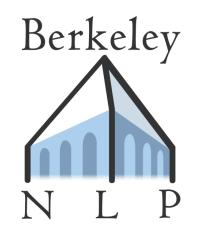
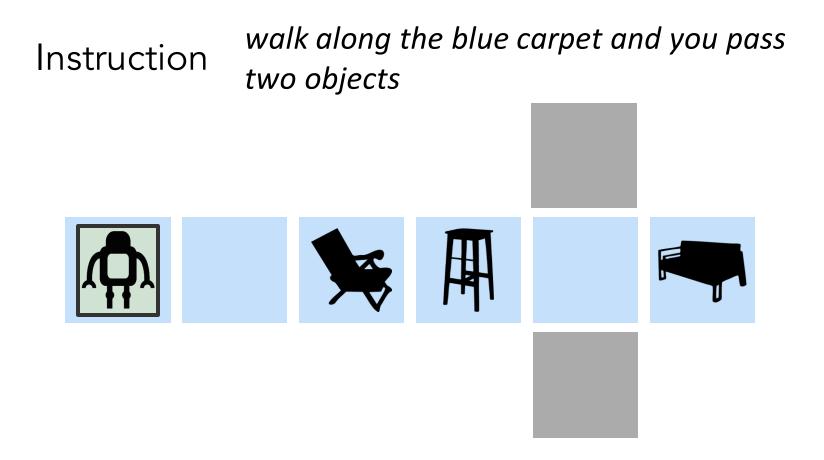
### Unified Pragmatic Models for Generating and Following Instructions

