Learning to Segment Actions from Observation and Narration



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Action Segmentation in Video

Task: make pancakes: {add egg, add flour, ..., pour batter, remove pancake}

Actions: background pour batter background remove pancake

Video:

Narration: hey folks here welcome to my kitchen ... pour a nice-sized amount ... change the angle to show ... and take it out

Challenges: visual diversity, noisy narration, varied task structure

How little supervision can we get away with?

make pancakes:

{add egg, add flour, ...,
pour batter, remove pancake}

Actions: Q

background

pour batter

Video features: χ



hey folks here welcome to my kitchen... pour a nice-sized amount...

Generative:

$$\max_{\theta} \sum_{a} p_{\theta}(a, x)$$

[Richard et al. 2018, Sener and Yao 2018]

Discriminative:

 $\max_{\theta,a} p_{\theta}(a|x)$

[Alayrac et al. 2016, Zhukov et al. 2019]

Weak-supervision for a:

- Likely ordering of the actions
- Time-aligned narration

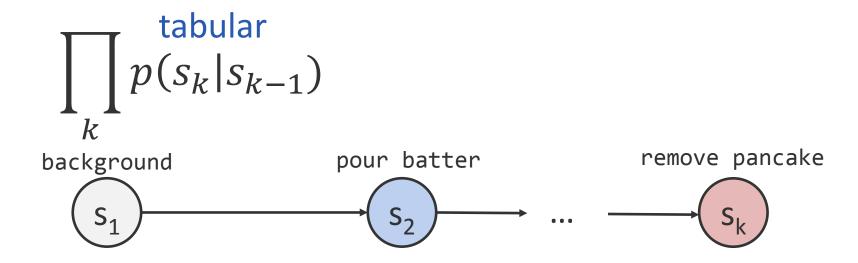
How little supervision can we get away with? Define a model that allows flexible training.

Actions

Video





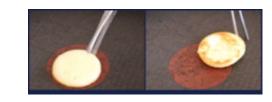


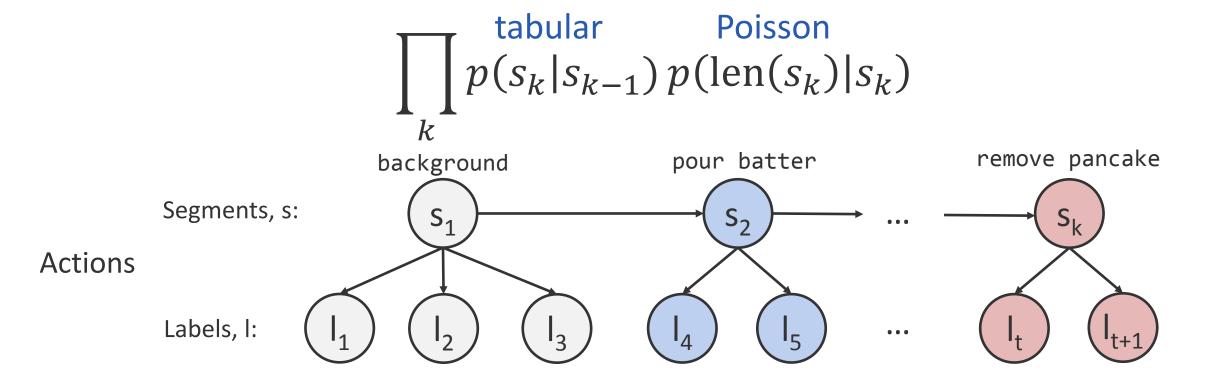
Segments, s:

Actions

Video



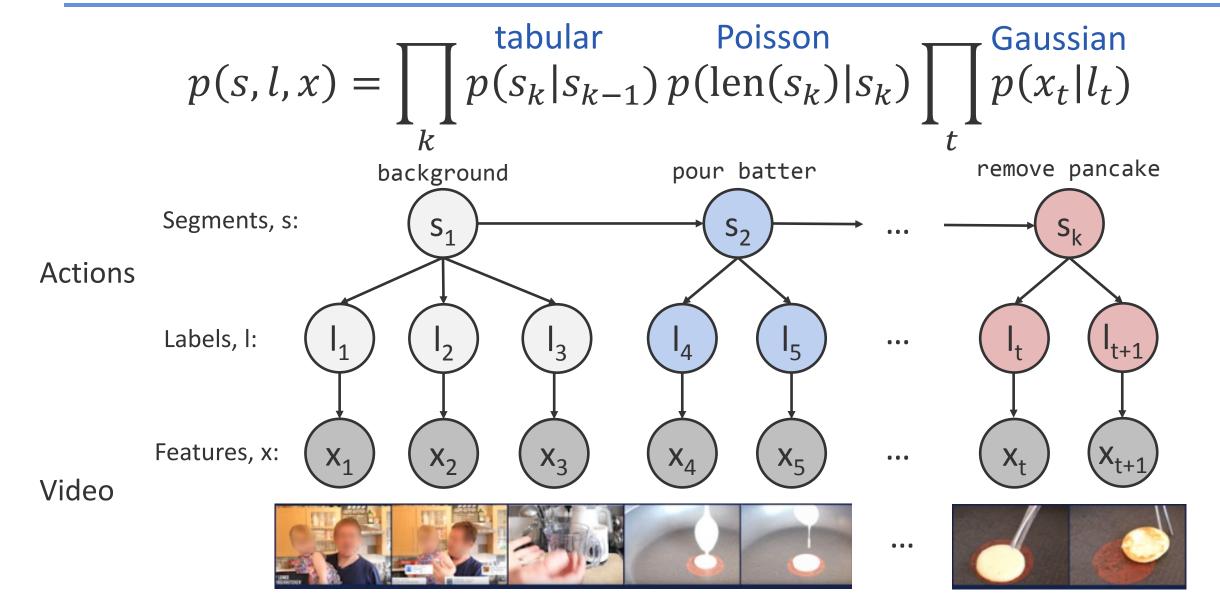




Video







CrossTask Dataset [Zhukov et al. 2019]

2,700 instructional YouTube videos, with transcribed narration

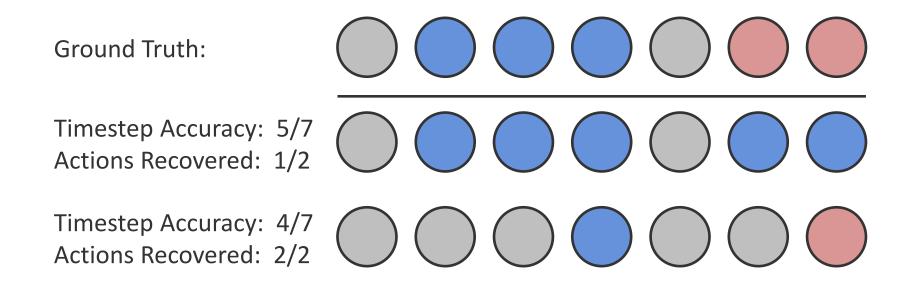
▶ 18 household tasks, e.g. cooking, changing a tire, assembling furniture

- Features from ConvNets trained on other related tasks
 - Action recognition [Carreira and Zisserman 2017; Kay et al. 2017]
 - Object classification [He et al. 2016; Russakovsky et al. 2015]
 - Audio classification [Simonyan and Zisserman 2015; Abu-El-Haija et al. 2016]

Evaluation

Two main metrics from past work:

- Timestep accuracy (1-second intervals) [Sener and Yao 2018, Richard et al. 2018, inter alia]
- Action recovery (with one timestep per action) [Alayrac et al. 2016, Zhukov et al. 2019]



How little supervision can we get away with? First, compare models in a supervised setting.

Supervised Training

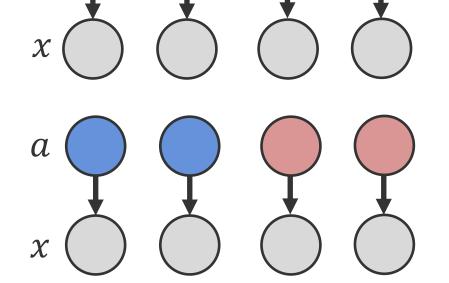
Structured:

Semi-Markov model

 \boldsymbol{a}

Unstructured:

Independent classifier at each time-step

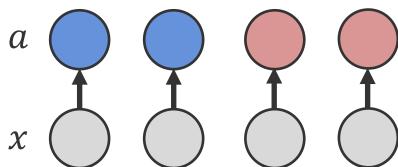


Generative:

p(a,x)

Discriminative:

 $\begin{array}{c|c}
p(a|x) \\
\hline
 x \\
\end{array}$



Supervised Results



Actions Recovered



Supervised Results

41%

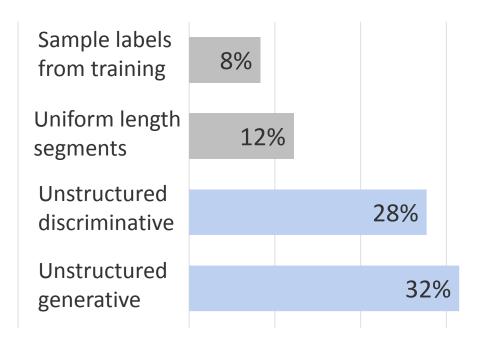
Non-Background Timestep Accuracy

Sample labels from training Uniform length segments Unstructured discriminative 7% 30%

