2008 Sep 15(3).

# Mesoscale molecular simulation with Dissipative particle dynamics (DPD)

- First devised in the early 1990s by Hoogerbrugge and Koelman [1], later revised by Espanol to ensure proper thermodynamics [2].
- It is a method of “coarse grained” simulation -- atomistic details of the solvent and other molecules are abstracted to yield larger particles (see the next slide for an example).
- Based on the laws of stochastic fluid dynamics (e.g., Brownian motion) to give correct hydrodynamic behavior at long time- and length-scales.
- The technique is becoming increasingly popular in materials and biological sciences.

$$\mathbf{F}_i = \sum_{j \neq i} [\mathbf{f}^C(\mathbf{r}_{ij}) + \mathbf{f}^D(\mathbf{r}_{ij}, \mathbf{v}_{ij}) + \mathbf{f}^R(\mathbf{r}_{ij})]$$

pair potential

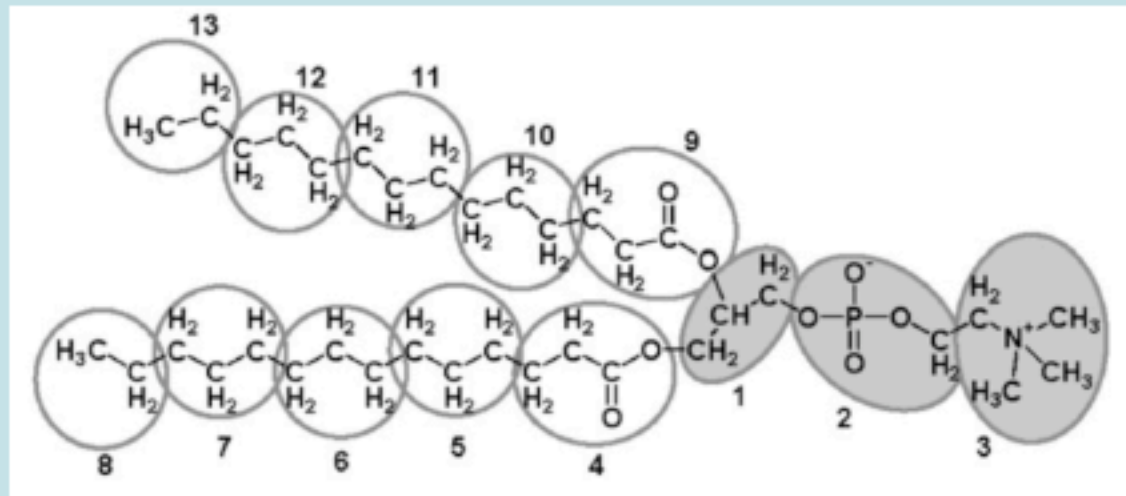
friction force

random force

[1] Hoogerbrugge PJ and Koelman MVA. Europhysics Letters, 19(3):155–160, 1992.

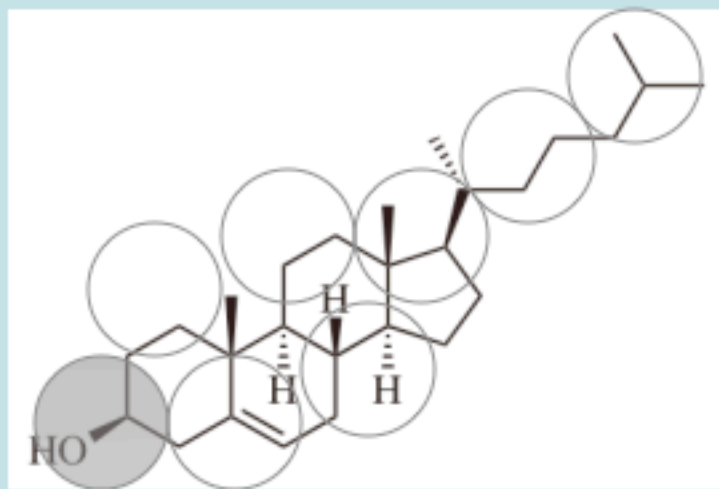
[2] Espanol P and Warren PB. Europhysics Letters, 30(4):191–196, 1995.