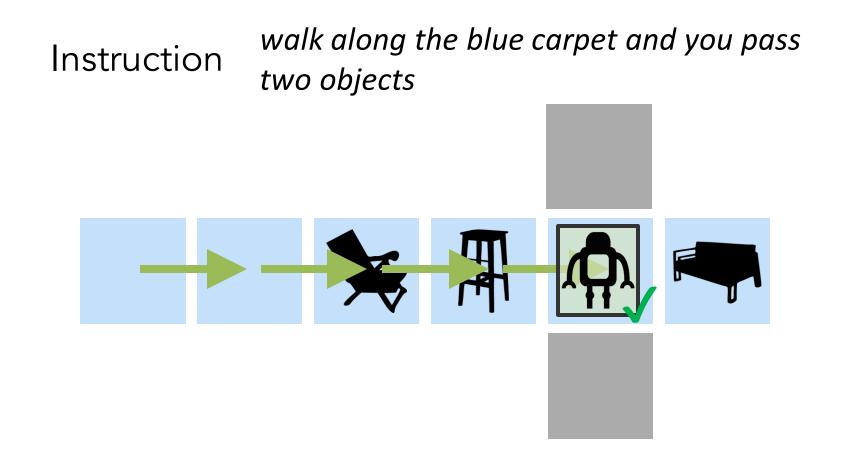


#### Daniel Fried, Jacob Andreas, and Dan Klein UC Berkeley

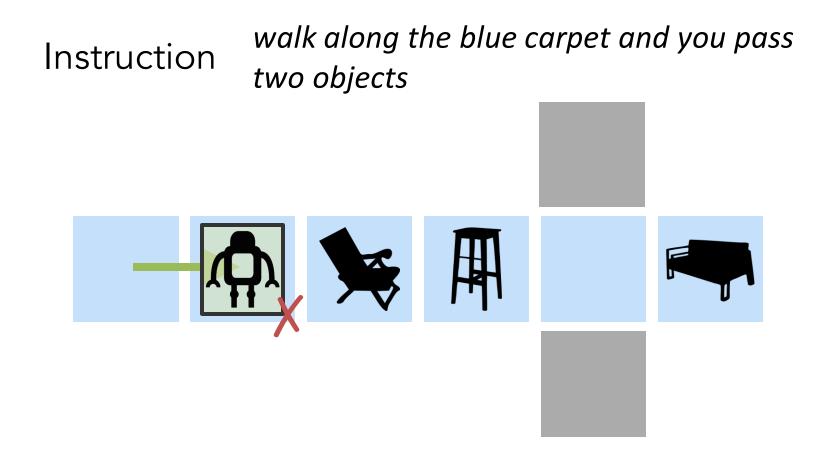




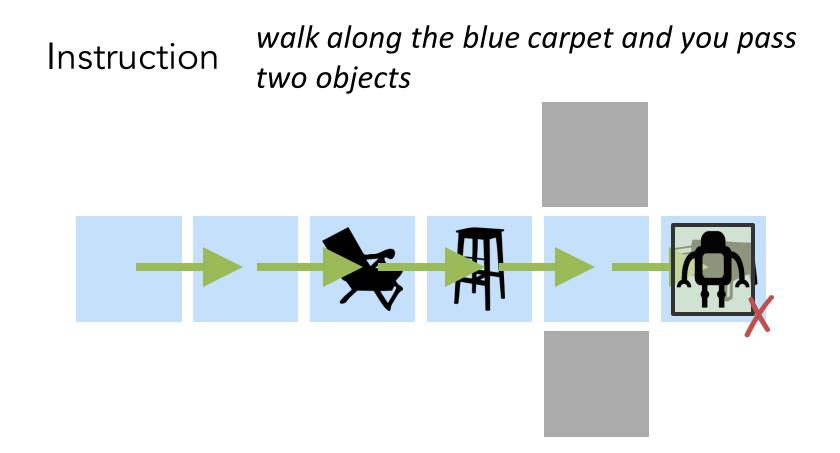




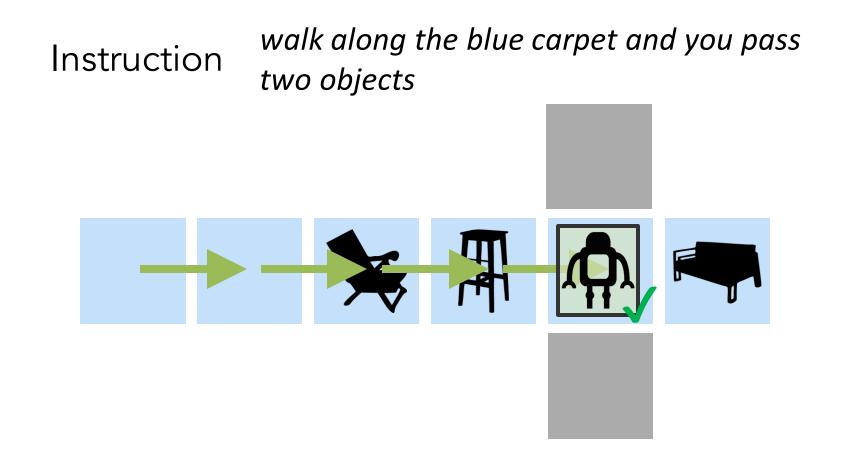




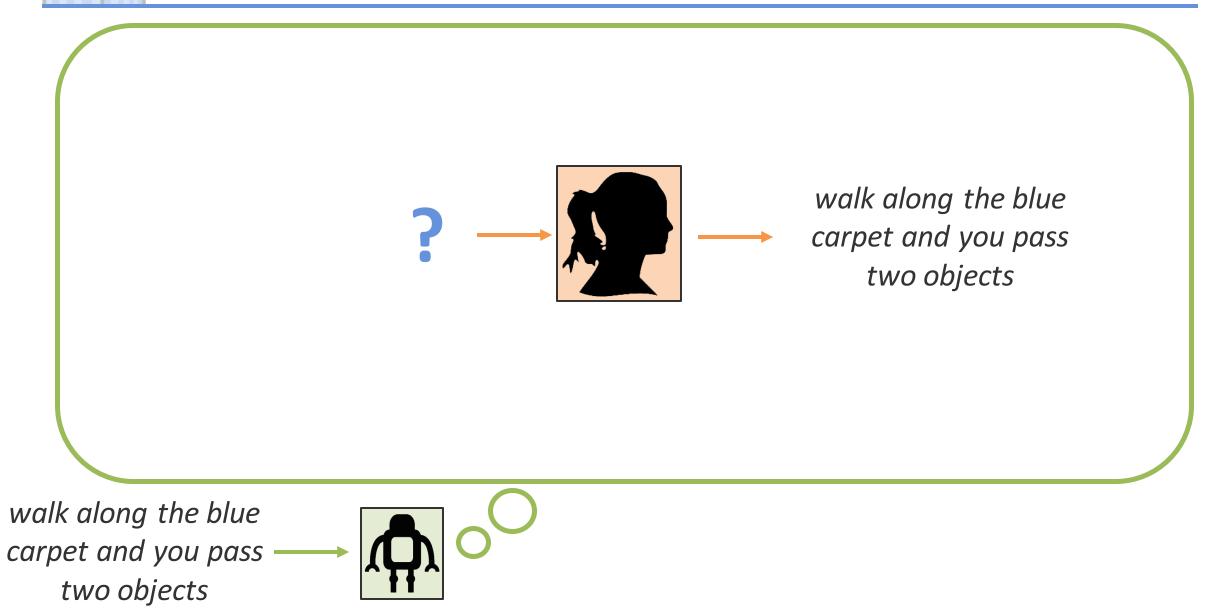






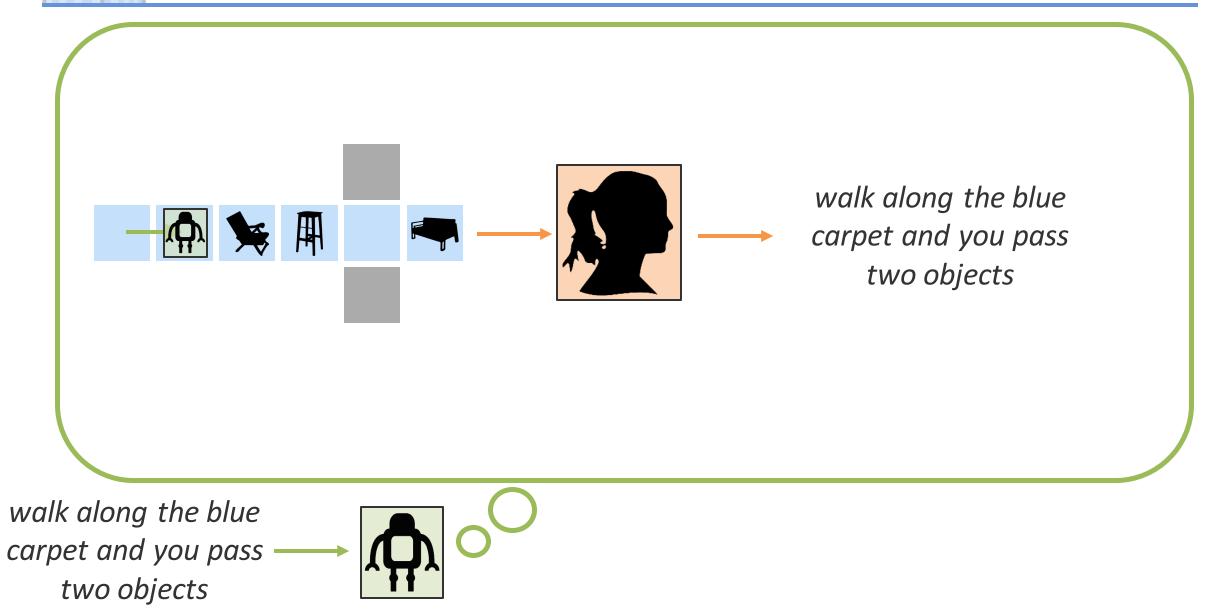






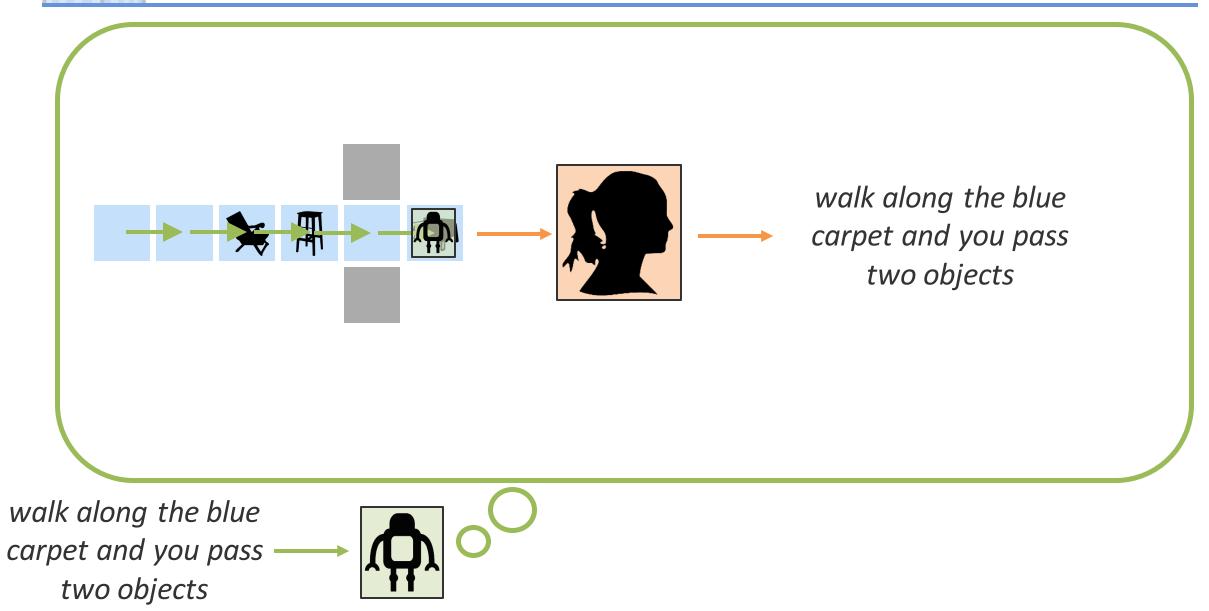


#### Listener: reasoning about routes



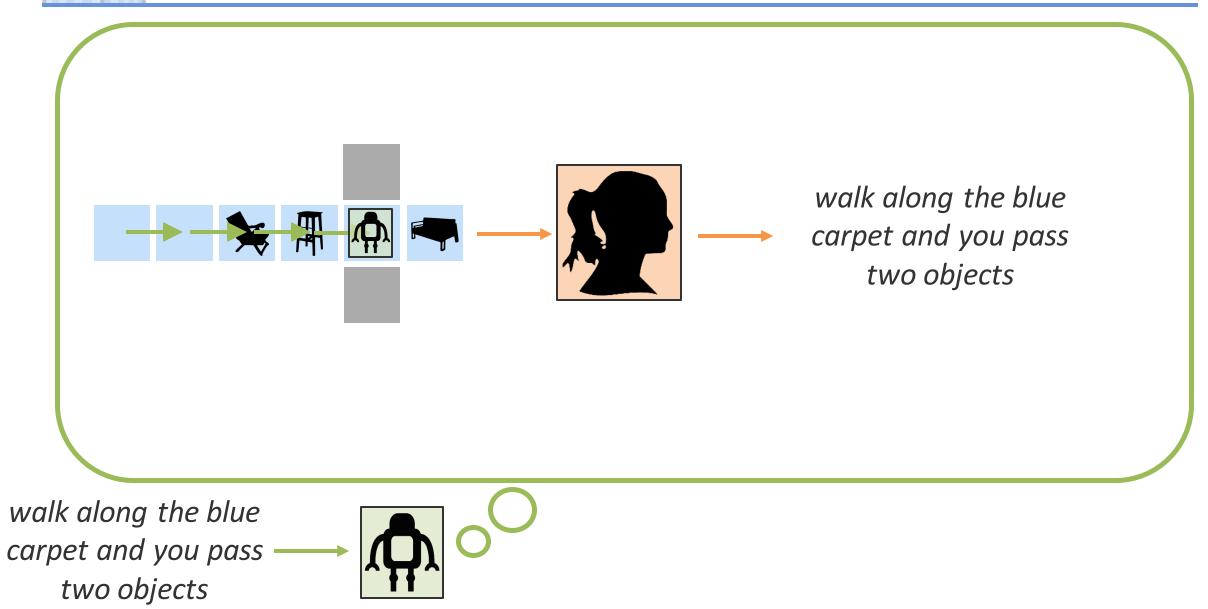


