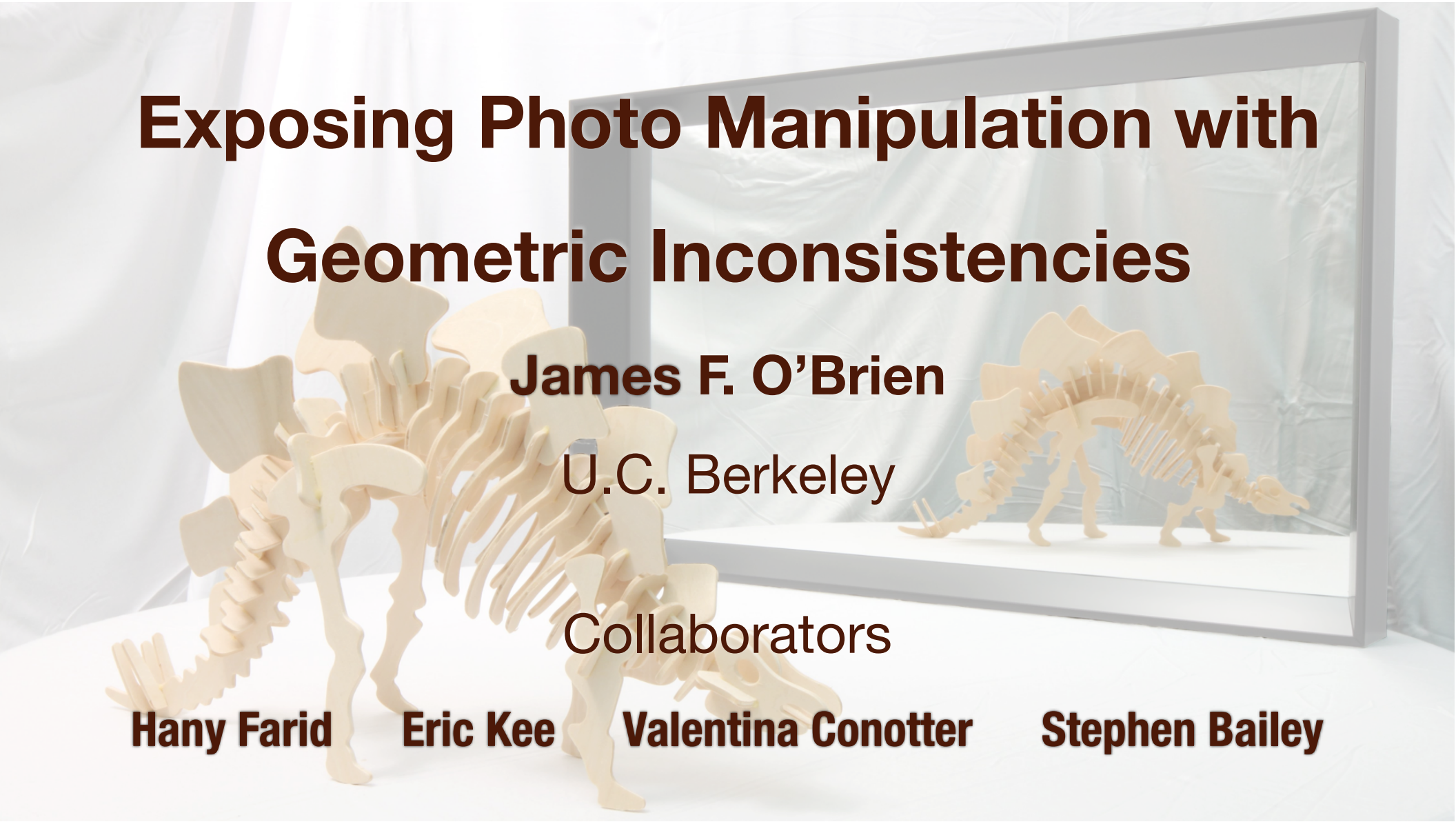


Exposing Photo Manipulation with Geometric Inconsistencies

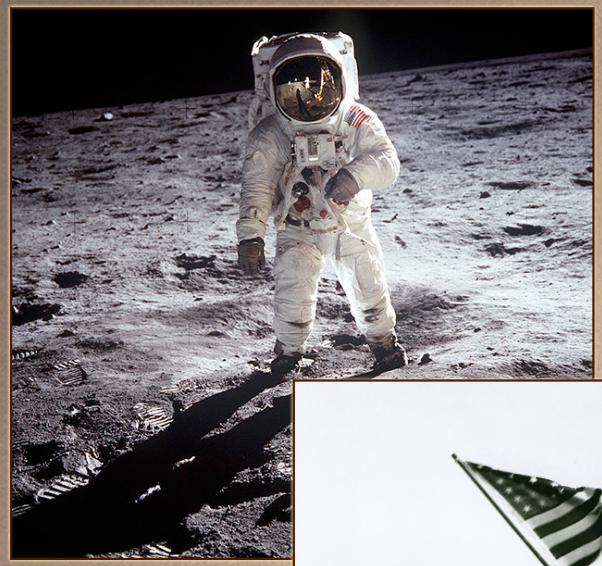
James F. O'Brien

U.C. Berkeley

Collaborators

Hany Farid **Eric Kee** **Valentina Conotter** **Stephen Bailey**

Communication by Images



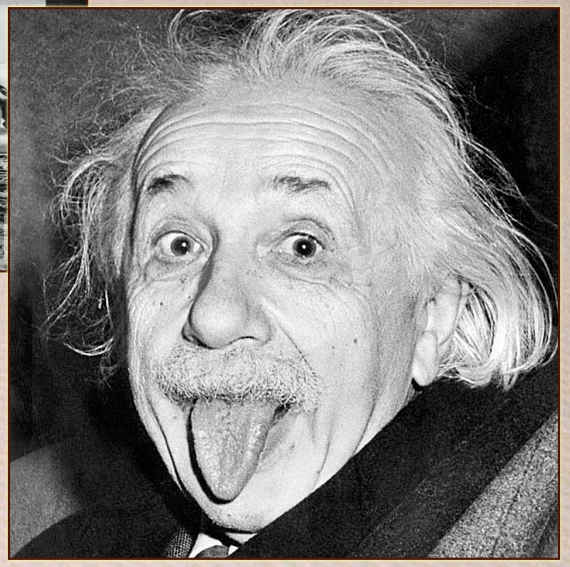


Image Manipulation

Iranian missile test, 2008

Image Manipulation

Iranian stealth fighter, 2013

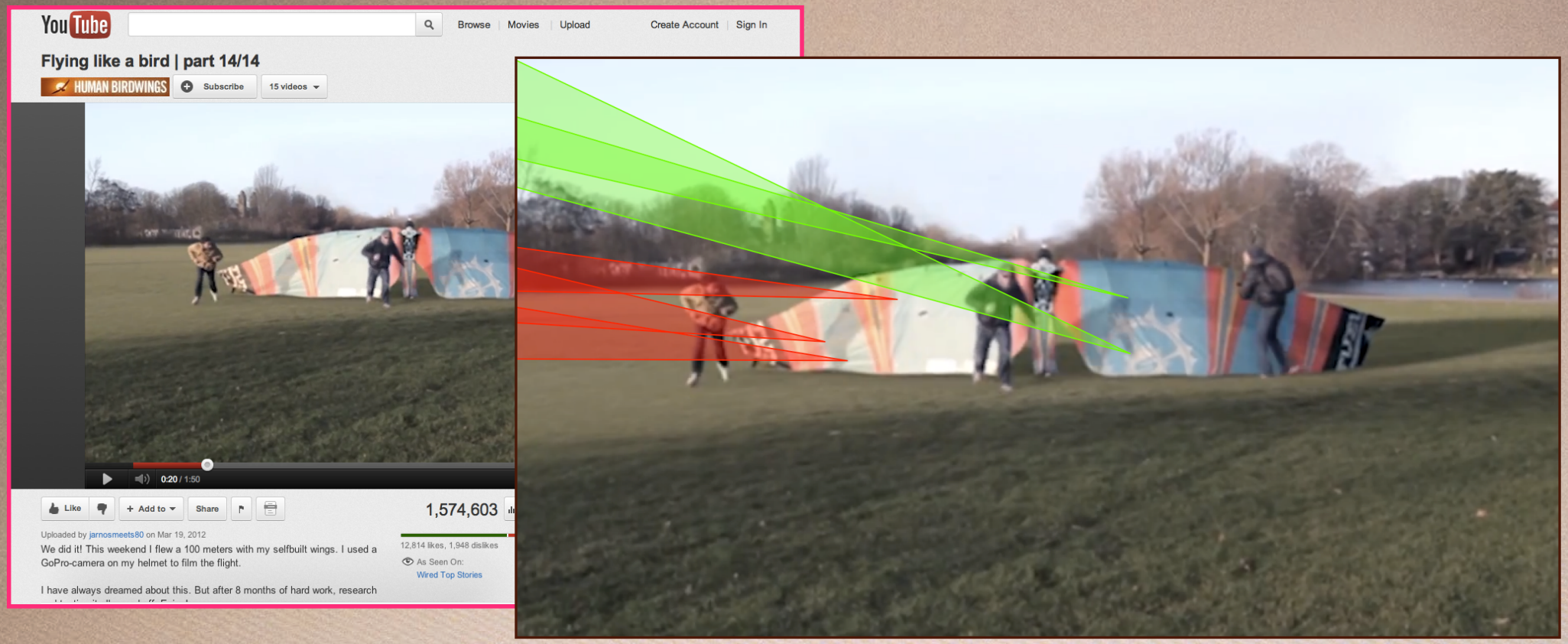
Image Manipulation

Economist manipulates image of Obama, 2010

Image Manipulation

Fabricated image of John Kerry and Jane Fonda, 2004

Video Manipulation

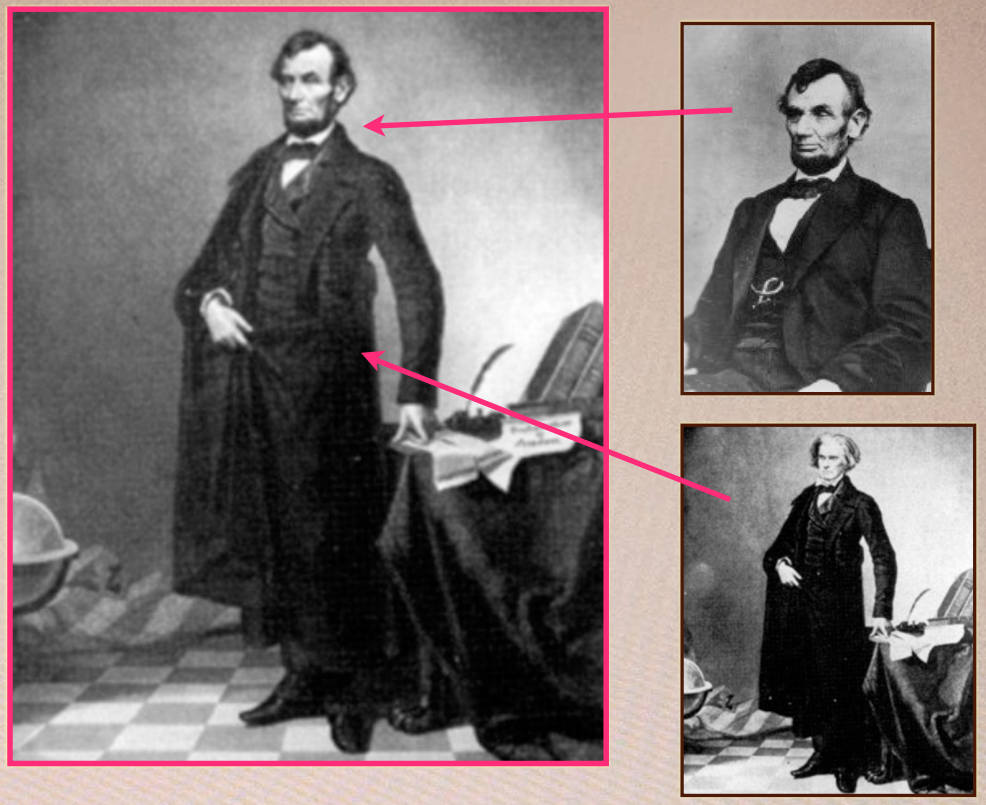


Flying Birdman Hoax, 2012

Historical Image Manipulation

Historical Image Manipulation

- Image manipulation as old as photography
- Primitive techniques work surprisingly well