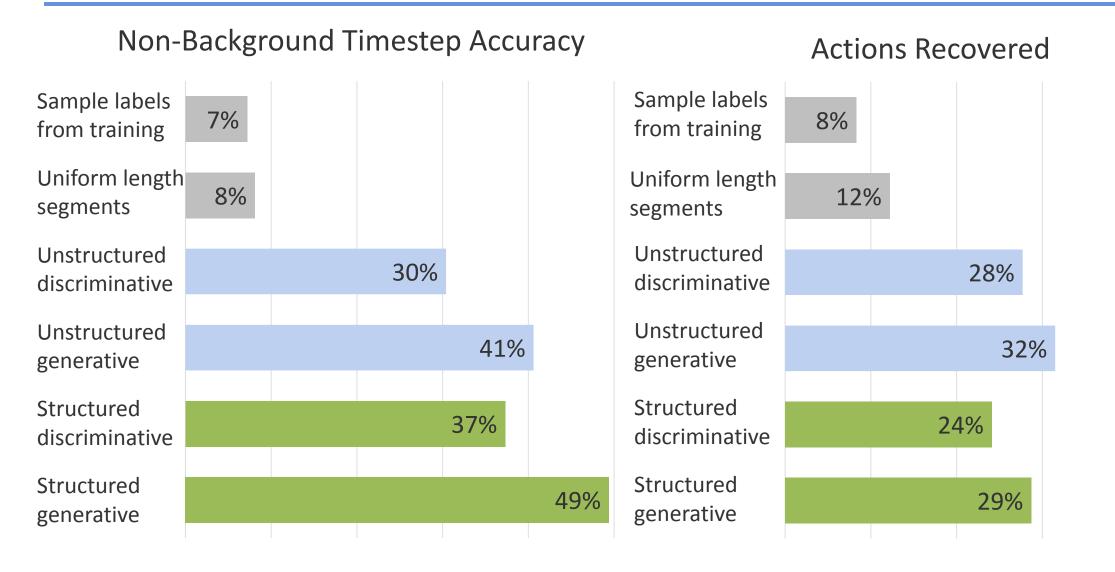
Unstructured

generative

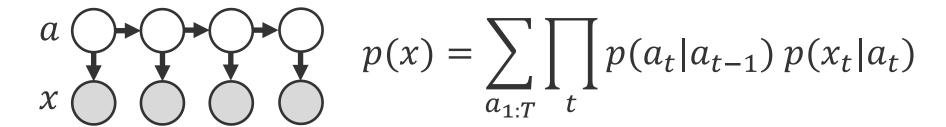
Actions Recovered



Supervised Results



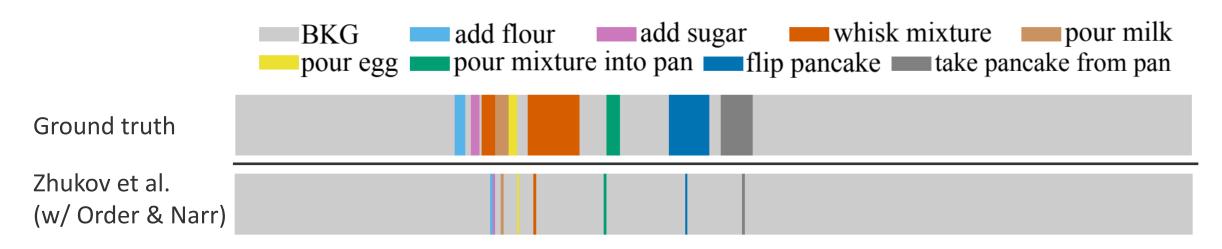
How little supervision can we get away with? Train the structured, generative model without labels.