#### Listener: reasoning about routes

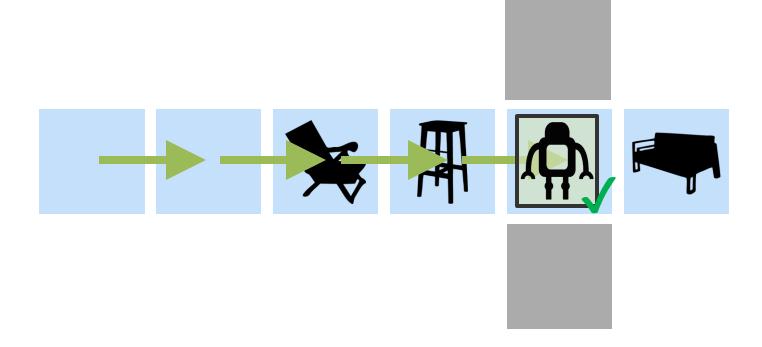




#### Listener: reasoning about routes

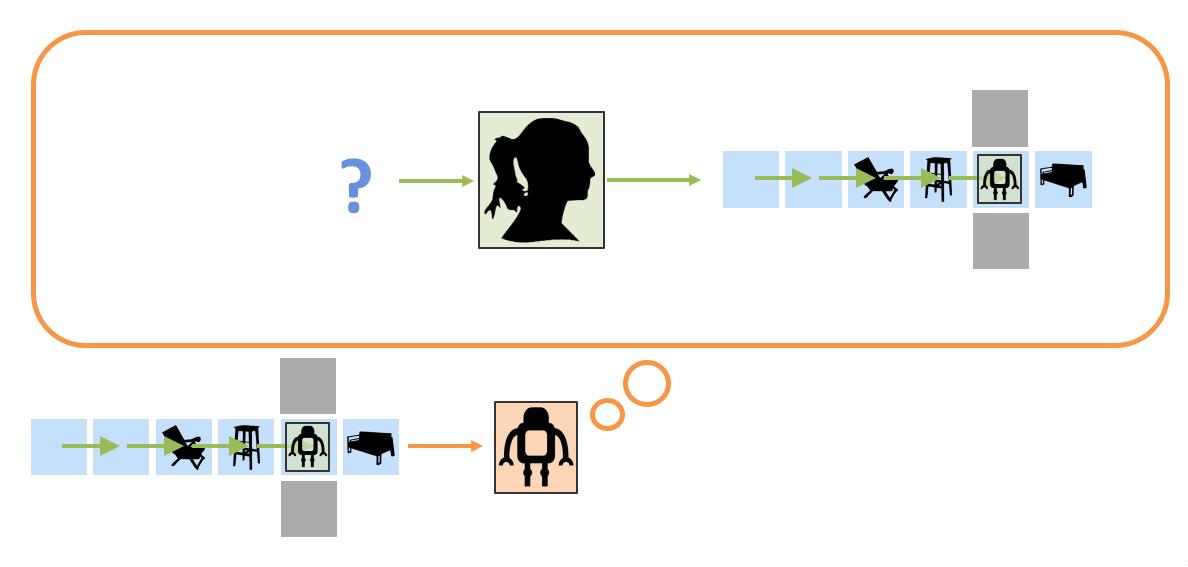


#### Generating instructions



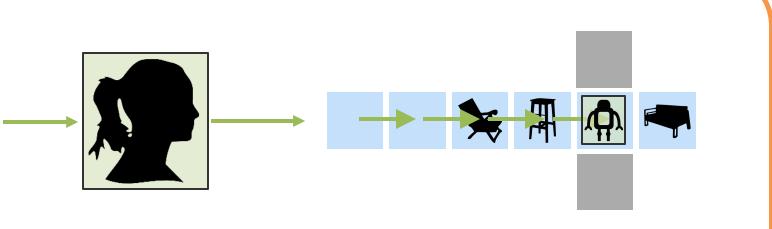
Generated go forward four segments to the Instruction: intersection with the bare concrete hall

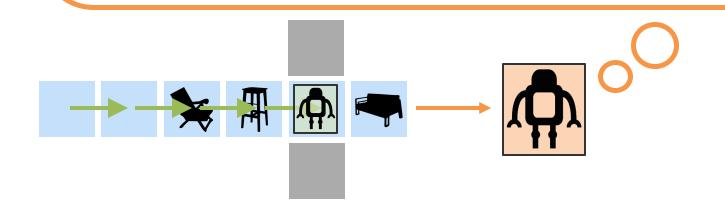
# Speaker: reasoning about interpretation



