

UNIVERSITY OF CALIFORNIA
Department of Electrical Engineering
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Computer Science Division

CS 282
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Assignment 2

Due: Thursday, 19 Feb 2004

One major approach to the problem of simplification of mathematical expressions is to define and maintain a canonical form valid over some interesting class of expressions as elements in that class are manipulated. In this problem set you will devise and analyze a canonical form for *sc-series* (sine-cosine series), a class of expressions we have invented for these exercises, but resembling so-called “Poisson” series used in Macsyma, CAMAL, and some other systems. Such series are typically highly useful in celestial mechanics (for orbital calculations) but are sometimes used for (mathematically similar) differential equations problems that occur in other disciplines.

We’ll define *sc-series* through the following sequence of informal definitions (If you need clarification or more formalism, ask):

- a *variable* is any alphanumeric name except for the literal “ ϵ ” which we reserved for later use. Examples: x , y , $t45$.
- a *rational number* is an integer or a pair of integers, numerator and denominator, in some suitable notation.
- a *term* is a rational number times a variable. Note that unless it causes confusion, we will denote multiplication by juxtaposition of symbols. Examples: $\frac{1}{2}x$, $3 t45$.
- an *arg* is a sum of one or more terms. Example: $\frac{1}{2}x - \frac{1}{3}y$.
- a *trigform* is a rational number times a non-negative power of the symbol ϵ times sin or cos of an *arg*. One example: $\frac{3}{4}\epsilon^2 \sin(\frac{1}{2}x + y)$. Another example: $\frac{8}{5}\epsilon^0 \cos(3 t45)$ ($= \frac{8}{5} \cos(3 t45)$).
- an *sc-series* must be able to represent any sum of trigforms.

We will not formally specify the meaning of these expressions, but they are meant to correspond to the usual applied-mathematics notions of computations over rational complex numbers, indeterminates (to the extent you need to be aware of this, the indeterminates denote complex numbers, and not, say, matrices), and the trigonometric functions. The common interpretation of trig functions should tell you what we mean by differentiation, for example.

1. In order to make sure that any two equivalent expressions are identical if expressed as sc-series, a number of other constraints must be placed upon the form. For example we could insist that the *terms* in the *arg* are in alphabetic order by *variable* name, and there are no duplicate names. What other constraints do you recommend, and why? (You may interpret this question as requiring you to eliminate the informality in the above specifications.)

2. How do you propose to represent rational constants? How about zero? The constant π is not available in this representation. What would happen if it were?

3. In order to make some use of sc-series, we need to develop programs for the following operations: Given an sc-series s , we must be able to compute the derivative or the integral of s with respect to some variable v . (The result must also be in canonical form, of course.)

Given two sc-series s and t , we must be able to compute their sum, their product, and their difference.

While you need not actually write these programs (although you may if you wish), provide enough of a pseudo-code description to demonstrate that you've addressed all important mathematical or representation issues. In particular, you should characterize the costs of running these programs, stating any assumptions you are making along the way.

4. There is a transformation which preserves equivalence only approximately turns out to be of some use. Given a series s , expand it in a new series s' where a particular variable, say x is known to be a small quantity, ϵ . Then an integer degree d is chosen and $\sin x$ and $\cos x$ are expanded in power series to degree d . For example, if $d = 3$, then $\sin(x + y)$ is (approximately) $\sin y + \epsilon \cos y - \frac{1}{2}\epsilon^2 \sin y - \frac{1}{6}\epsilon^3 \cos y$. The dependence on x is changed from trigonometric to algebraic. Explain how to do this. (Pseudo-code algorithm, cost)

5. Computing $u := s^4$ can be done by computing $t := s * s$ and then $u := t * t$. Or it can be computed by $t := s * s$, $v := s * t$, and finally $u := s * v$. Discuss which is better. This requires that you refer to your cost model of multiplication of sc-series (in answer to question 3) carefully. You will probably have to specify how you are storing sc-series. You should also make some statements about the maximum, minimum, and/or likely sizes of s , t , u , and v in order to complete your analysis.