Library of Congress archive photo of Abraham Lincoln 1826

Image Forensics

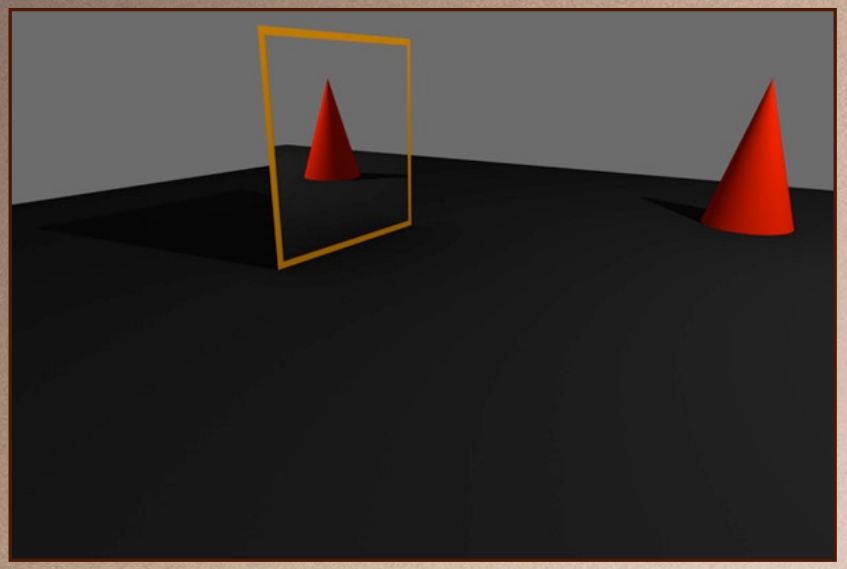
- Detect forgeries
  - Detect signs of manipulation
    - **Prove image was modified in some way**
  - Cannot *prove* an image *unmodified*

- Suite of detection tools
  - Individual methods can be countered
  - Individual tools may not apply in all cases
  - Each additional method makes forgery harder

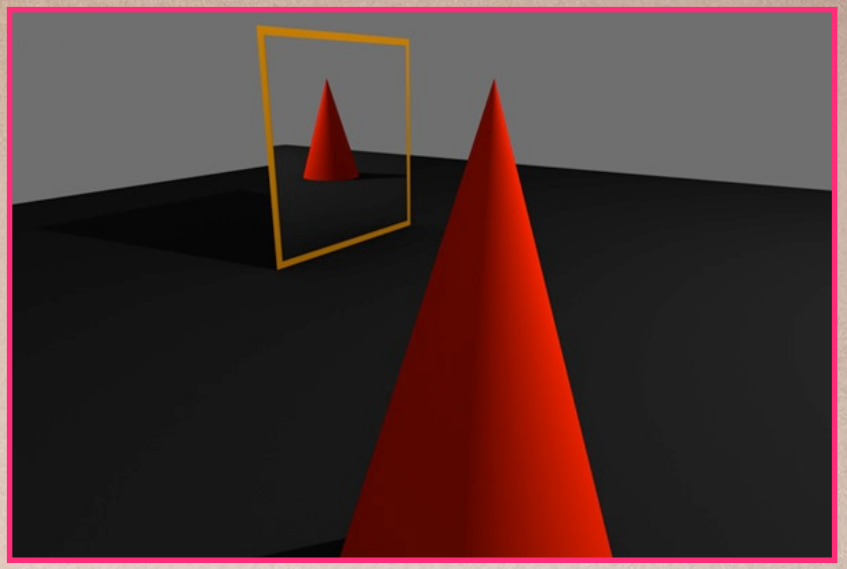
Advantage: Forgers

- People:
  - Good at understanding scene content
  - Poor at noticing many types of inconsistencies
- Simple manipulation methods work well
- New manipulation methods being developed

Example Inconsistency



Selected as correct: 62.1%



Selected as correct: 50.1%

N = 20; RT = 7.6s

Farid and Bravo 2010

Things we don’t see

Things we don’t see

Advantage: Forgers

- People:
  - Good at understanding scene content
  - Poor at noticing many types of inconsistencies
- Simple manipulation methods work well
- New manipulation methods being developed

Image Forensics

- **Format Methods**
  - EXIF meta data
  - Quantization tables
  - Coding decisions
  - Signatures or watermarks
- **Pixel Methods**
  - Linear dependance
  - Bayer pattern artifacts
  - Chromatic aberration
  - Compression artifacts

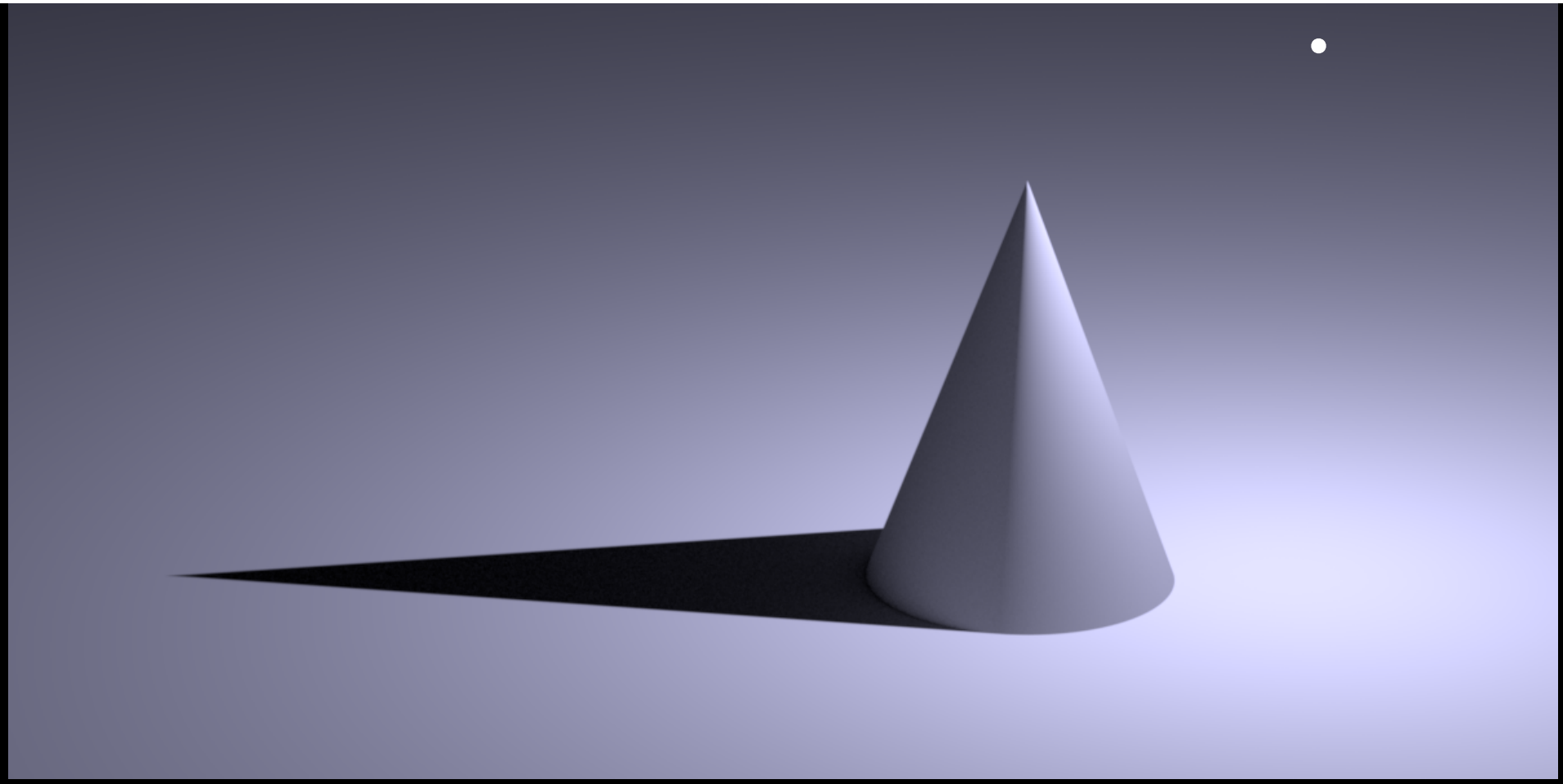
- Not tied to scene content
  - Easy to apply
  - Easy to fool (informed attacker)
  - Not robust to common operations