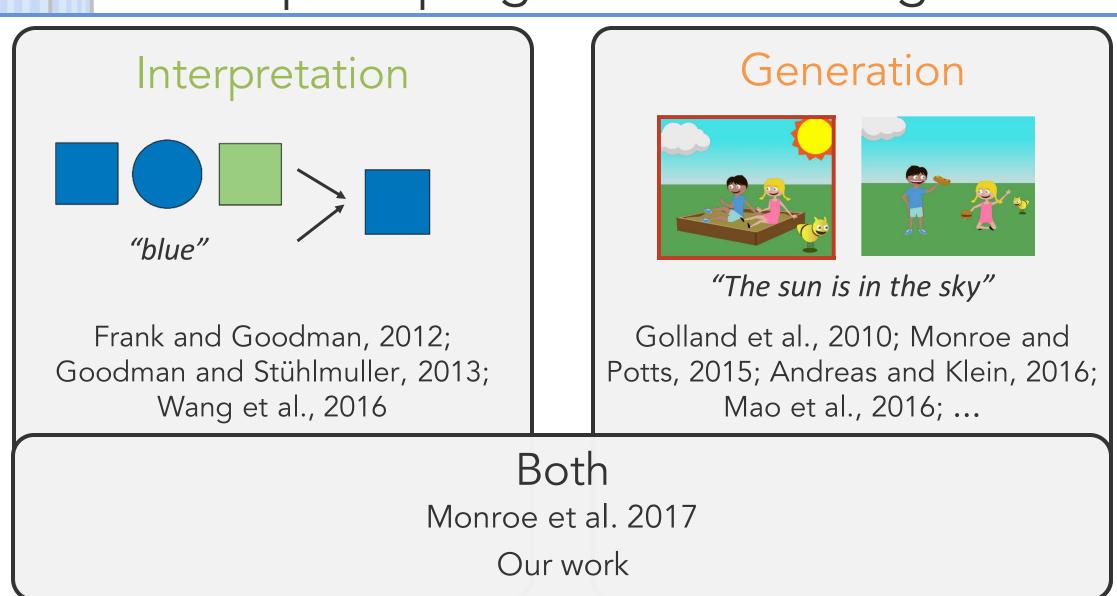
# Speaker: reasoning about interpretation