# An example of DPD coarse-graining: biological membranes

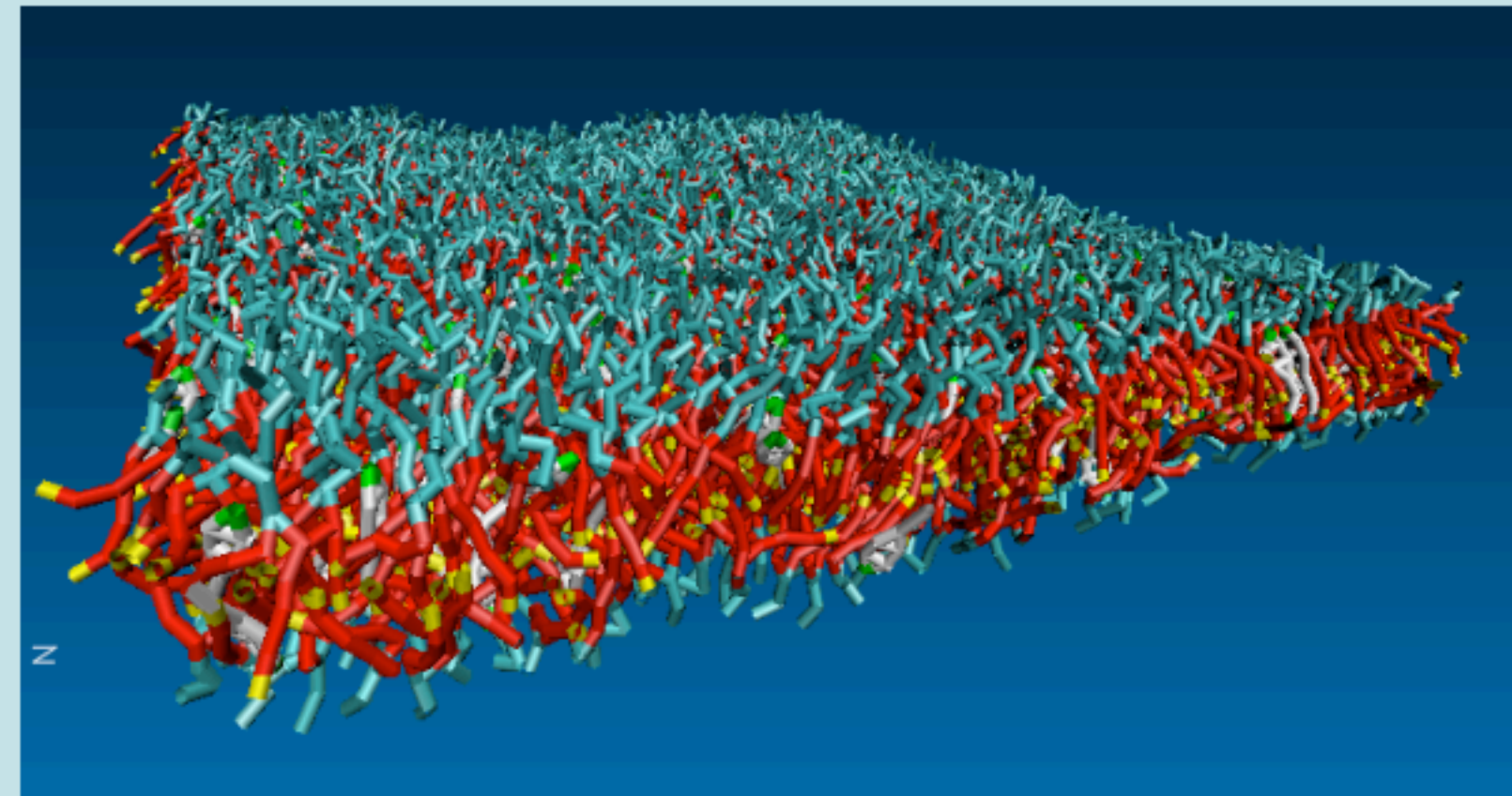


phospholipid

+



cholesterol

