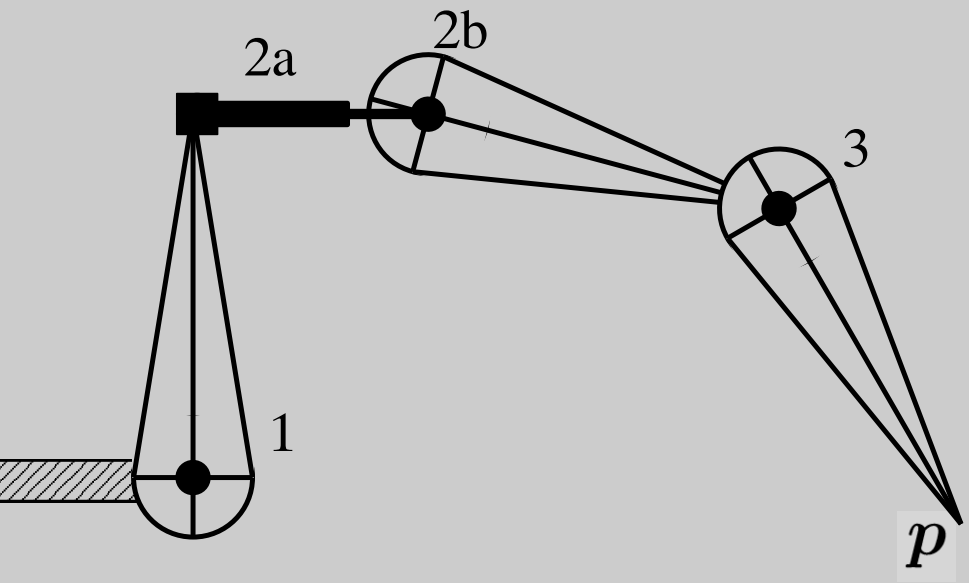

$$\tilde{J} = [J_3 \; J_{2\mathrm{b}} \; J_{2\mathrm{a}} \; J_{1\mathrm{b}}]$$

$$\boldsymbol{d} = \begin{bmatrix} d_3 \\ d_{2\mathrm{b}} \\ d_{2\mathrm{a}} \\ d_{1\mathrm{b}} \end{bmatrix}$$

$$\mathrm{d}\boldsymbol{p} \neq \tilde{J} \cdot \mathrm{d}\boldsymbol{d}$$