go forward four segments to the intersection with the bare concrete hall

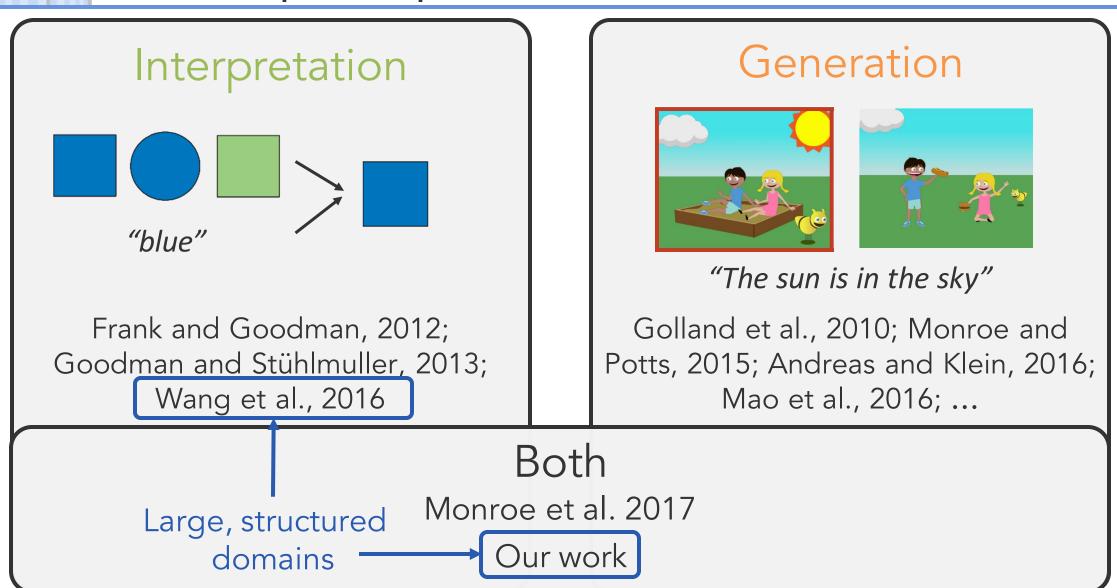




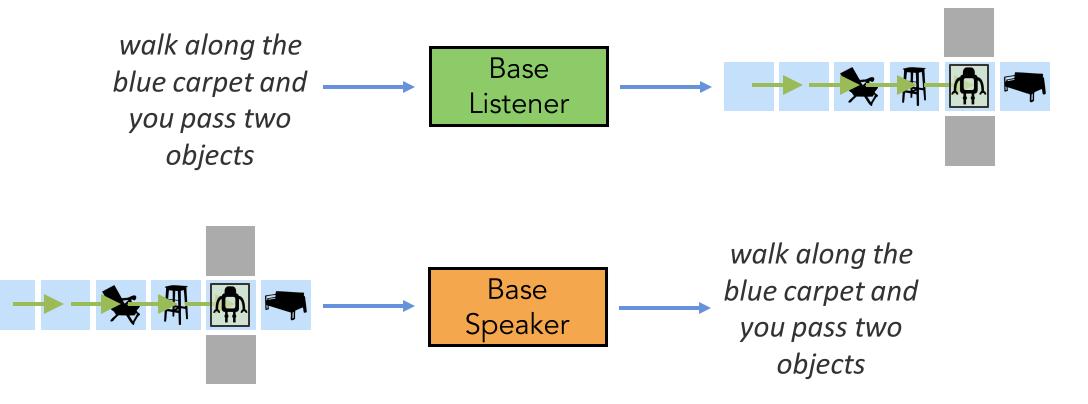
#### Explicit pragmatic reasoning



#### Explicit pragmatic reasoning

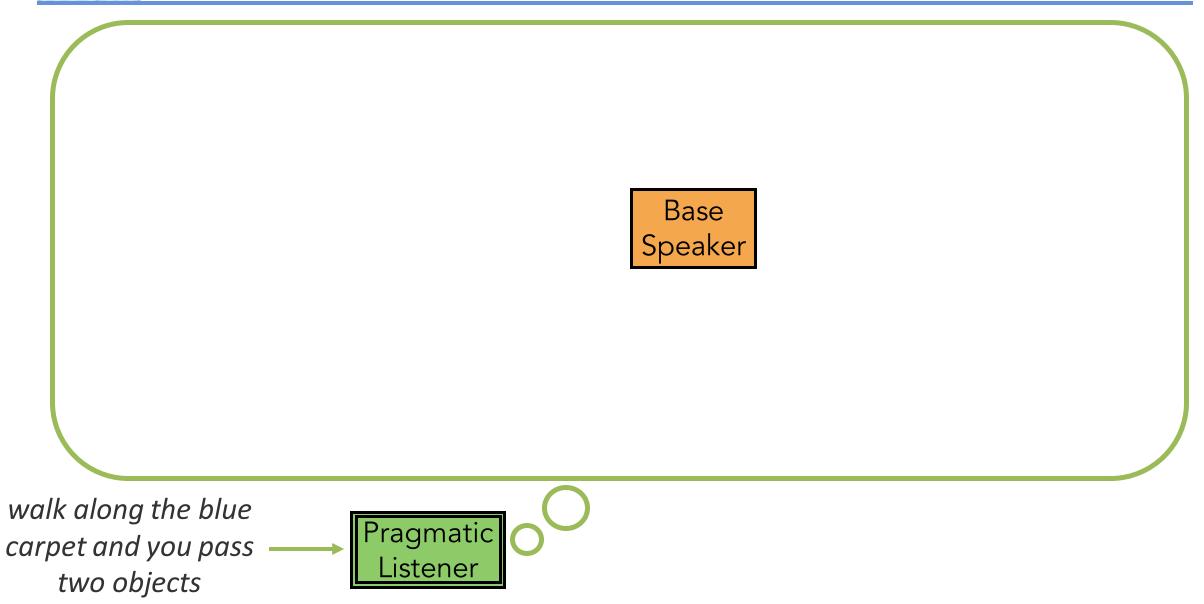


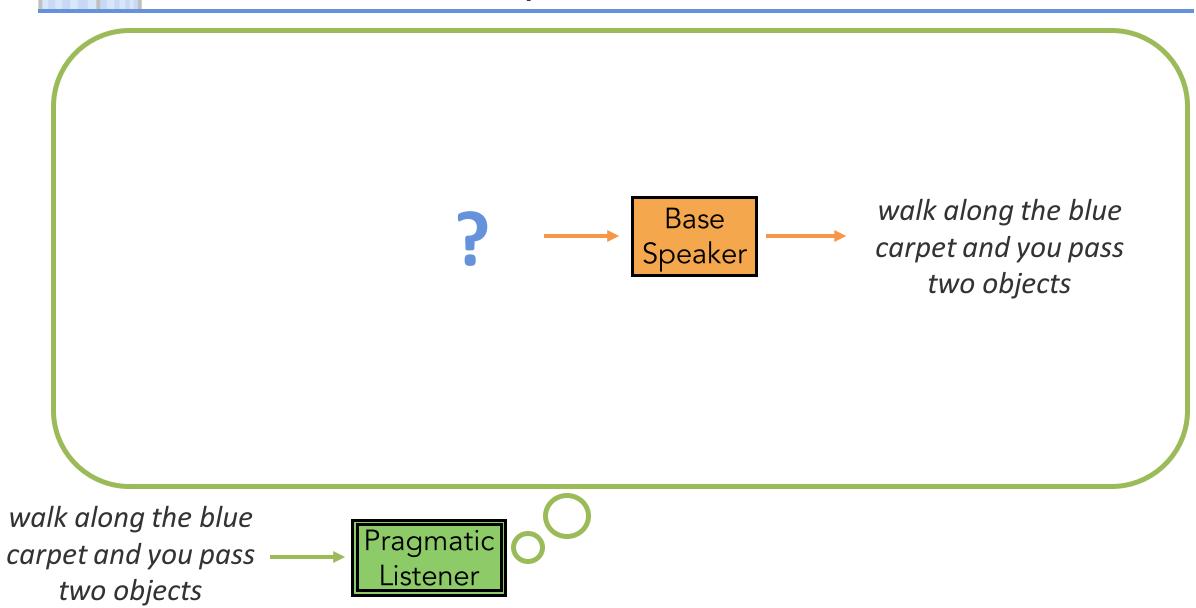


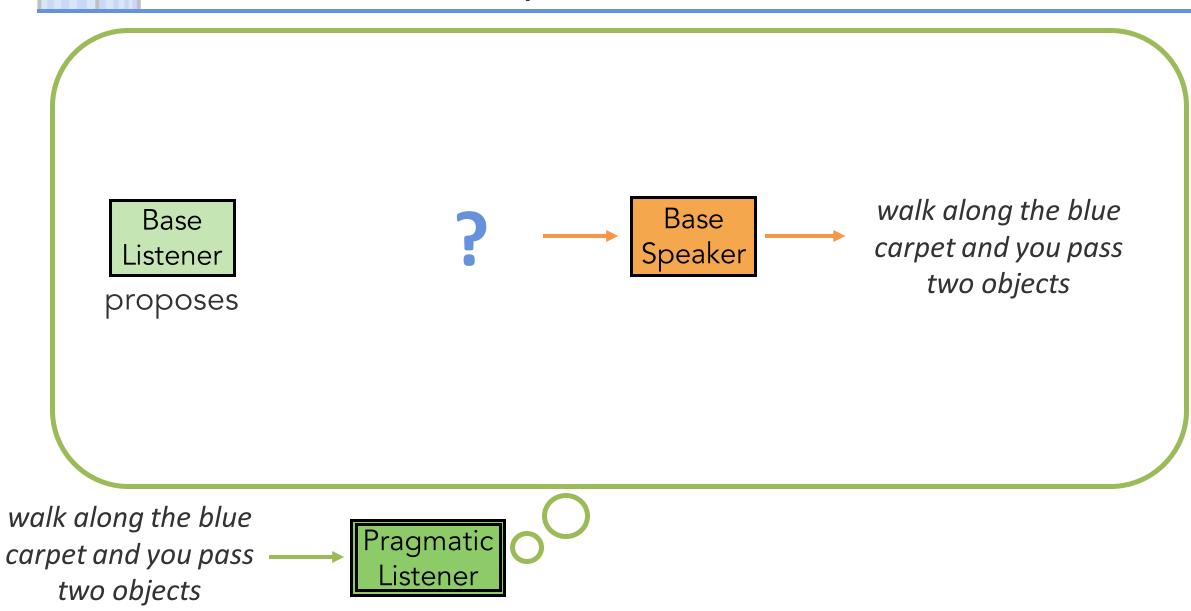


Both models trained independently on action sequences annotated with human instructions







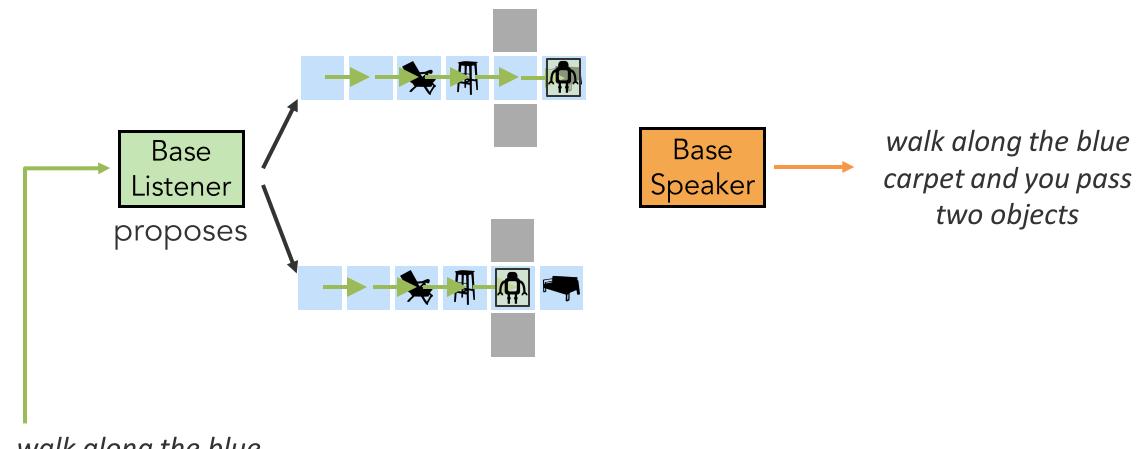




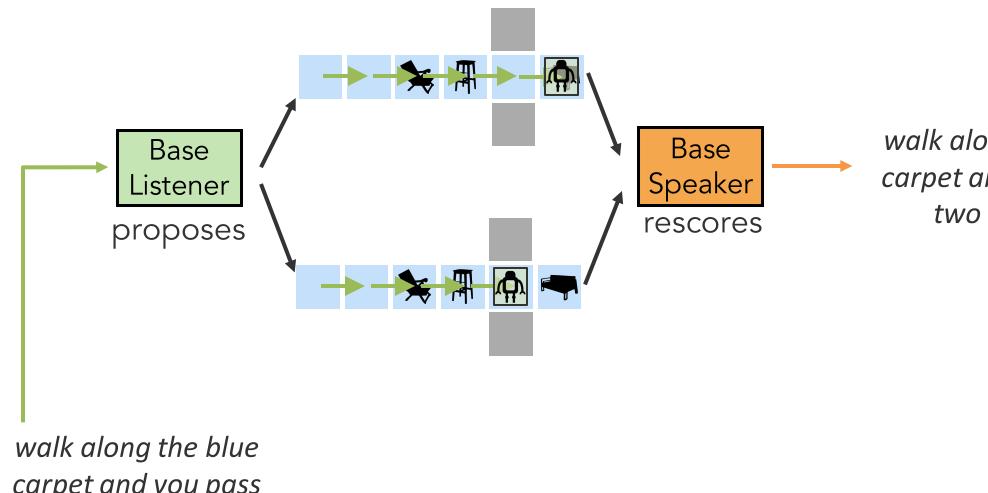


walk along the blue carpet and you pass two objects





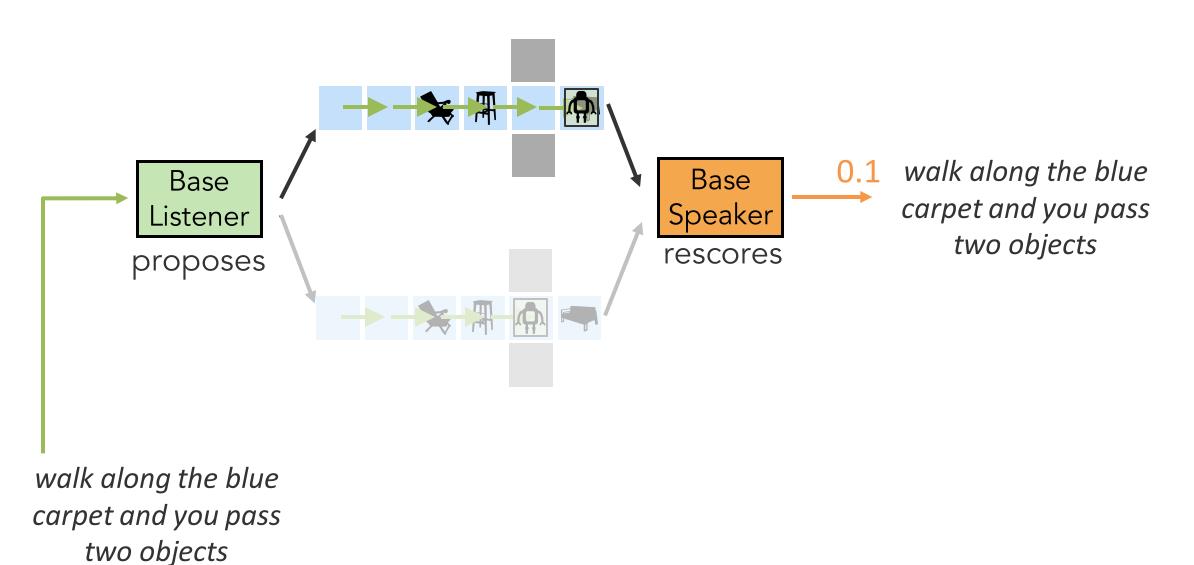




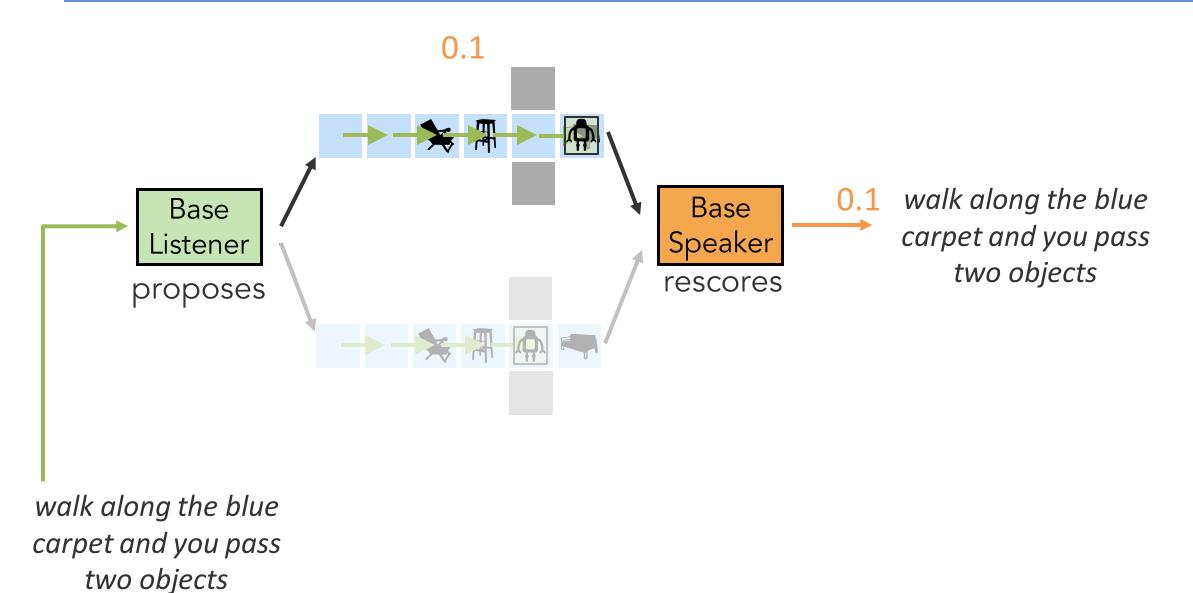
walk along the blue carpet and you pass two objects