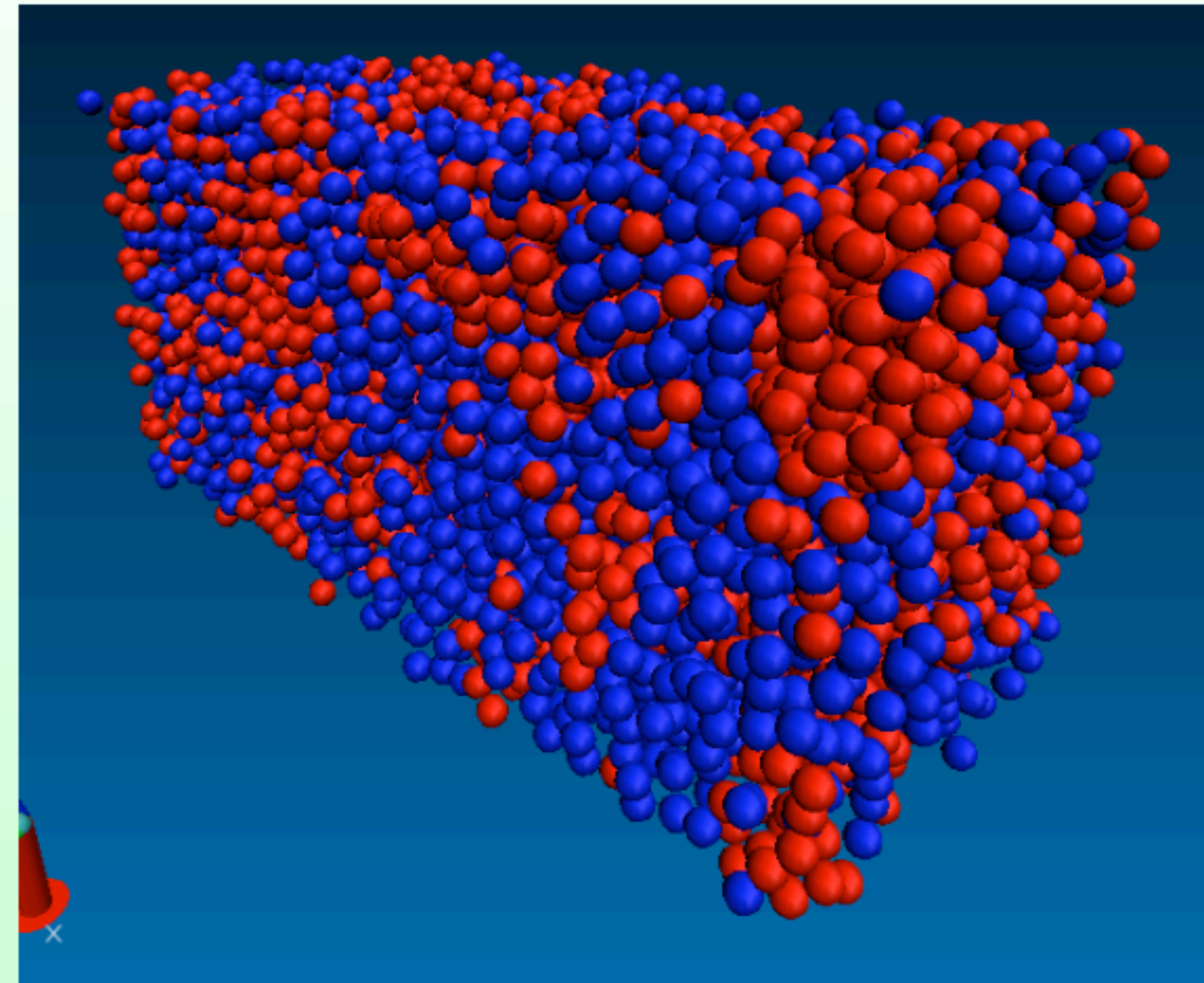


- 3600 phospholipid / cholesterol molecules
- 90000 water particles (3 water molecules per particle)