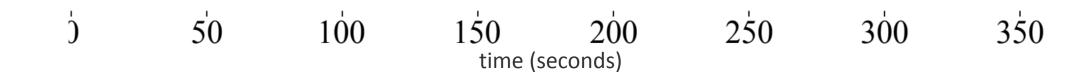


Maximize $\log p(x)$ (gradient-based soft EM [Eisner 2016])

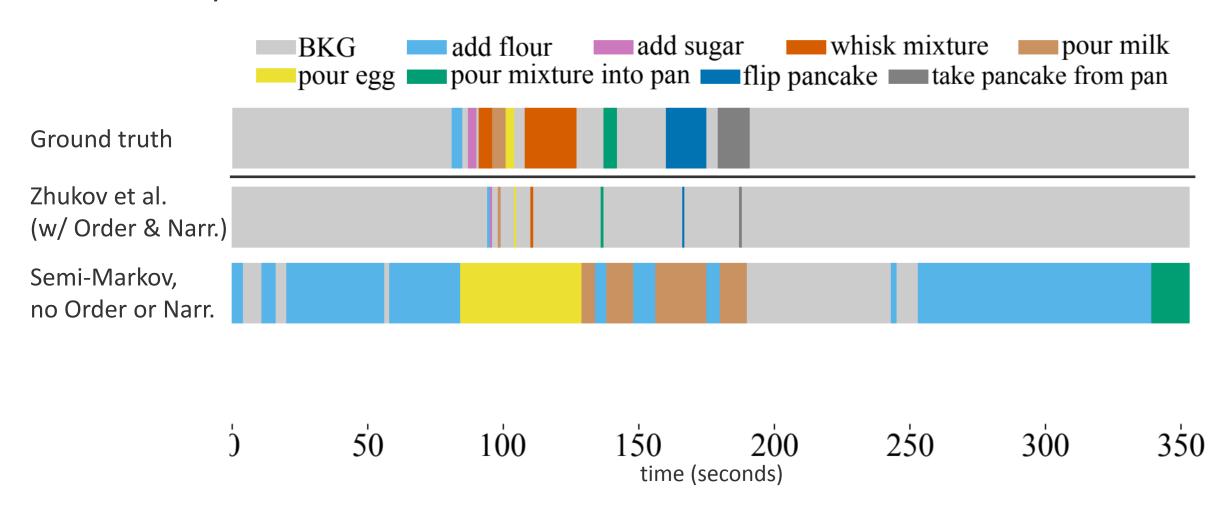
- Ordering Supervision Use a typical ordering of steps for each task, e.g. add flour, add sugar, ... [Zhukov et al.] Constrain $p(a_t|a_{t-1})$ to enforce this ordering over segments in all videos for the task
- Narration Supervision Use label—narration similarity and time alignment to constrain labels [Zhukov et al.] In training, constrain the sum over label assignments $\sum_{a_1 \cdot T}$