carpet and you pass two objects

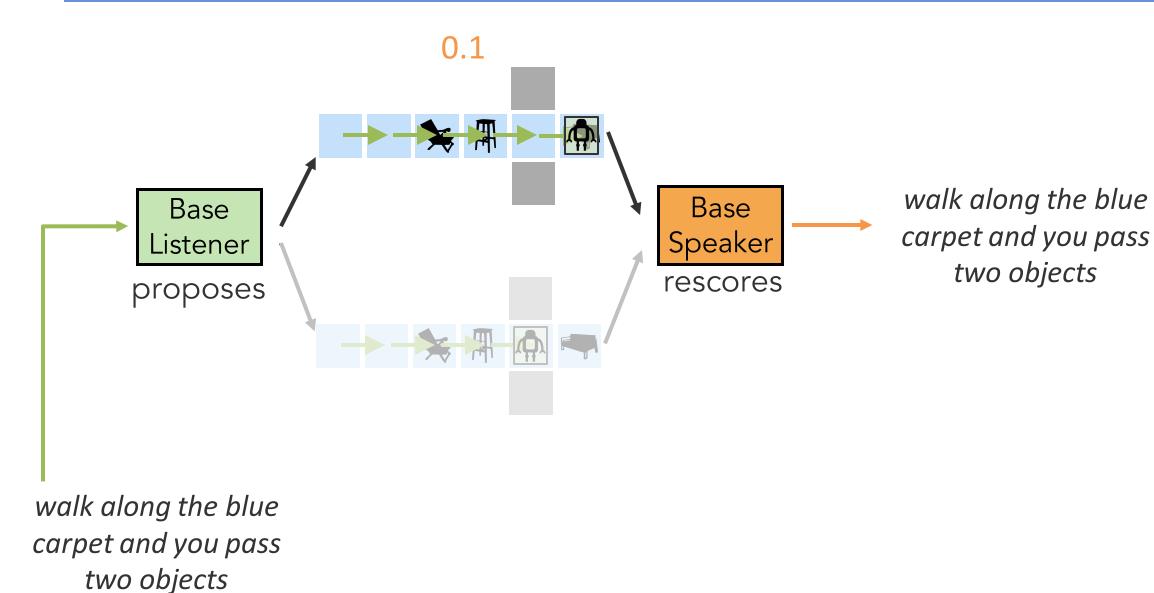




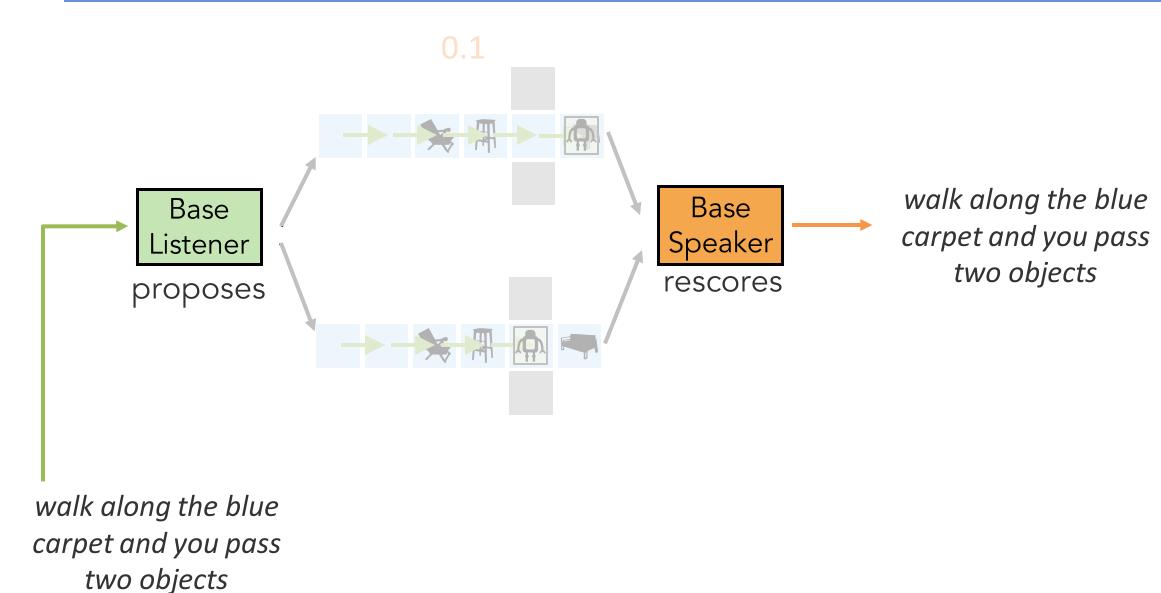




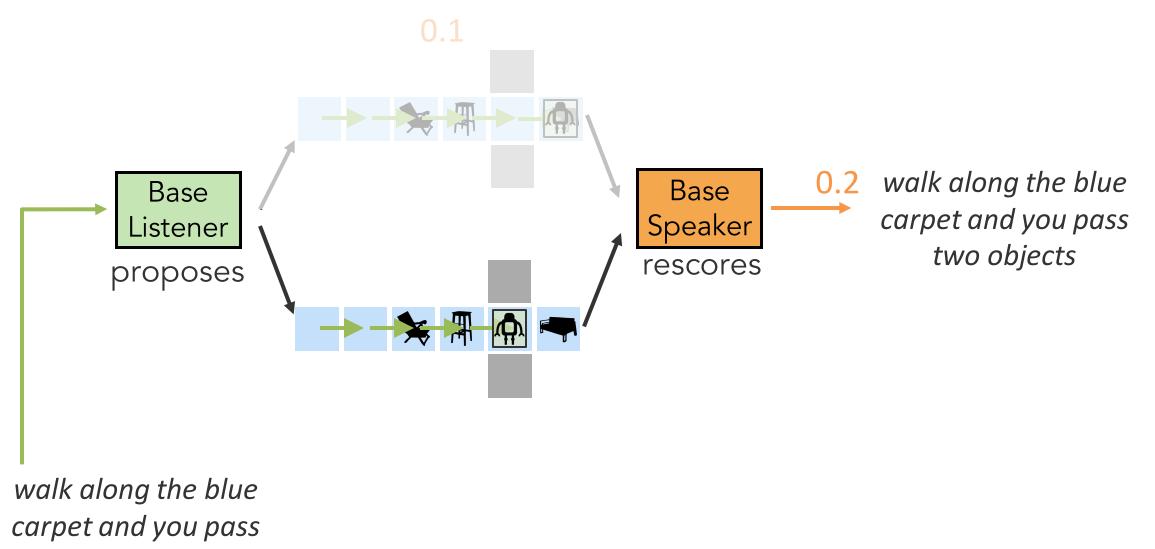






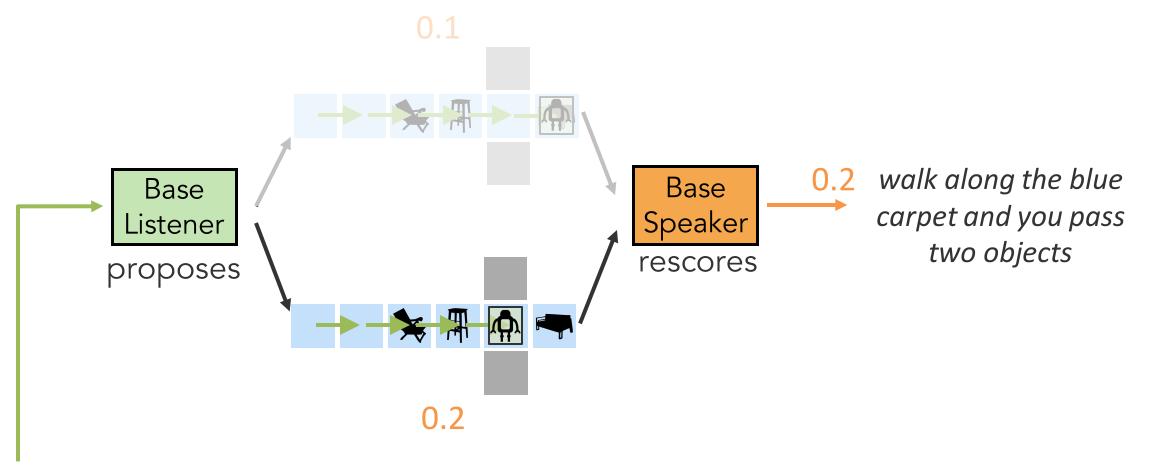




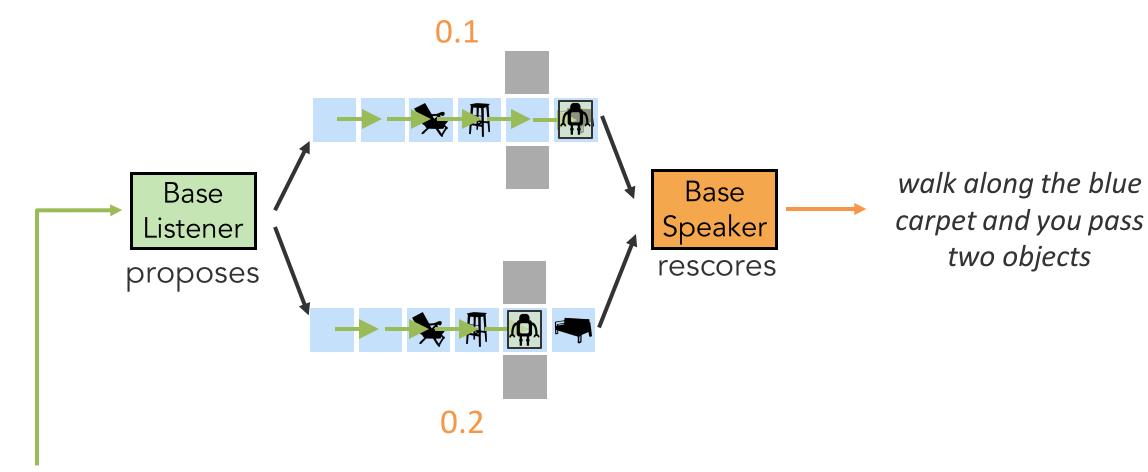


two objects

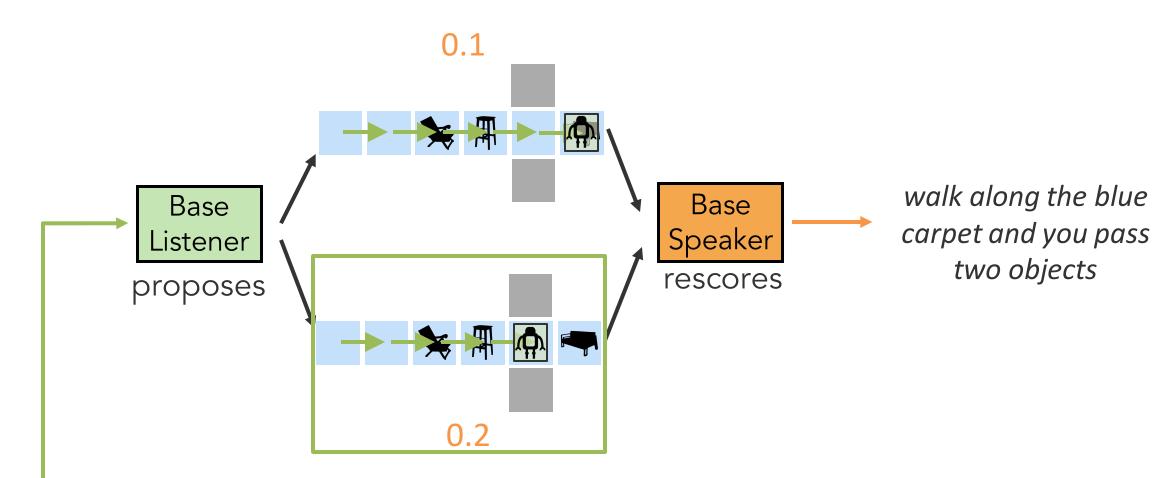




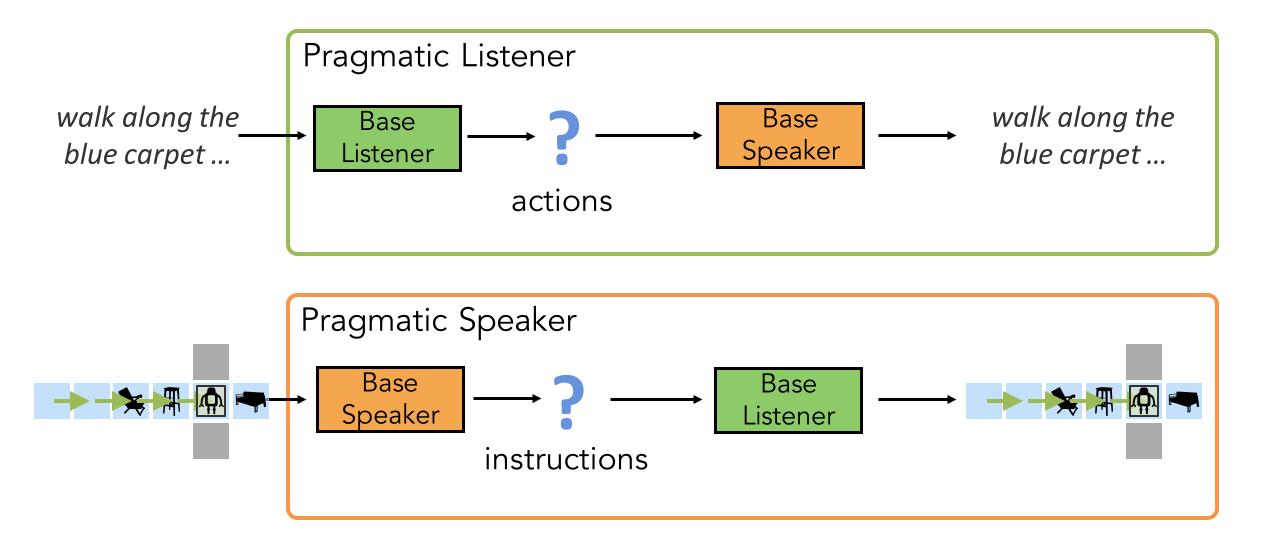




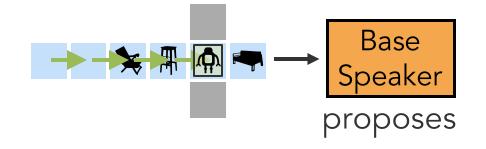




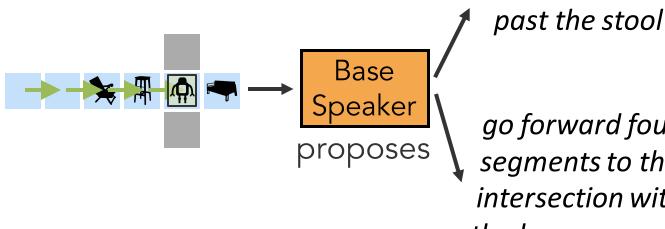
### Unified pragmatic inference







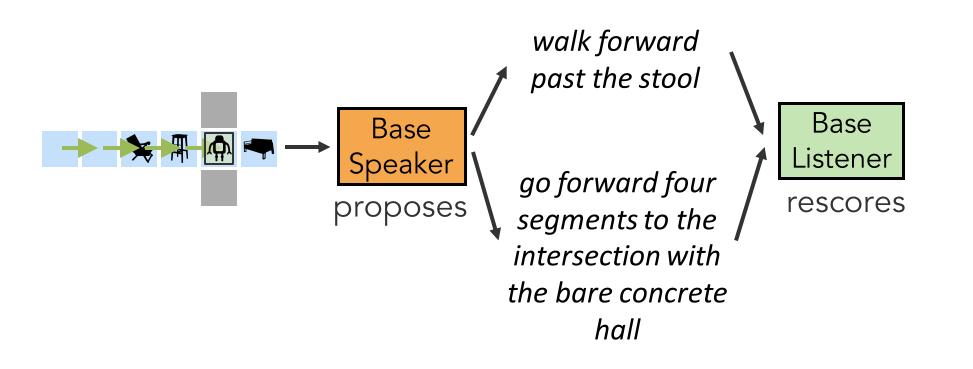




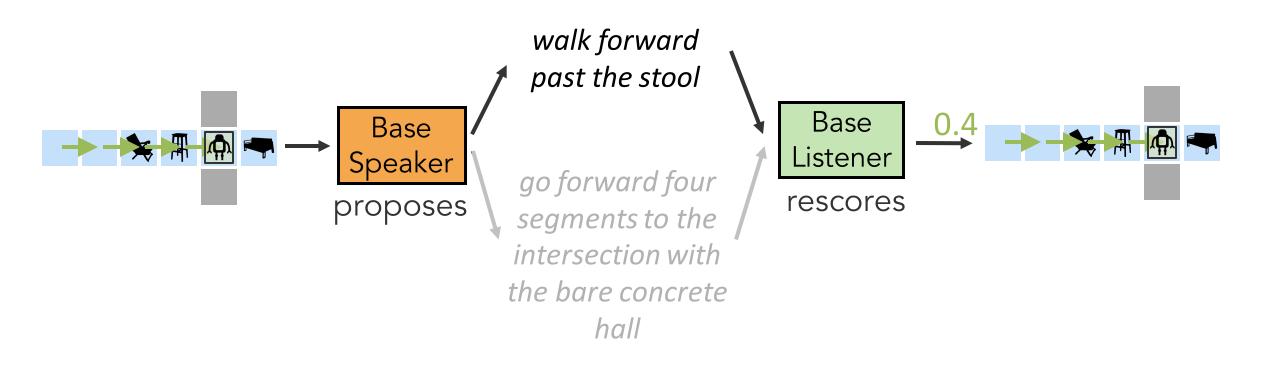
go forward four segments to the intersection with the bare concrete hall