# The model system: mixing and phase separation in a 2-component liquid

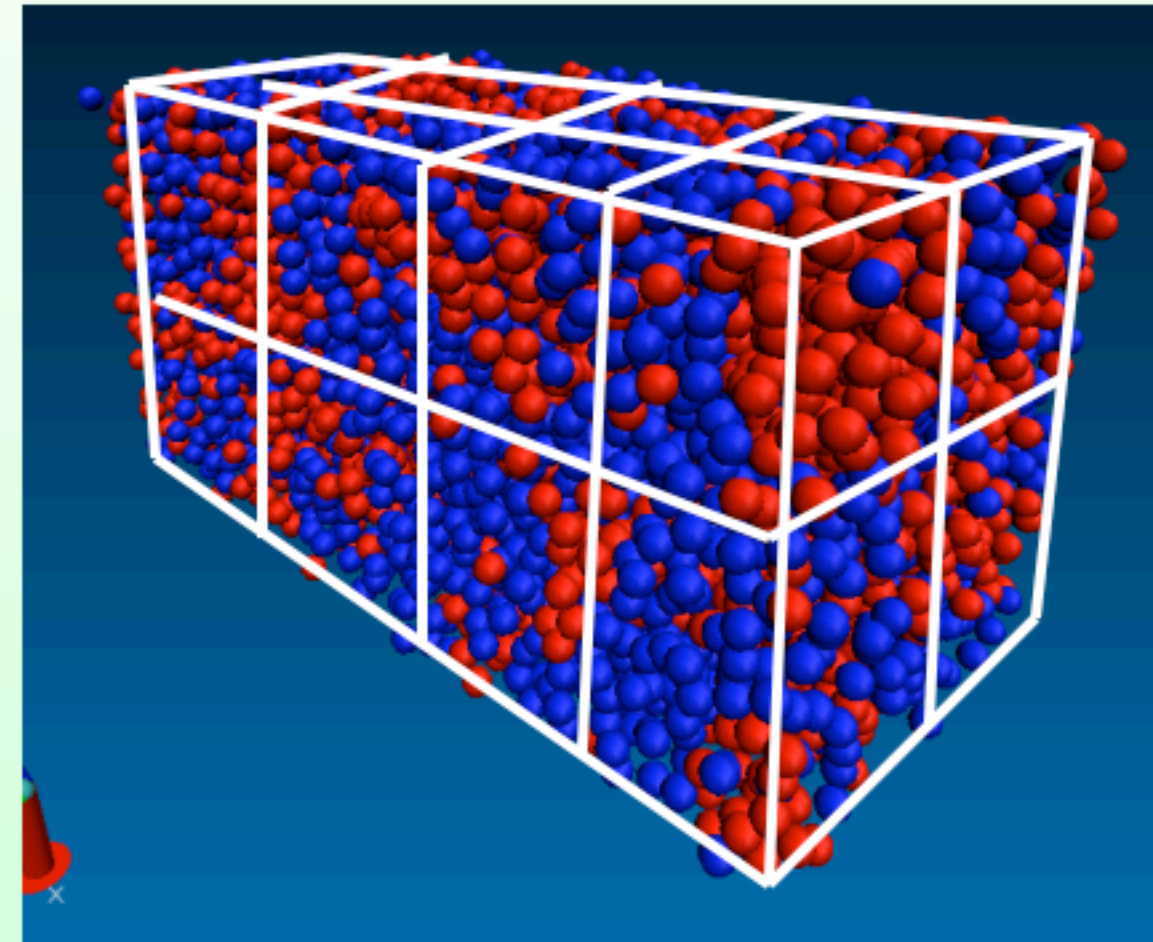
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- Adapted from *Understanding Molecular Simulation* by Daan Frenkel & Berend Smit [1].
- Particles interact with each other by a soft repulsive force.
- Numerical physical quantities can be obtained (e.g., density profile along the z-axis, interfacial tension, pressure, temperature, etc).



# General strategies for parallelization

- Decompose the simulation box into **equidistributed domain sizes**. Since the system is in a condensed phase (unlike in HW 2), work can be distributed approximately evenly without a quad tree. The size of the dimension of each box will approximately equal the cutoff distance.
- Let each core be responsible for calculating the force on each particle **within its designated volume**. This is the most computationally expensive part of the algorithm by which the system evolves.



evenly-sized domains  
(note: this scale is much smaller than what will be implemented in the final version.)

# CUDA implementation

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- **Graphics Card.** Nvidia 9500 GT (fairly modest). 8-way SIMD on 4 “multiprocessors,” 8 kb of dedicated memory (I think). Running on Ubuntu Linux.
- **Memory concerns will likely dominate performance tuning.** It will be challenging to store and cheaply update the particle position array on the dedicated constant cache.
- **Multidimensional matrices should not be an issue.** Though a sparse matrix of particle interactions *could* be made, only the sum of these forces needs to be stored (so no need for concern about matrix padding).