Task: make pancakes

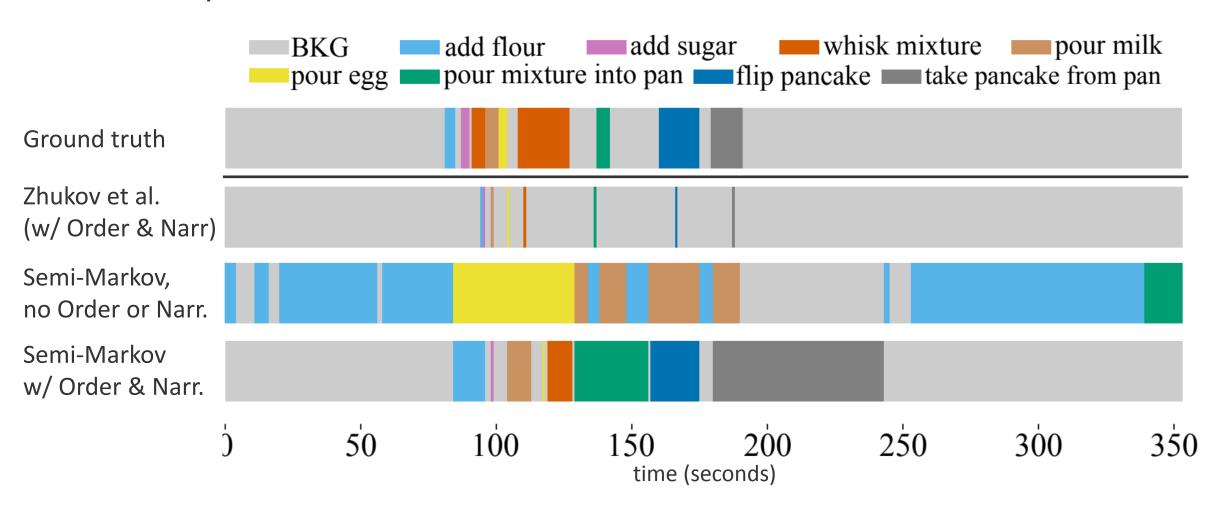


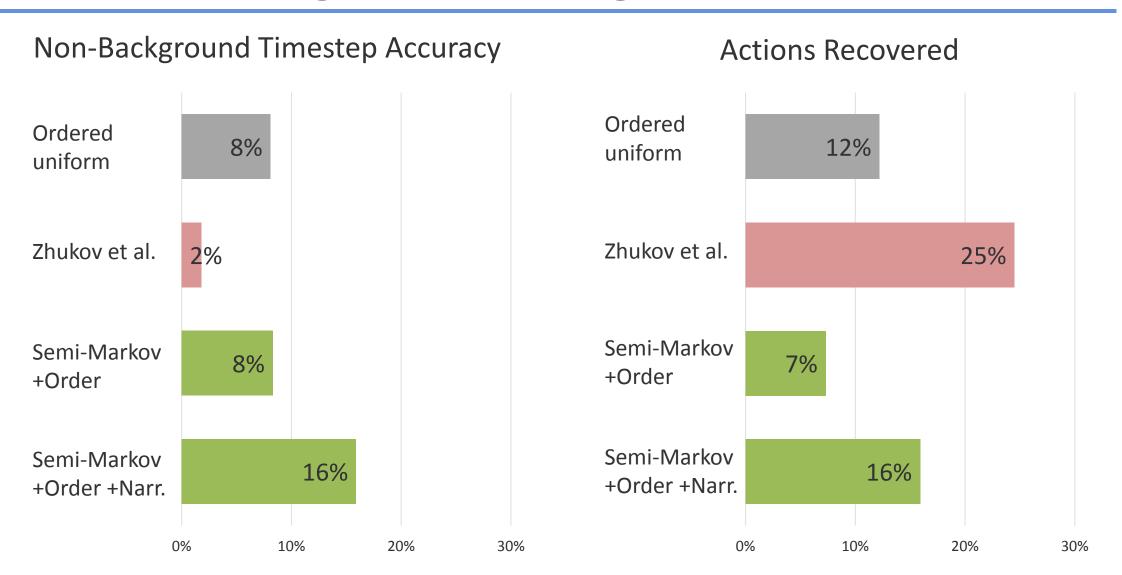


Task: make pancakes

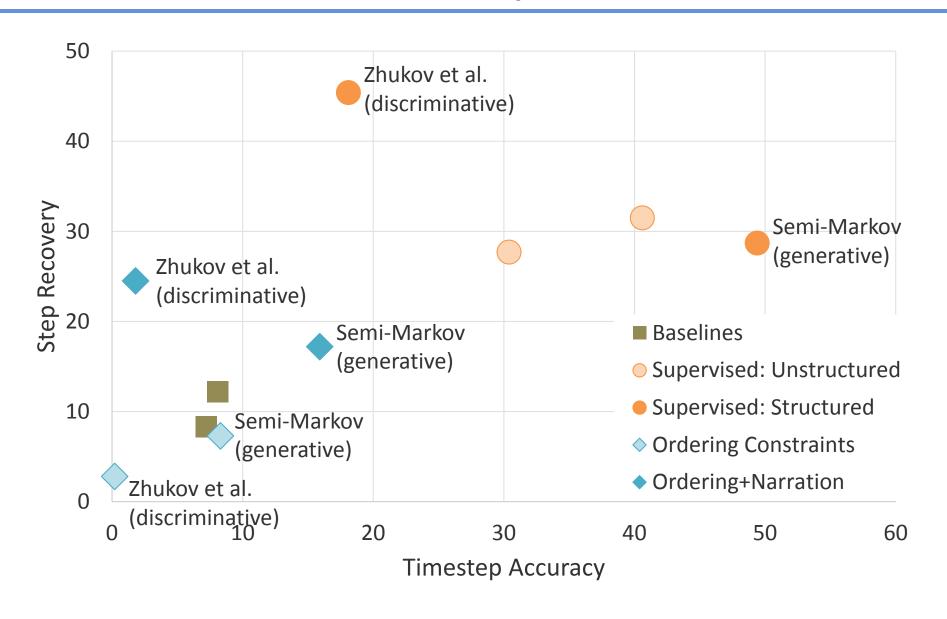


Task: make pancakes





Effects of Supervision



How little supervision can we get away with?

Weak supervision from narration helps substantially!



QA Sessions:

Monday, July 6. 4B: Language Grounding-1. 18:00-19:00 UTC+0

Monday, July 6. 5B: Language Grounding-2. 21:00-22:00 UTC+0

github.com/dpfried/action-segmentation

Thank you!