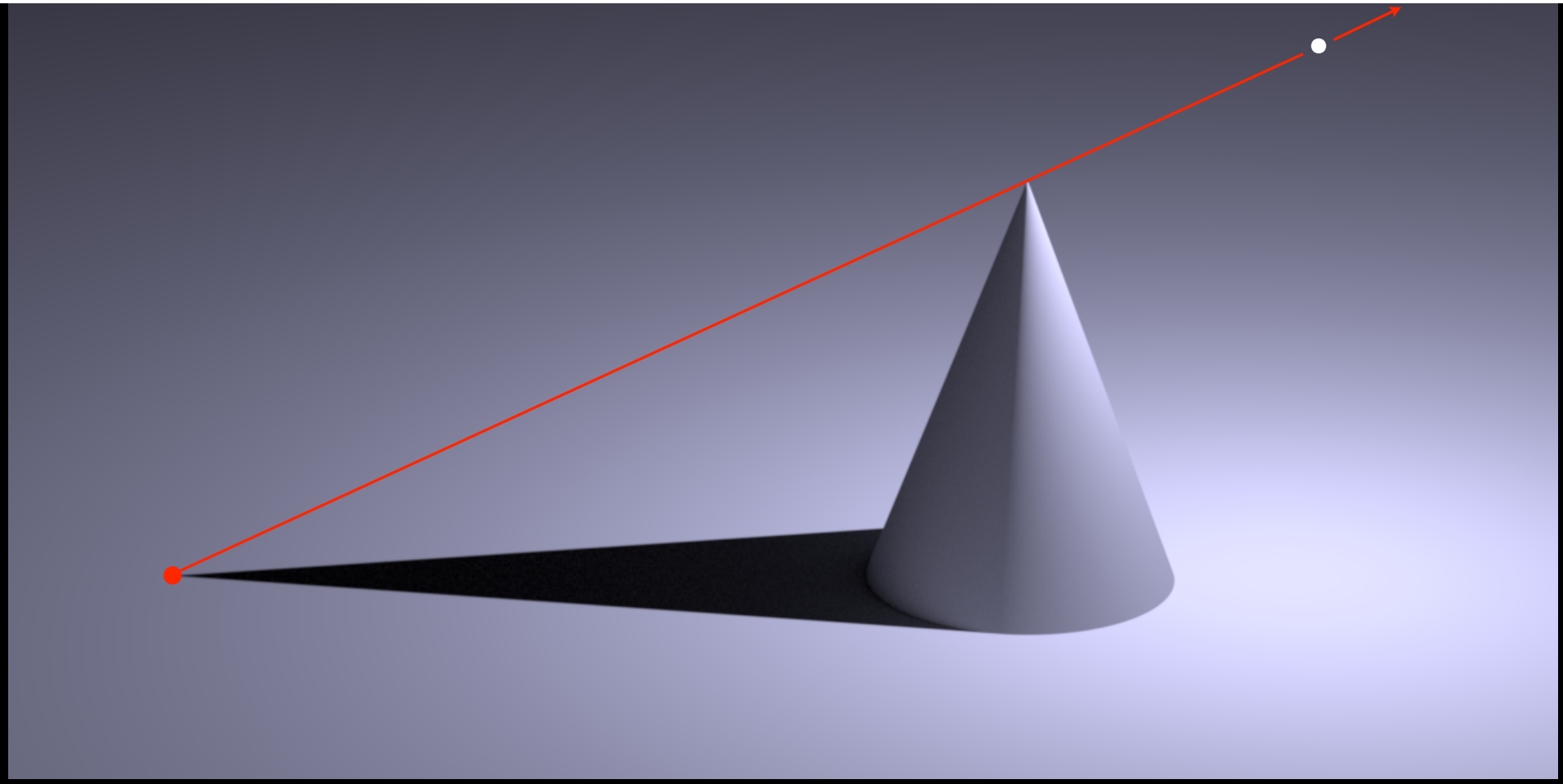
Image Forensics

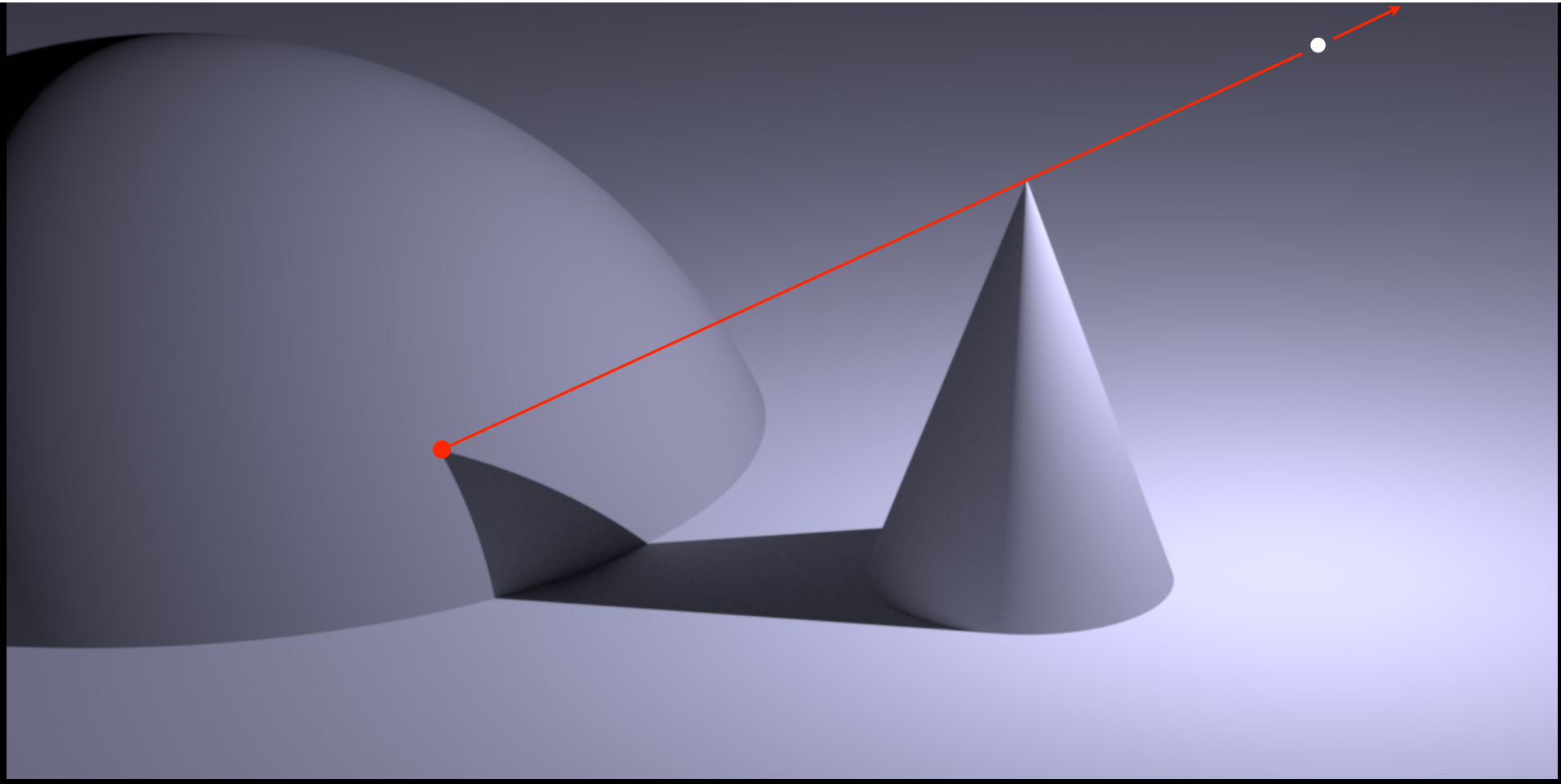
- **Geometric methods**
  - Content inconsistencies
  - Require human annotation
    - Computer analysis
  - Examples:
    - Shadows
    - Lighting
    - Reflections

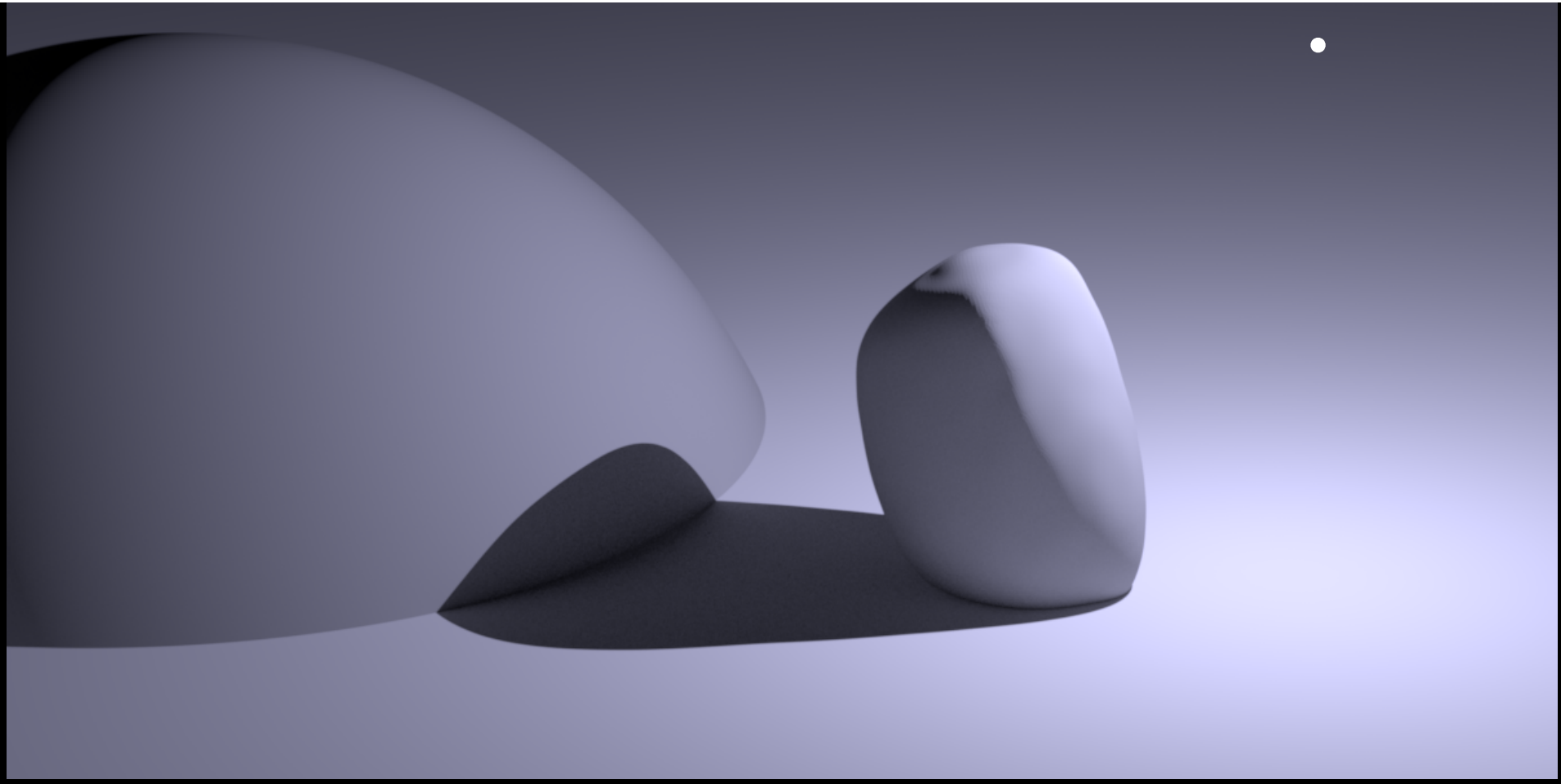
Geometric Image Forensics

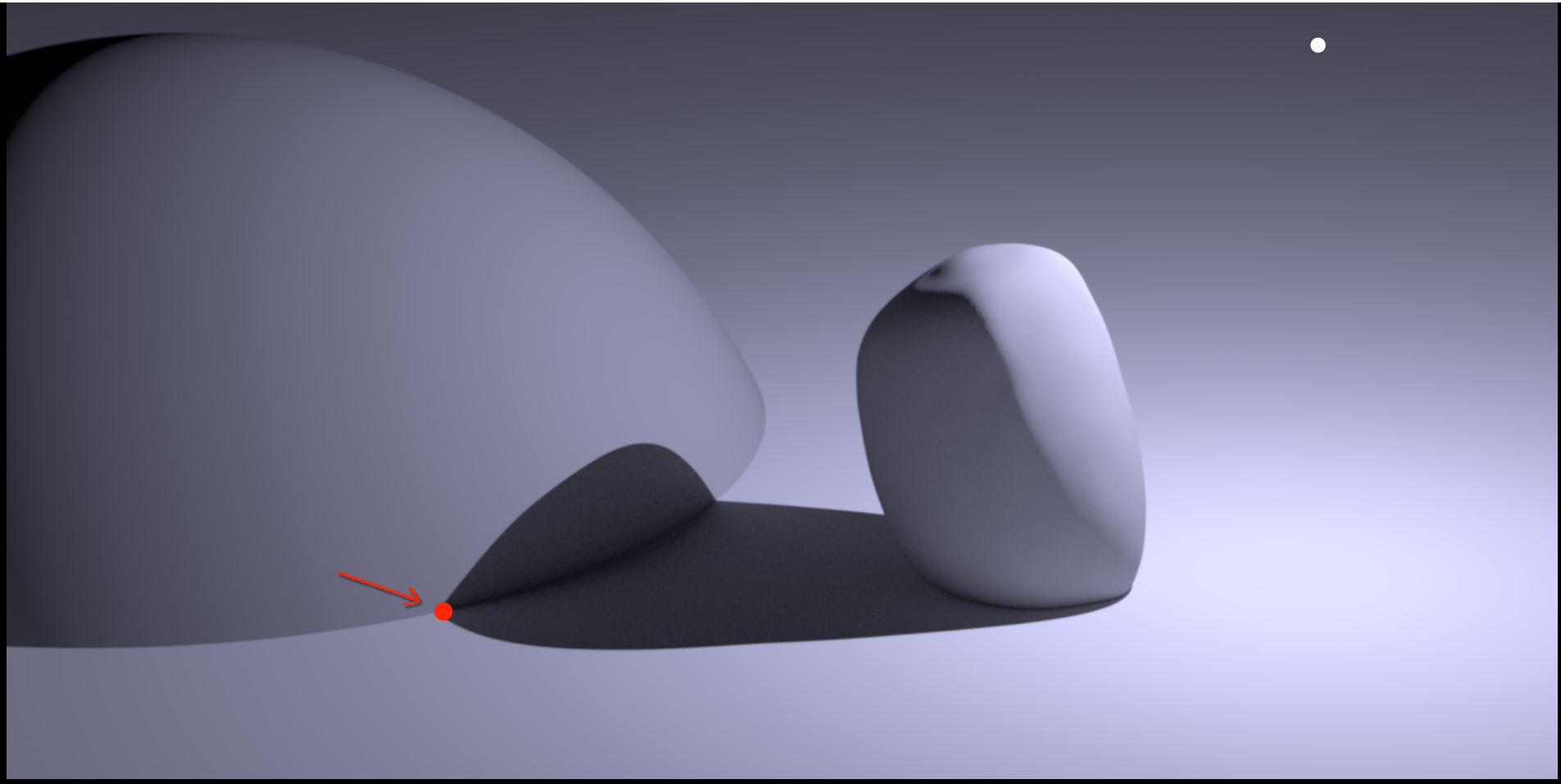
- Not same as Computer Vision
  - Possibly user involved in loop
  - Only looking for inconsistencies only
    - Don’t need to fully extract scene content