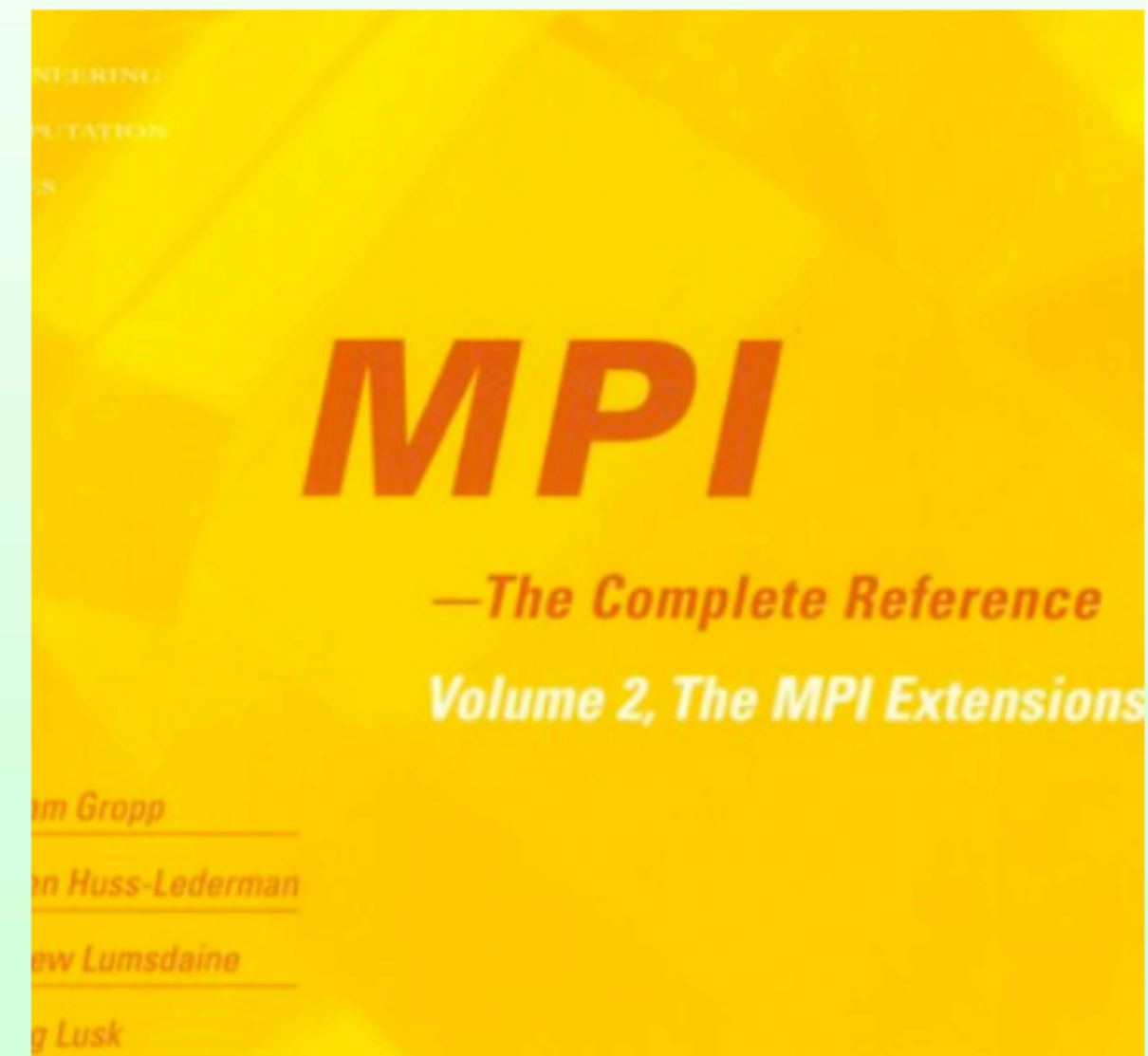




# MPI implementation

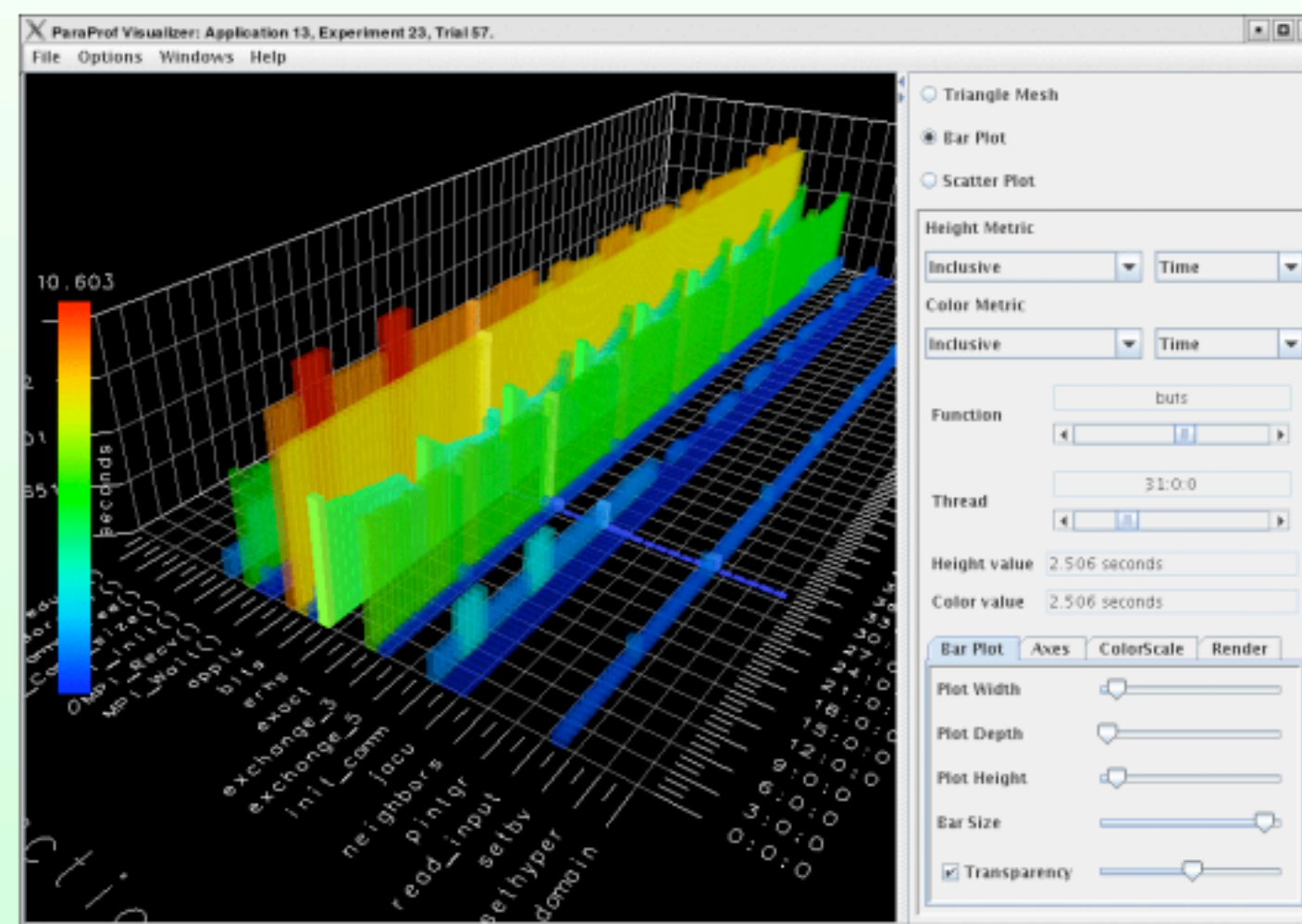
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- Available parallel computing resources include the NERSC computers and an 8-core Mac Pro.
- In comparison to the CUDA implementation, the MPI implementation should afford larger domains. I expect that one domain size will be more “natural” than the other, since particles feel pair-potential and dissipative forces of each other as given by the energy function.
- Some similar techniques to those used in HW2 could be used, however since particle impose forces on each other (even over domain boundaries) the problem is particularly different.



# Other tools that I hope to use

- Performance analysis tools (Karl Fuerlinger, 3/18/2009):
  - IPM -- for MPI version
  - TAU -- for both (?)
- An OpenMP version (if I *really* have extra time).



3D performance data from TAU

# Thanks!

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- Jocelyn Rodgers
- The membrane simulation subgroup
- Professor Smit
  
- UC Berkeley biophysics graduate group