walk forward







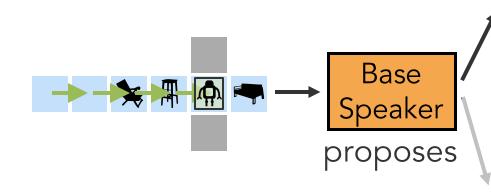




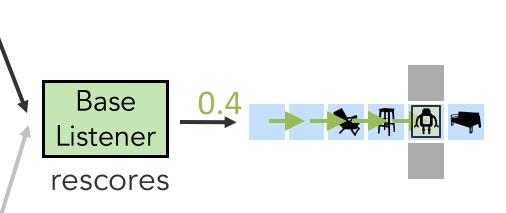


walk forward

past the stool

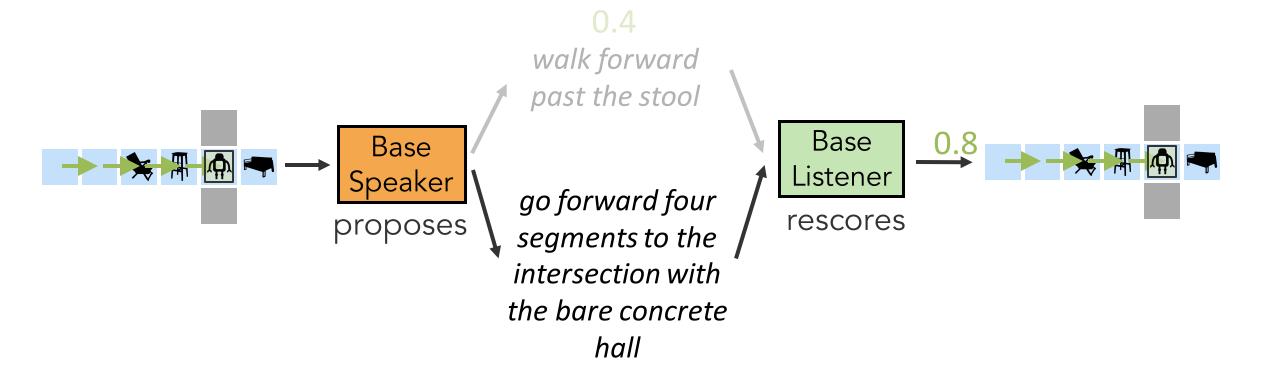


go forward four segments to the intersection with the bare concrete hall



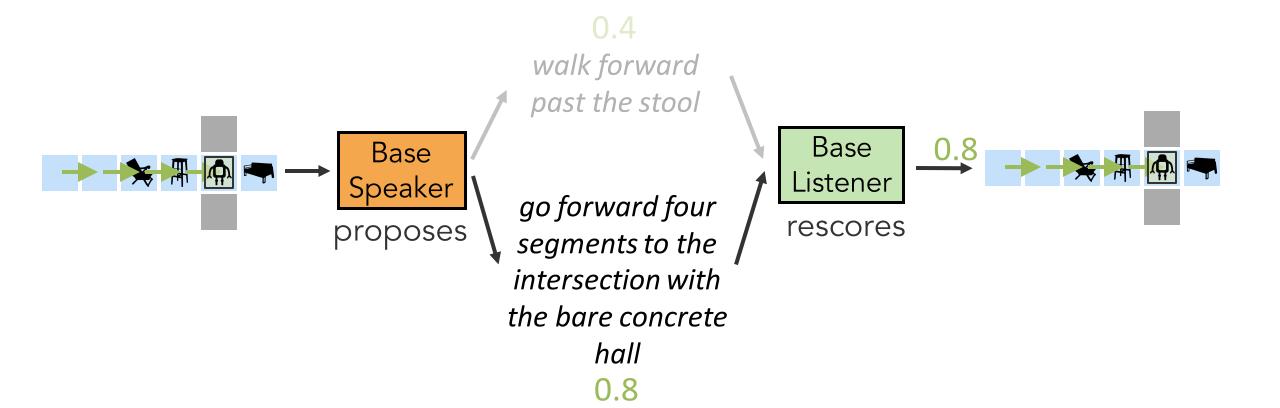


# Building a pragmatic speaker



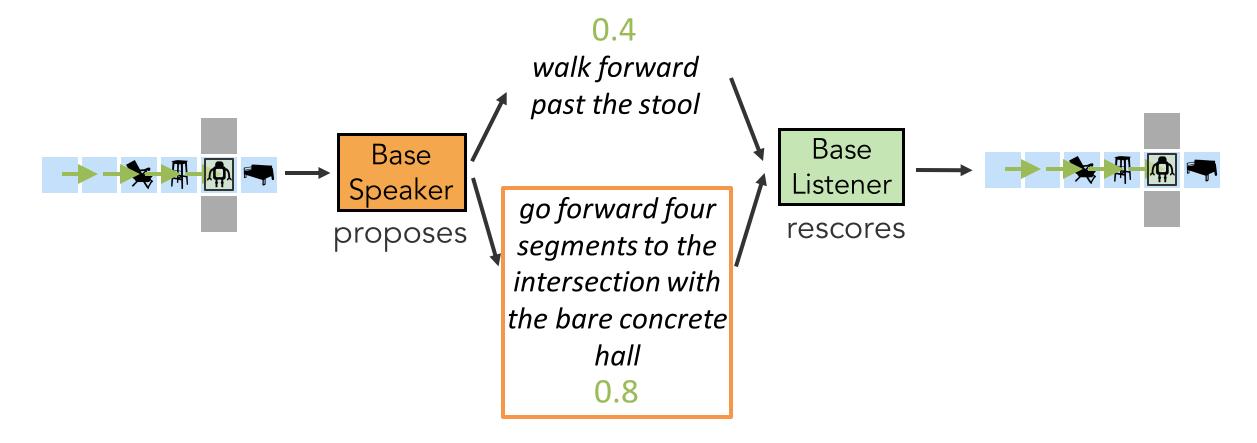


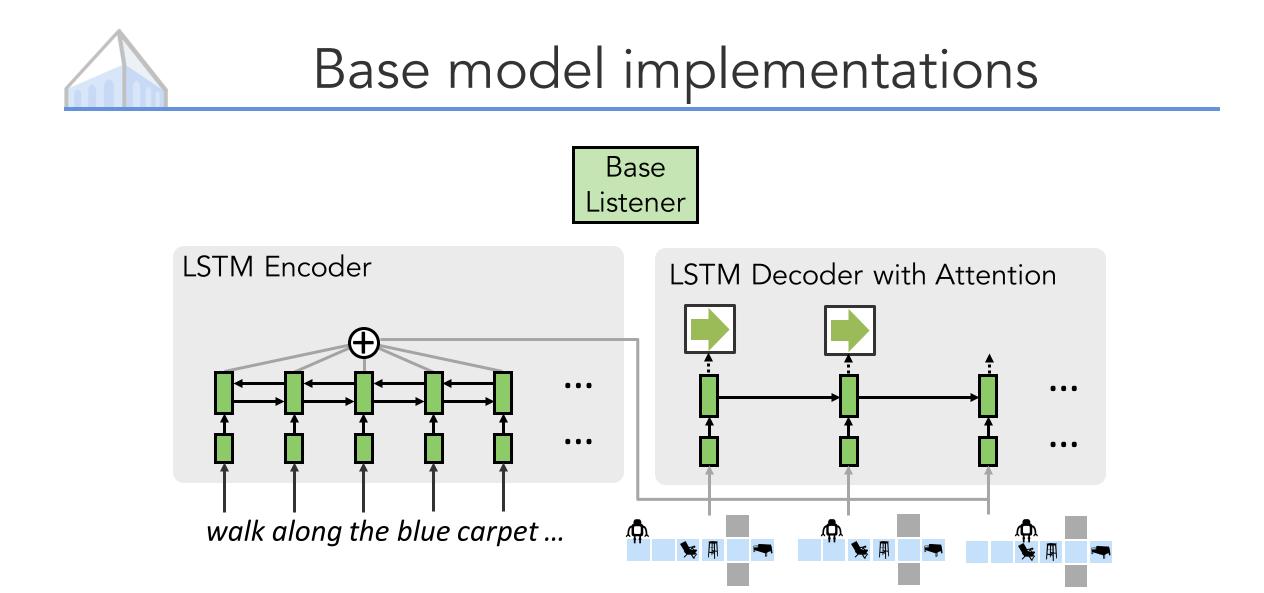
# Building a pragmatic speaker





## Building a pragmatic speaker

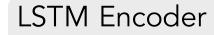


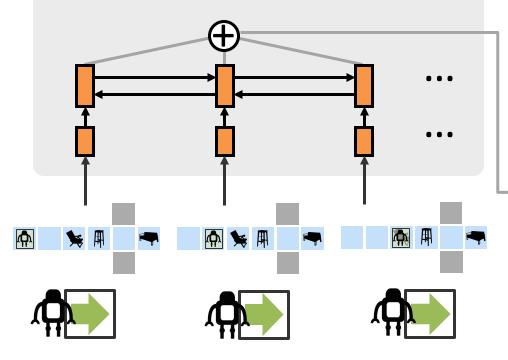


[Mei et al., 2016]

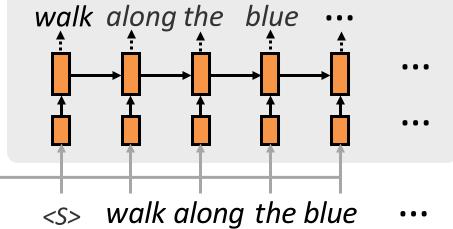
### Base model implementations





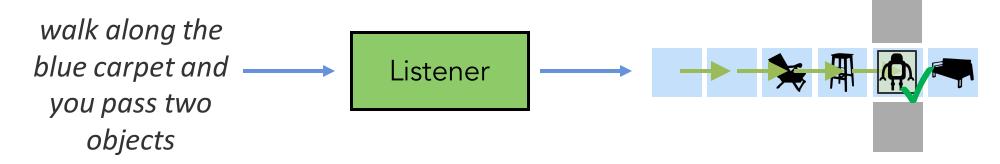


LSTM Decoder with Attention

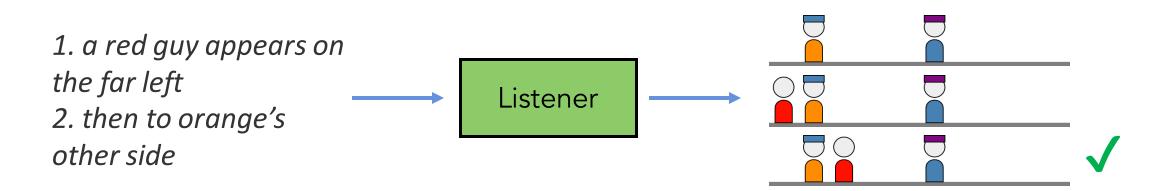


### Listener tasks

SAIL navigation [MacMahon et al., 2006; Chen and Mooney, 2011]



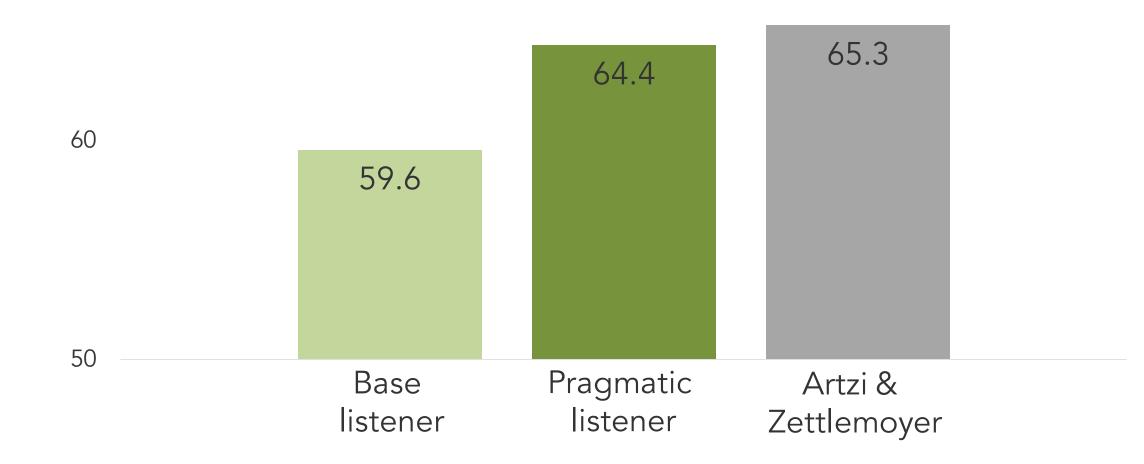
Sequential Context-dependent Execution (SCONE) [Long et al. 2016]