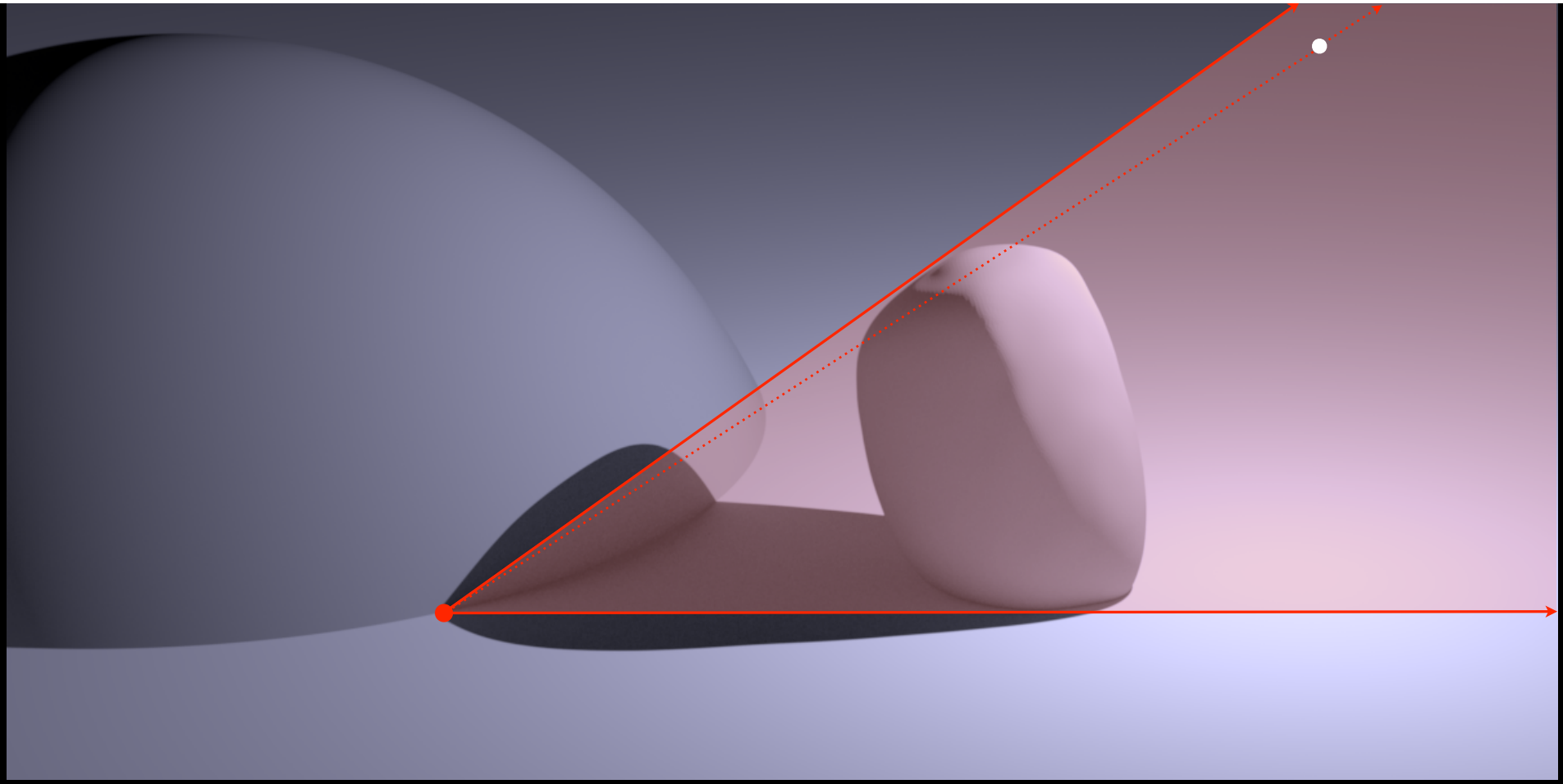


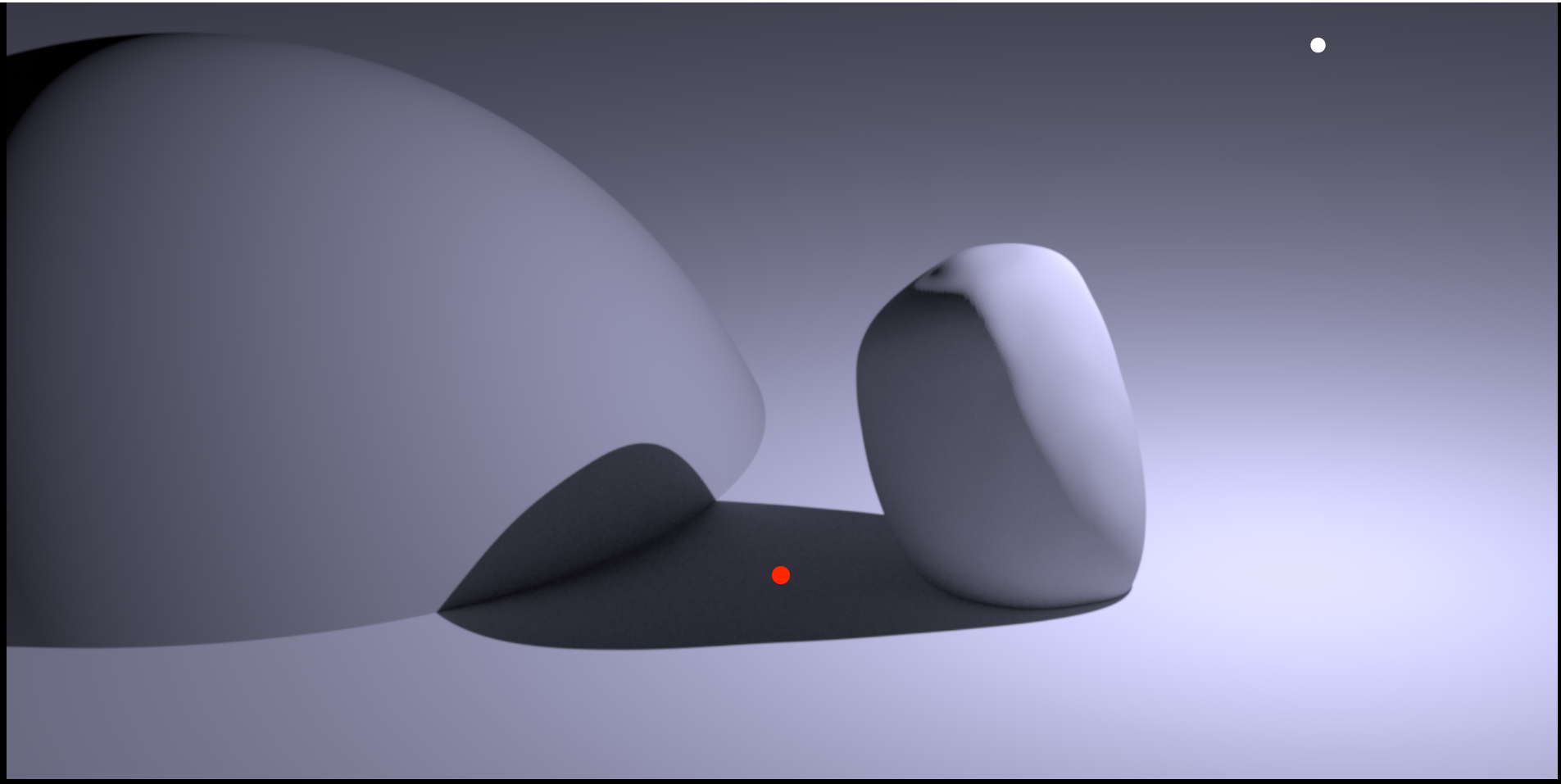


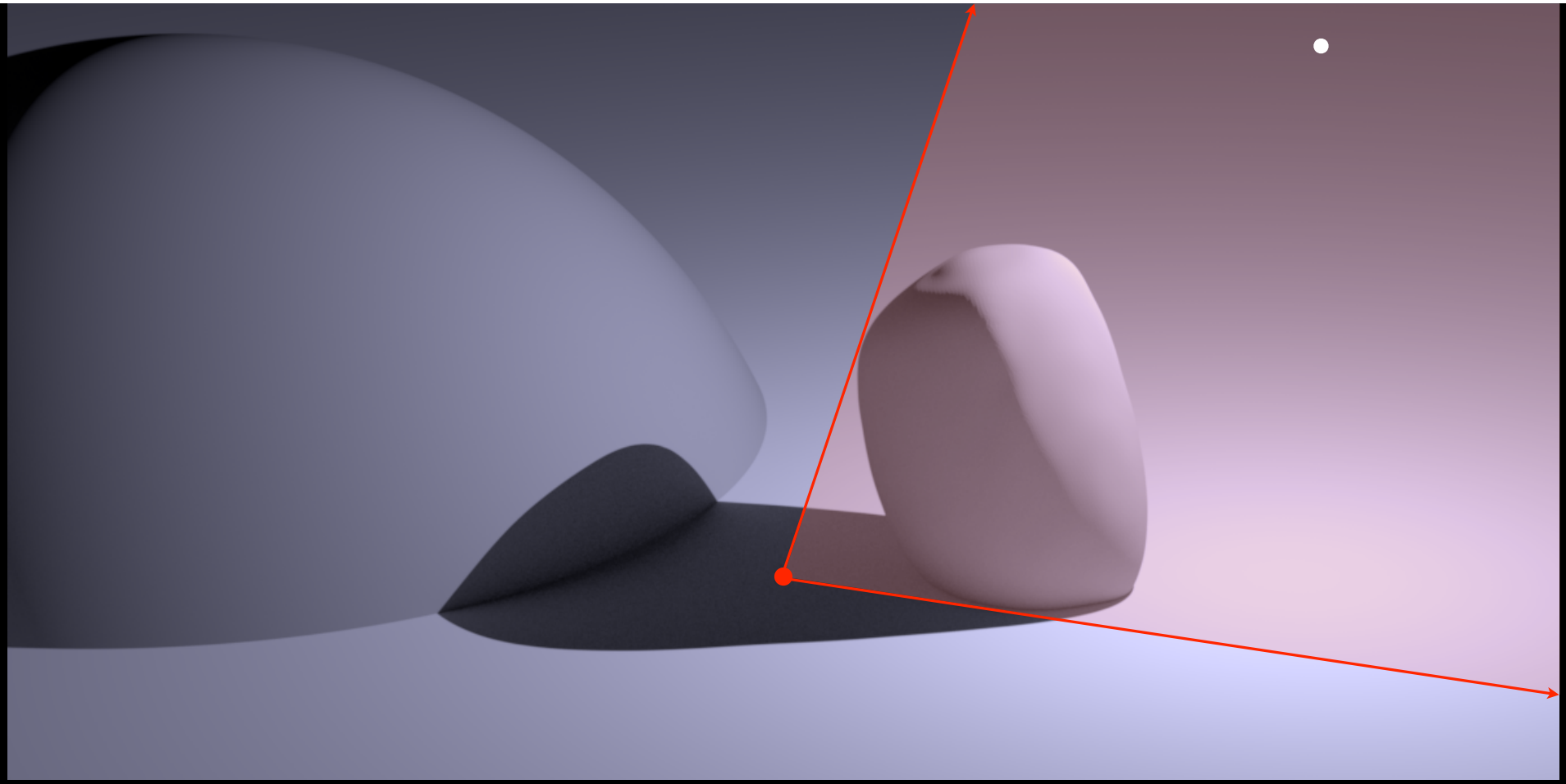


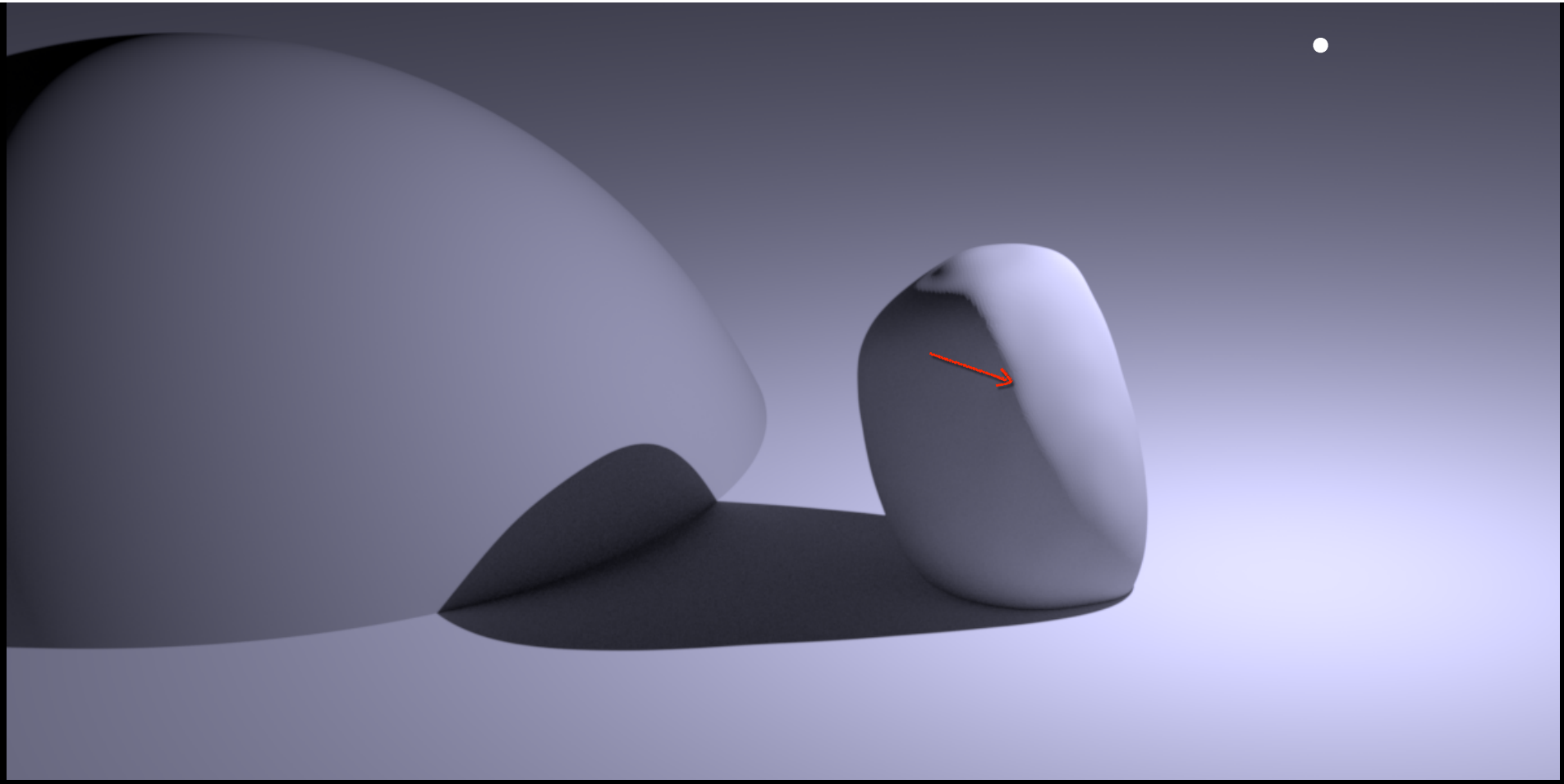


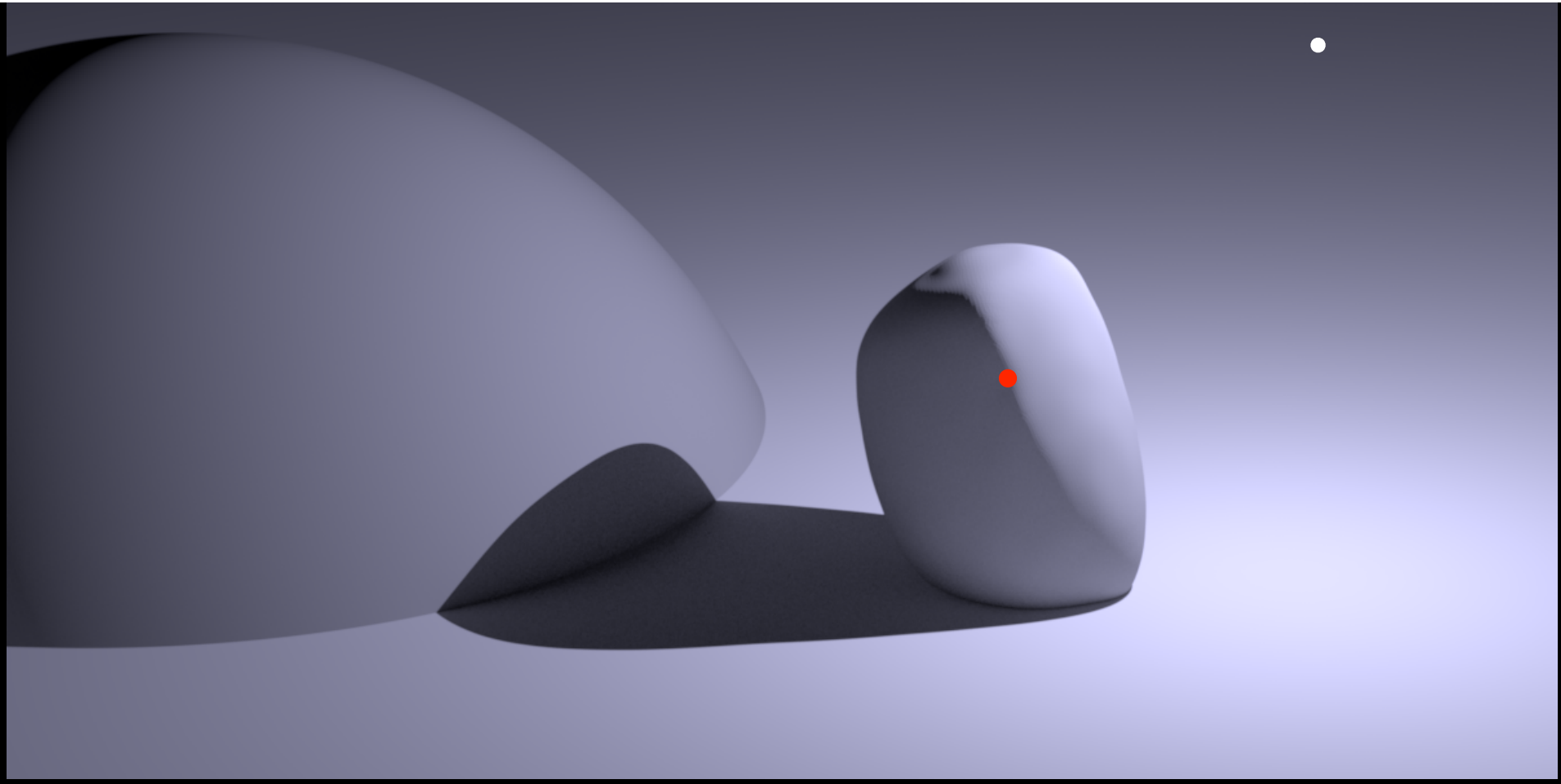


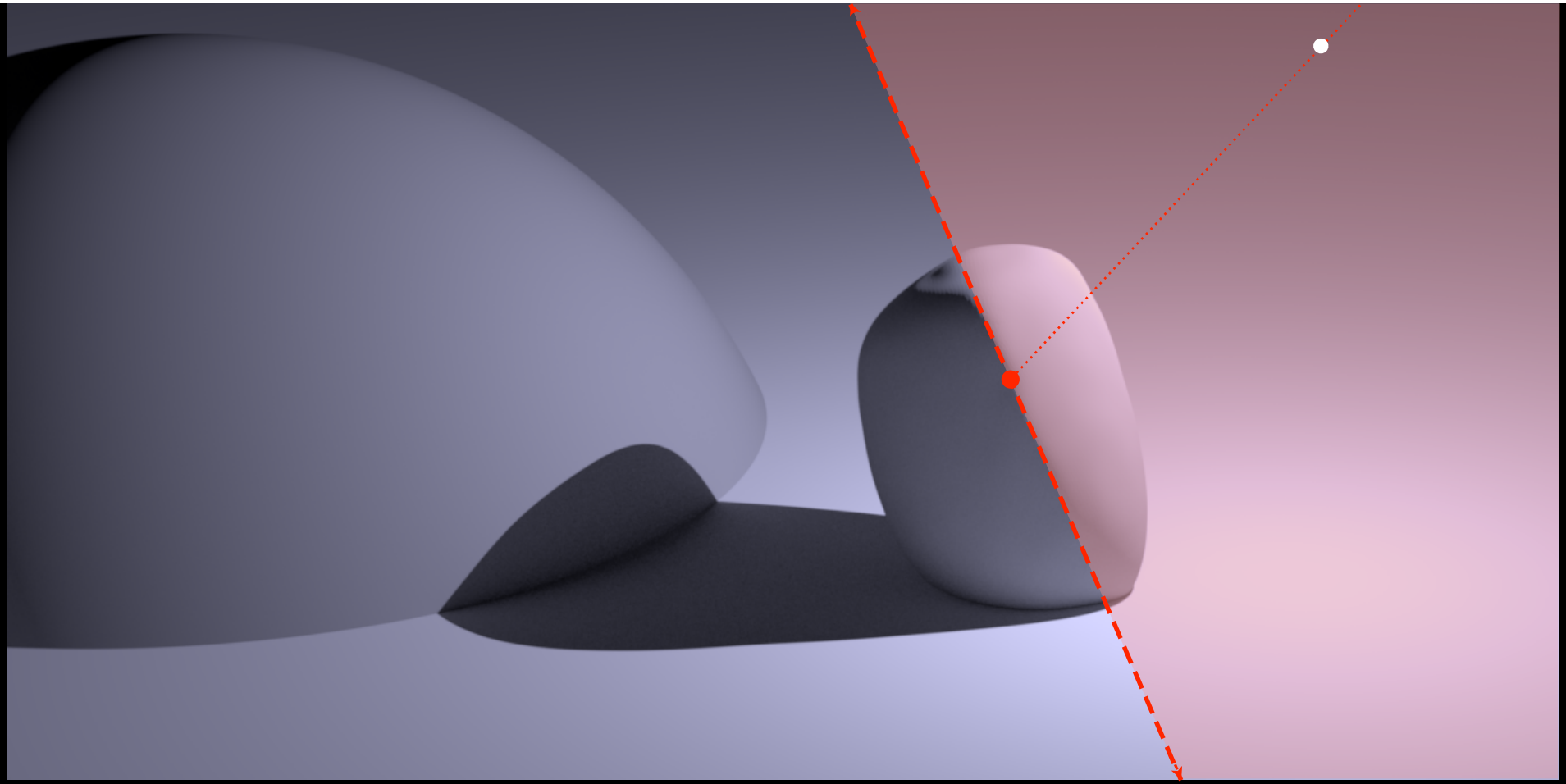


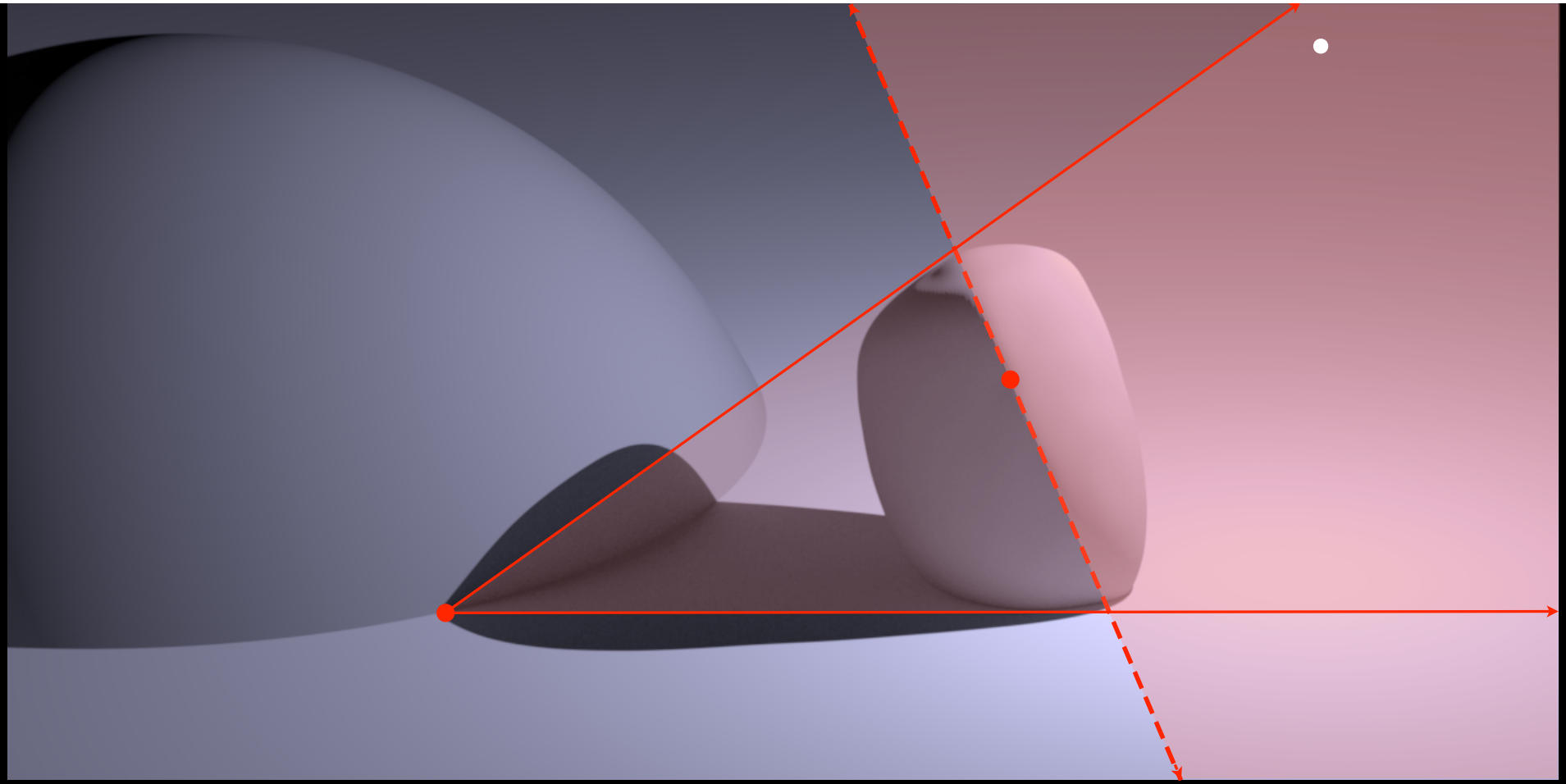


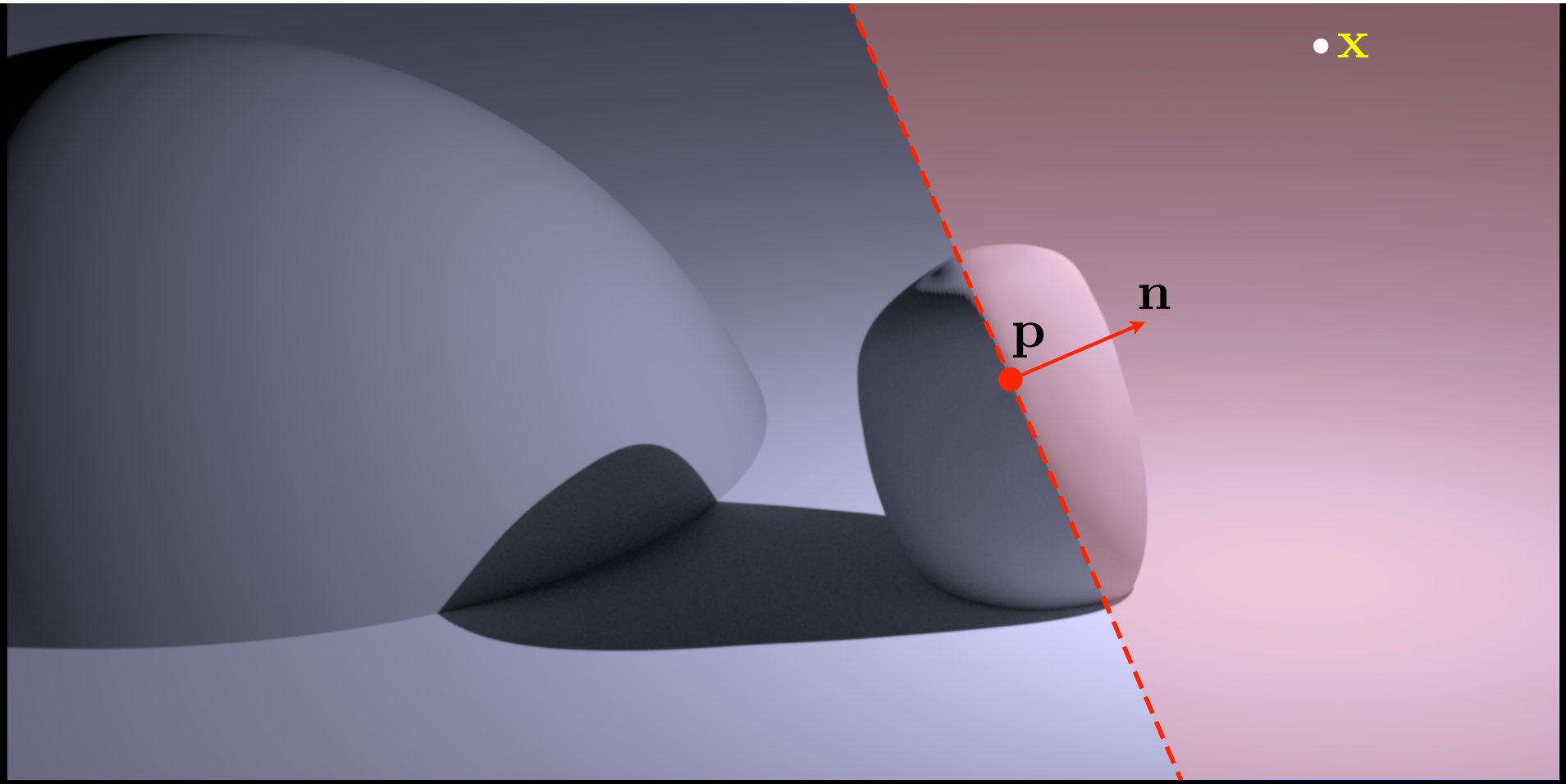


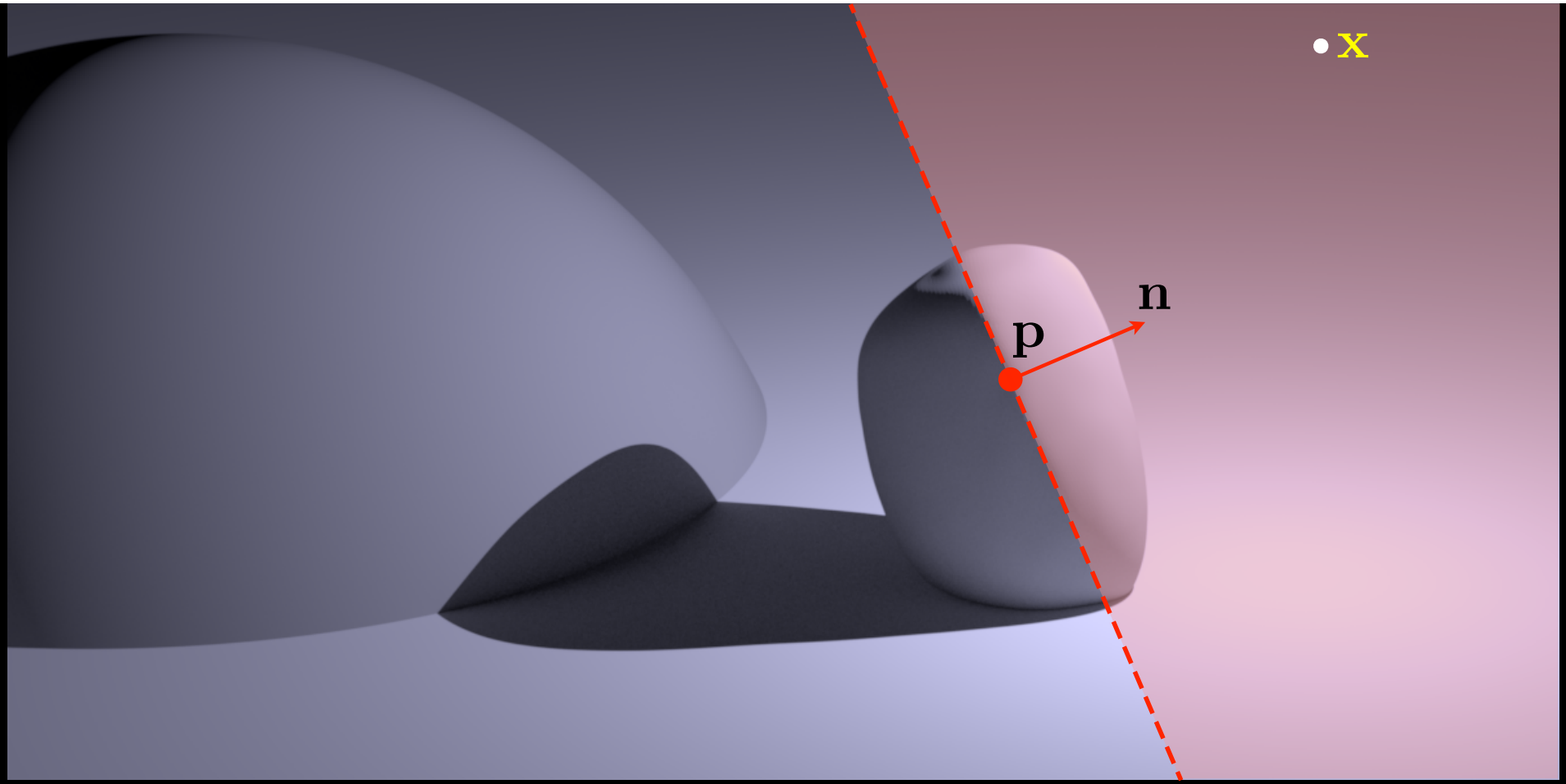




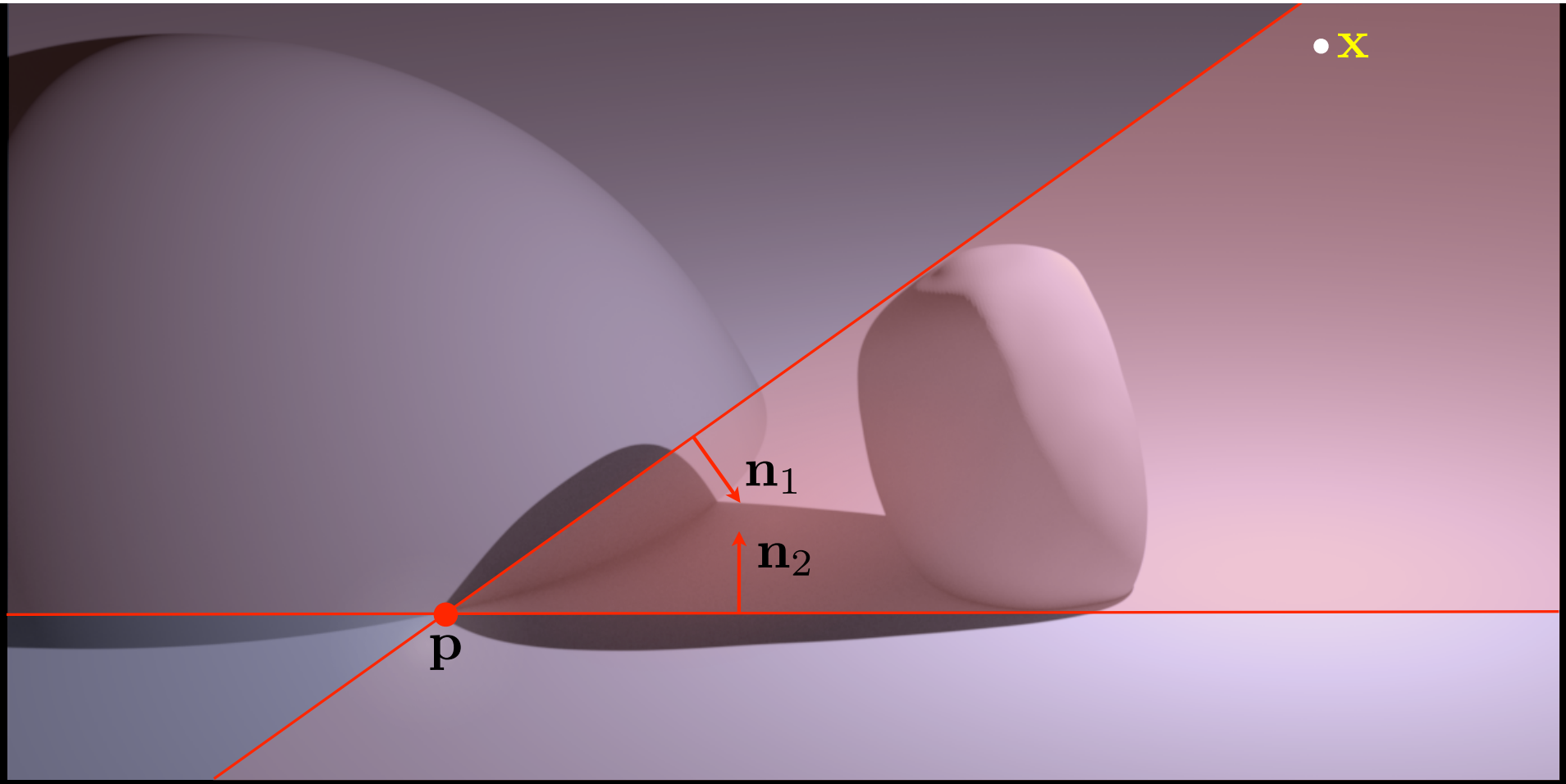