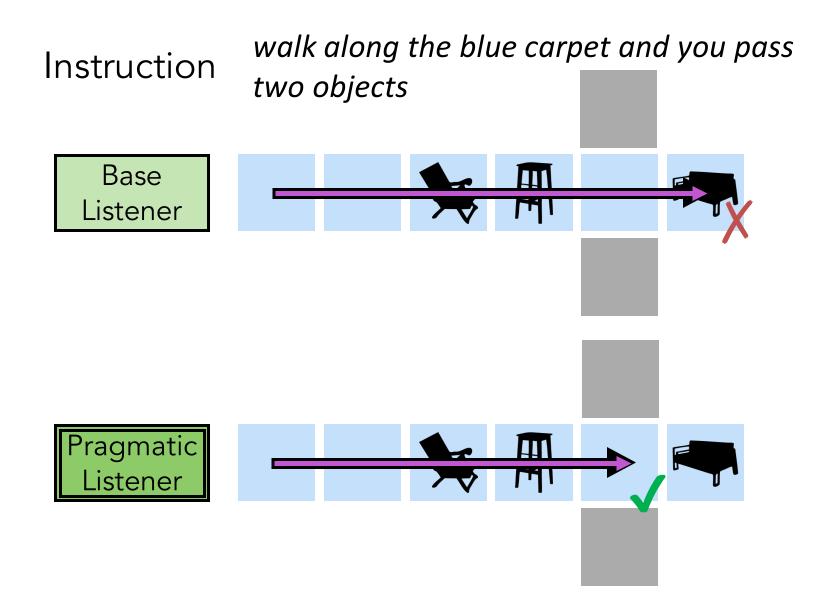
### Listener results, SAIL

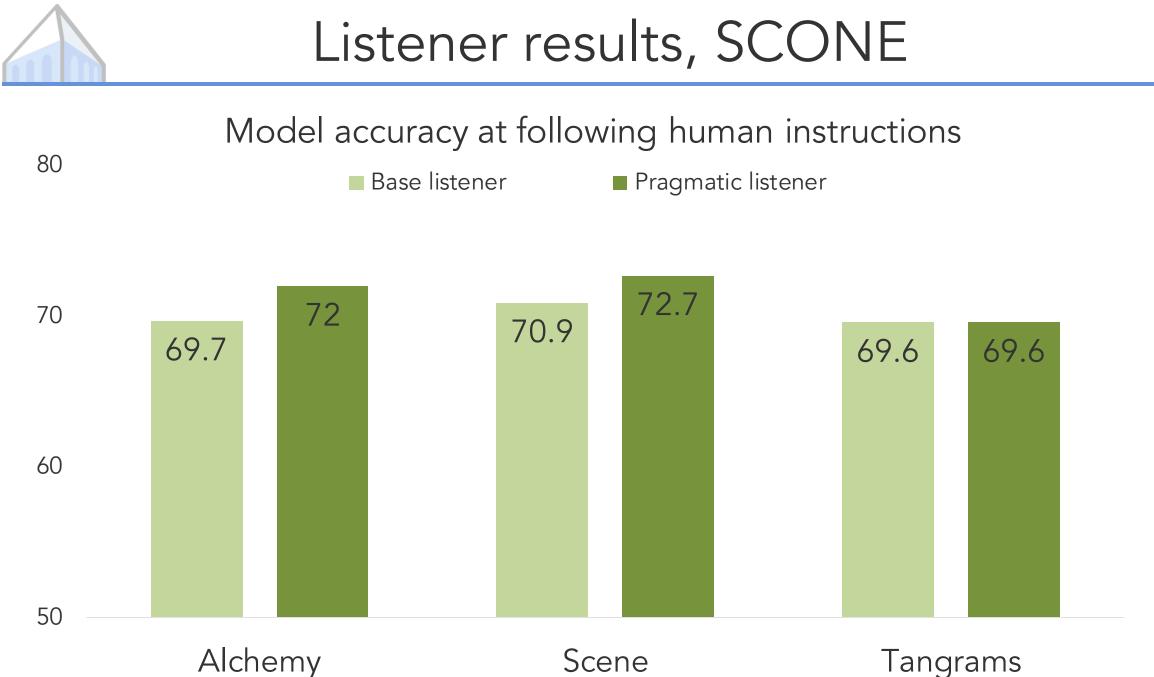
### Model accuracy at following human instructions

70



### Listener example, SAIL

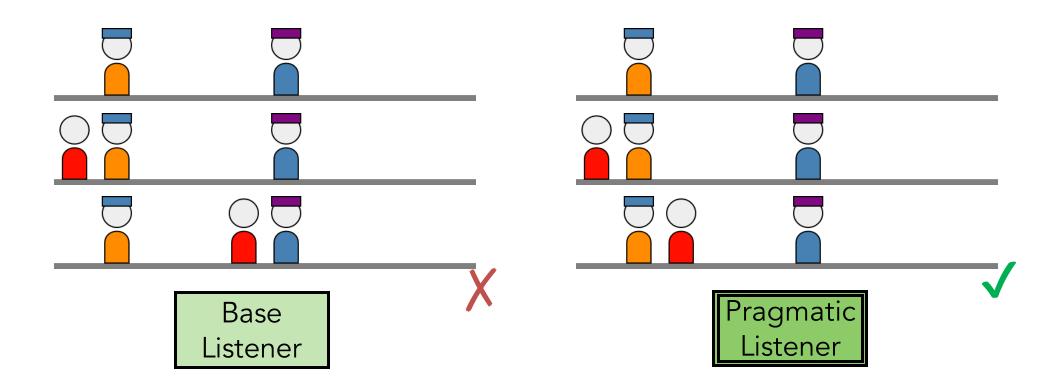






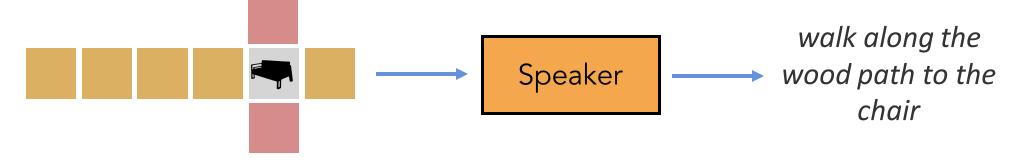
### Listener example, SCONE

### Instruction *a red guy appears on the far left then to orange's other side*





### Speaker produces an instruction

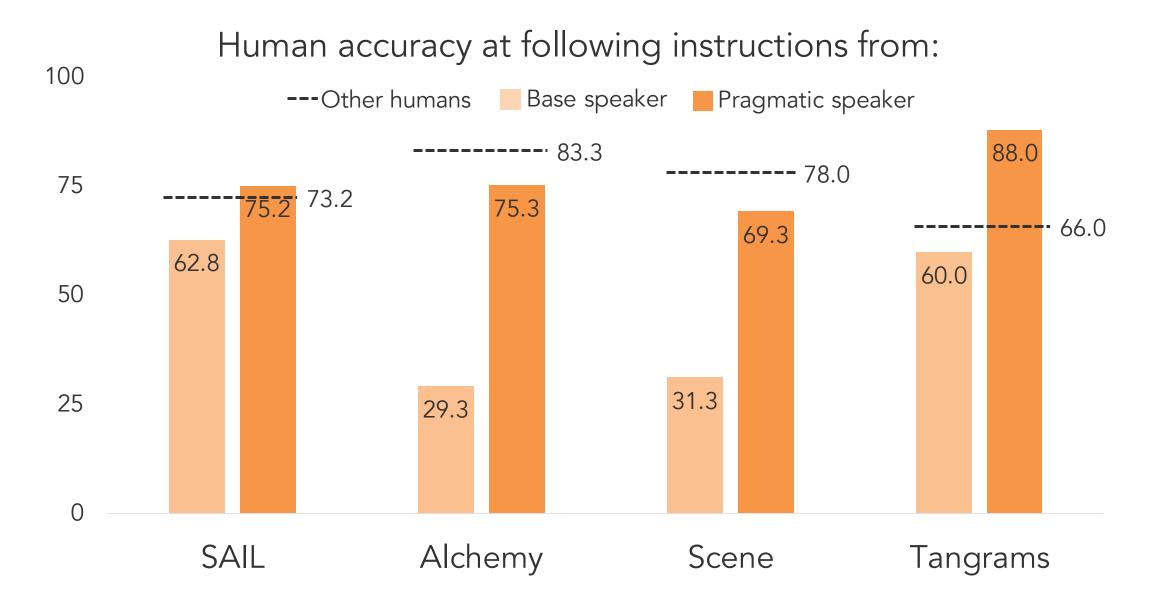


### Humans try to interpret it

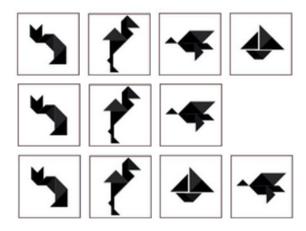
walk along the wood path to the chair

Human direction followers (MTurk)

### Speaker results



# Speaker example, SCONE





*remove the last figure add it back* 

X



*remove the last figure add it back in the 3rd position* 



take away the last item undo the last step



# Real-world navigation

Matterport3D vision-and-language navigation dataset [Anderson et al., 2018]



#### human description:

walk through the kitchen. go right into the living room and stop by the rug.

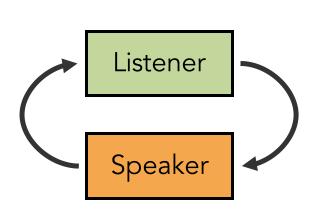
#### base speaker:

walk past the dining room table and chairs and wait there .

### pragmatic speaker:

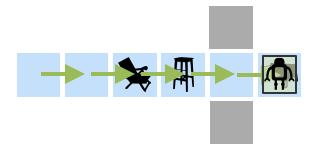
walk past the dining room table and chairs and take a right into the living room . stop once you are on the rug .





Unified inference for sequential interpretation and generation

Reasoning counterfactually, and about likely interpretations



Pragmatics helps for complex tasks in structured domains

# Thanks!

http://github.com/dpfried/pragmatic-instructions