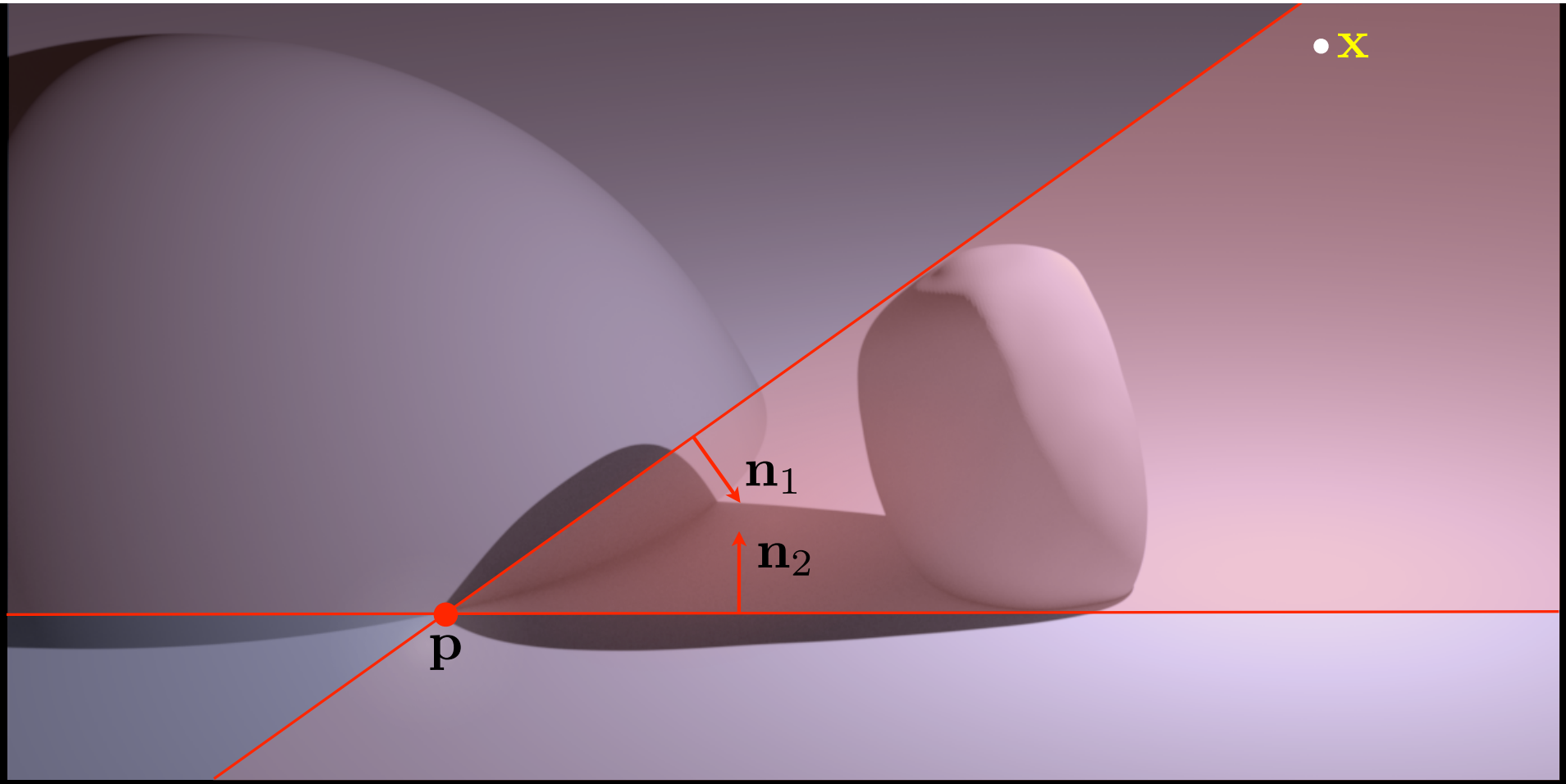



x
n
p

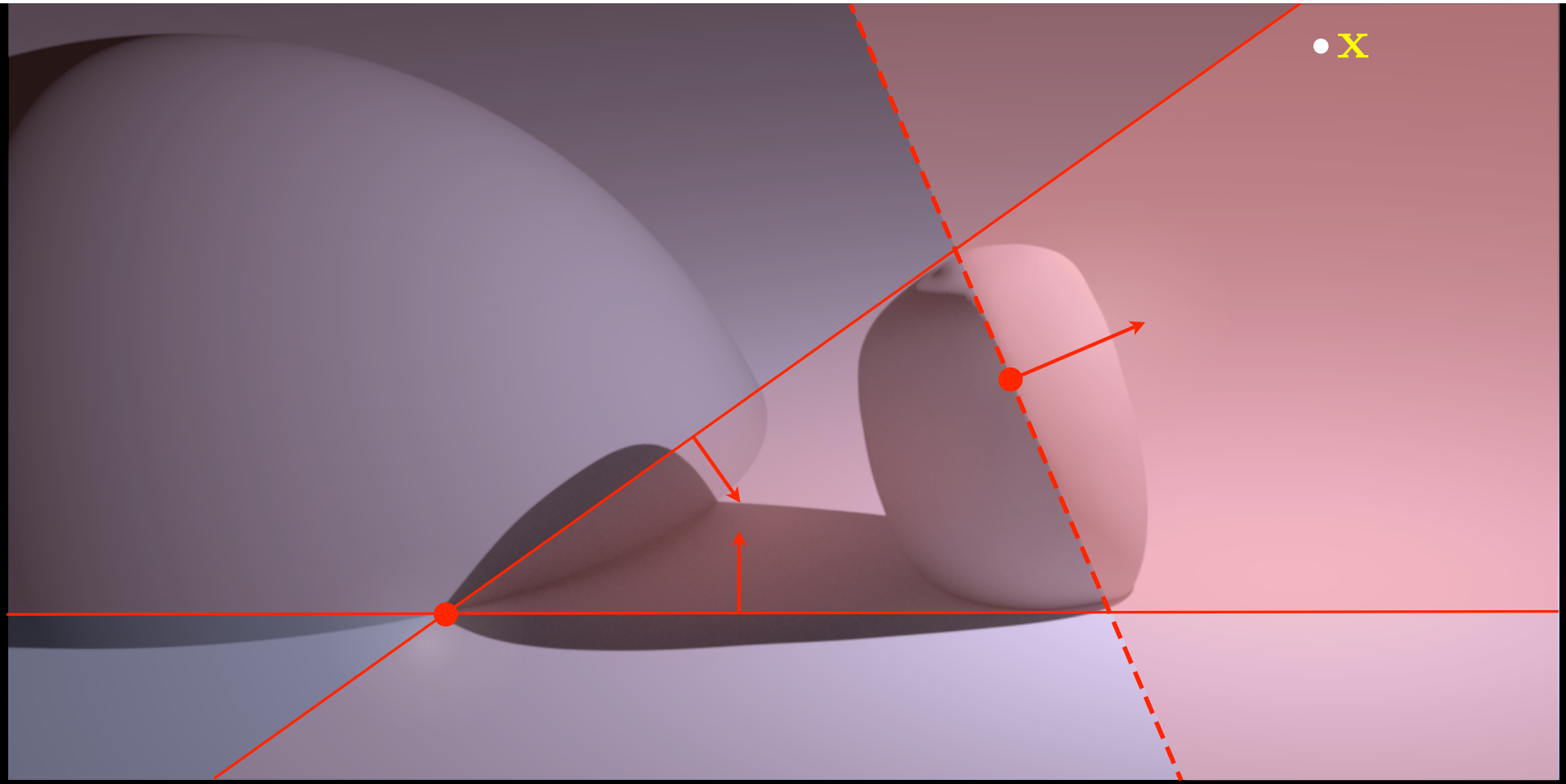


$$\mathbf{n} \cdot \mathbf{x} - \mathbf{n} \cdot \mathbf{p} \geq 0$$

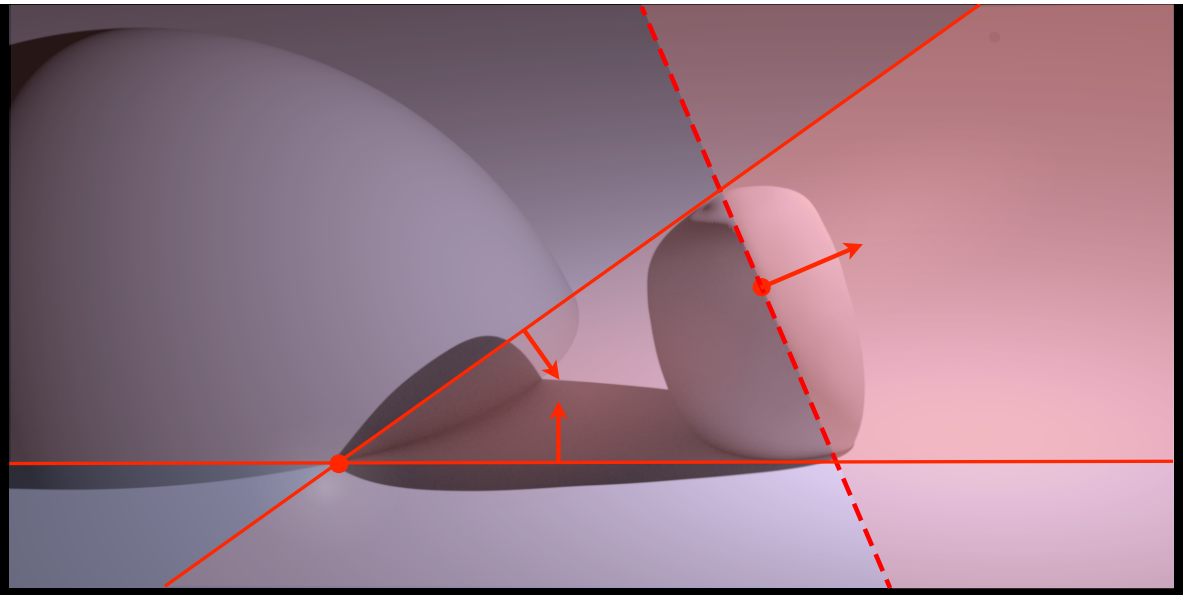

x
$\mathbf{n}_1$
$\mathbf{n}_2$
p



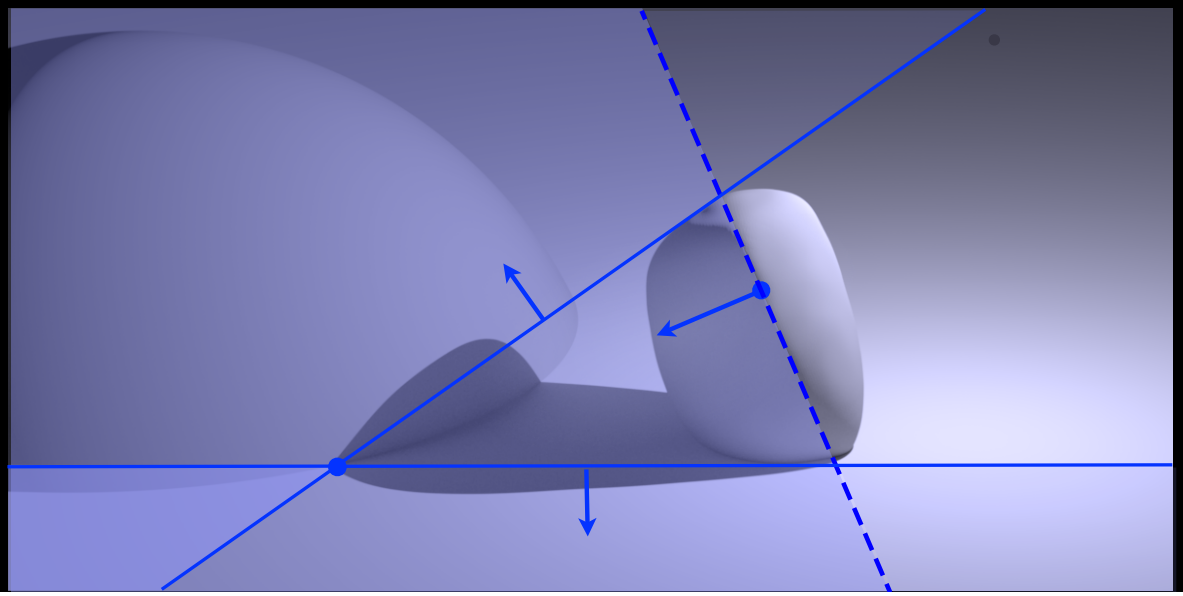
$$\begin{bmatrix} \mathbf{n}_1 \\ \mathbf{n}_2 \end{bmatrix} \mathbf{x} - \begin{bmatrix} \mathbf{n}_1 \cdot \mathbf{p} \\ \mathbf{n}_2 \cdot \mathbf{p} \end{bmatrix} \succeq \mathbf{0}$$



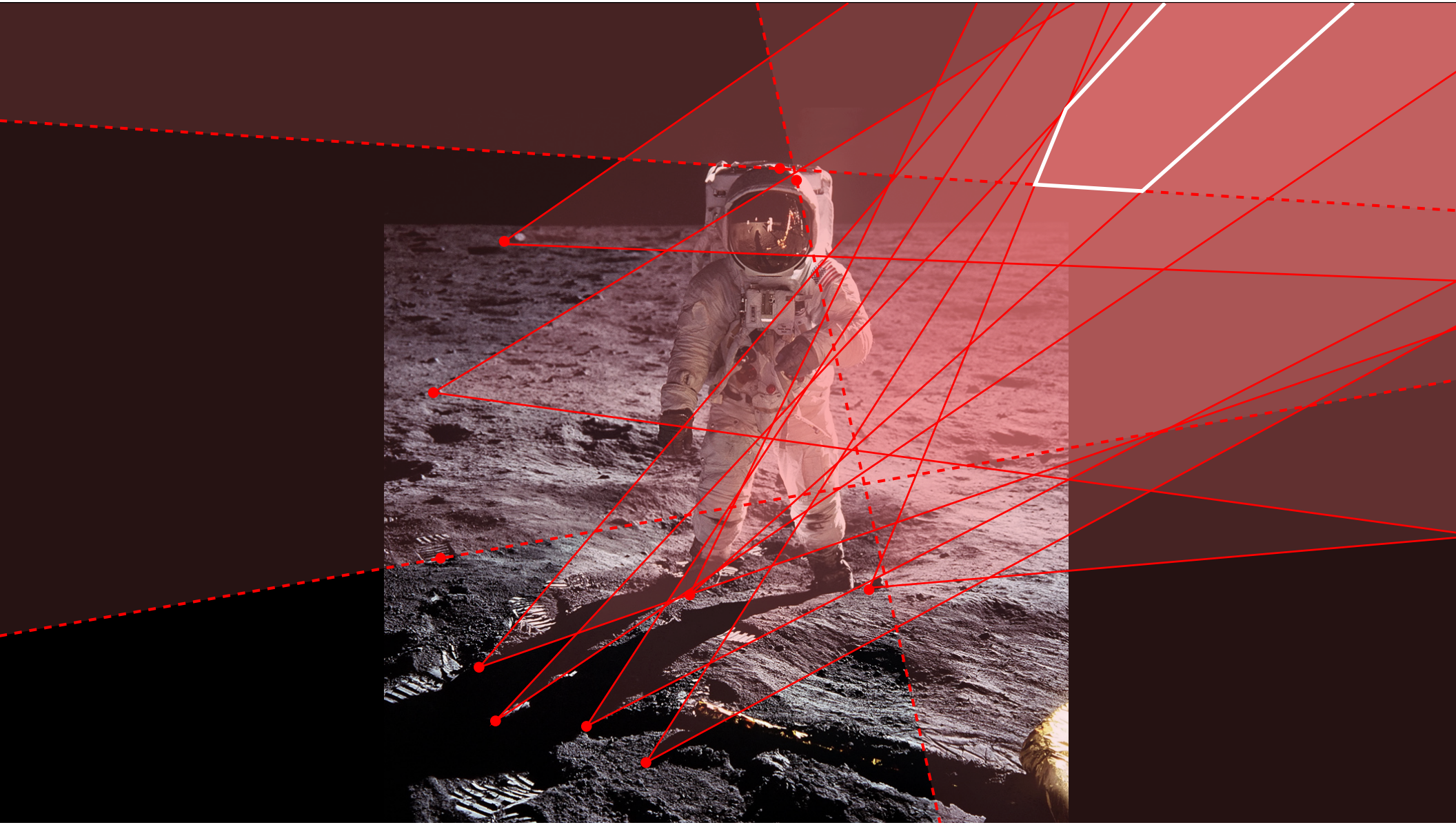
$$\mathbf{N}\mathbf{x} - \mathbf{P} \succeq \mathbf{0}$$



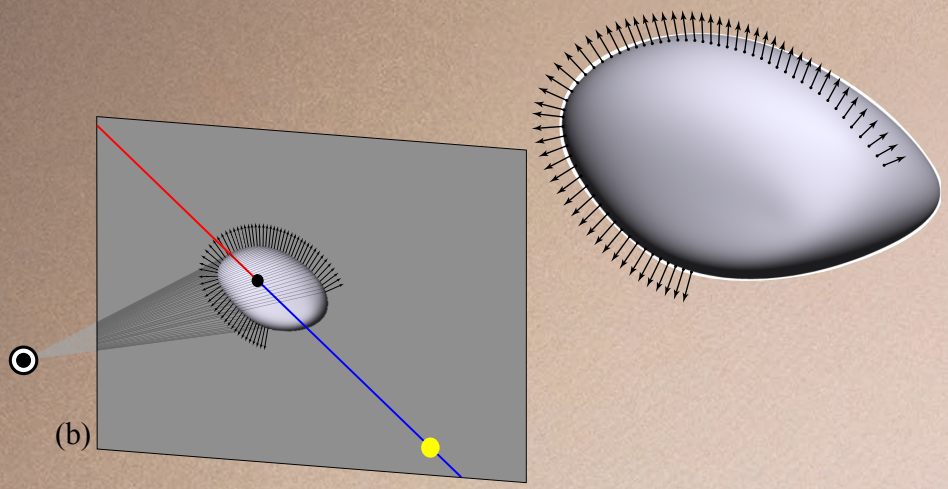
$$\mathbf{Nx} - \mathbf{P} \succeq \mathbf{0}$$

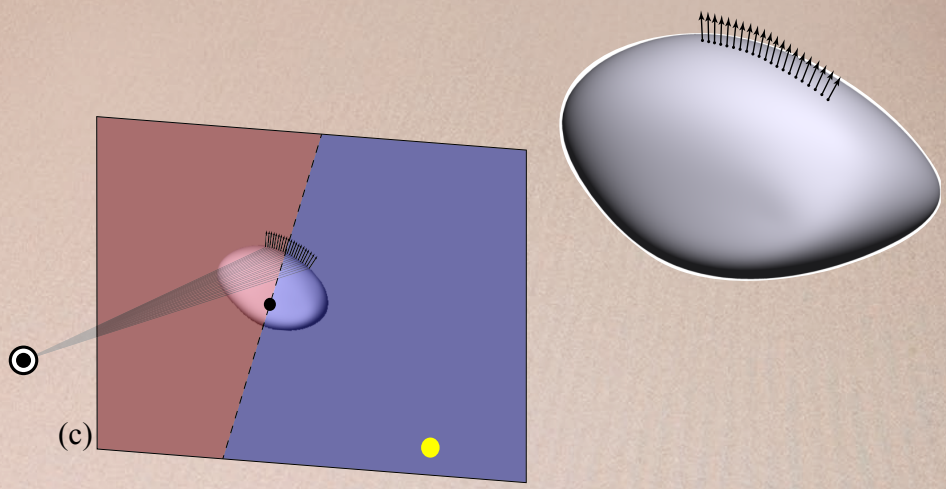


$$-\mathbf{Nx} - \mathbf{P} \succeq \mathbf{0}$$



Shading Constraints





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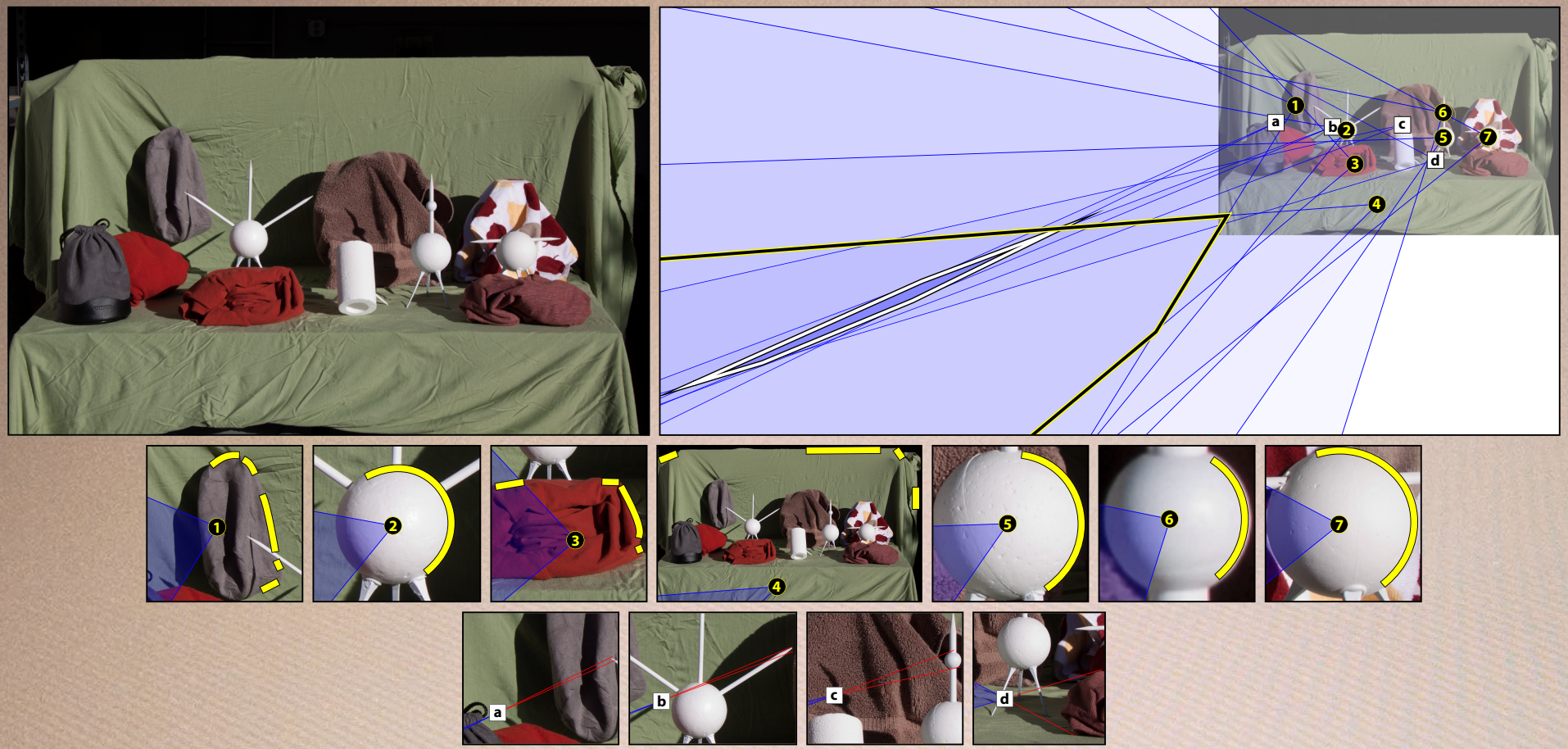

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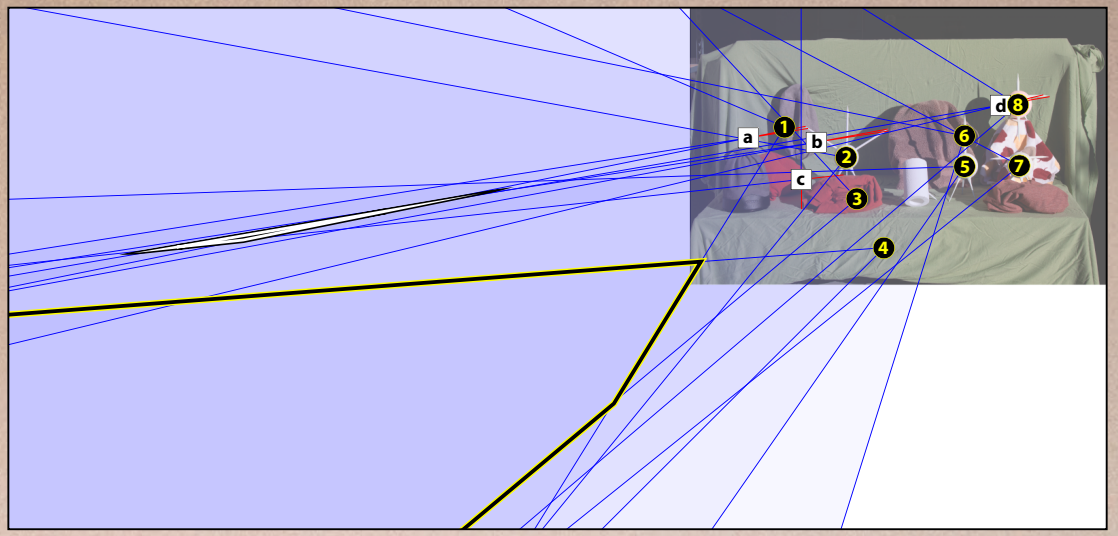
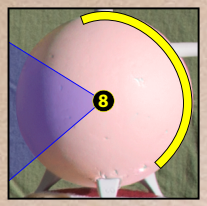
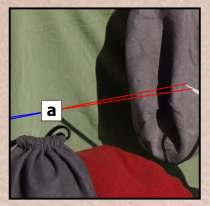
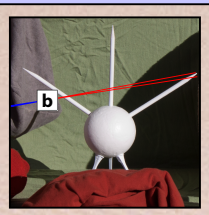
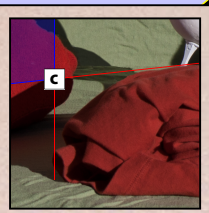
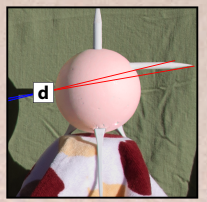




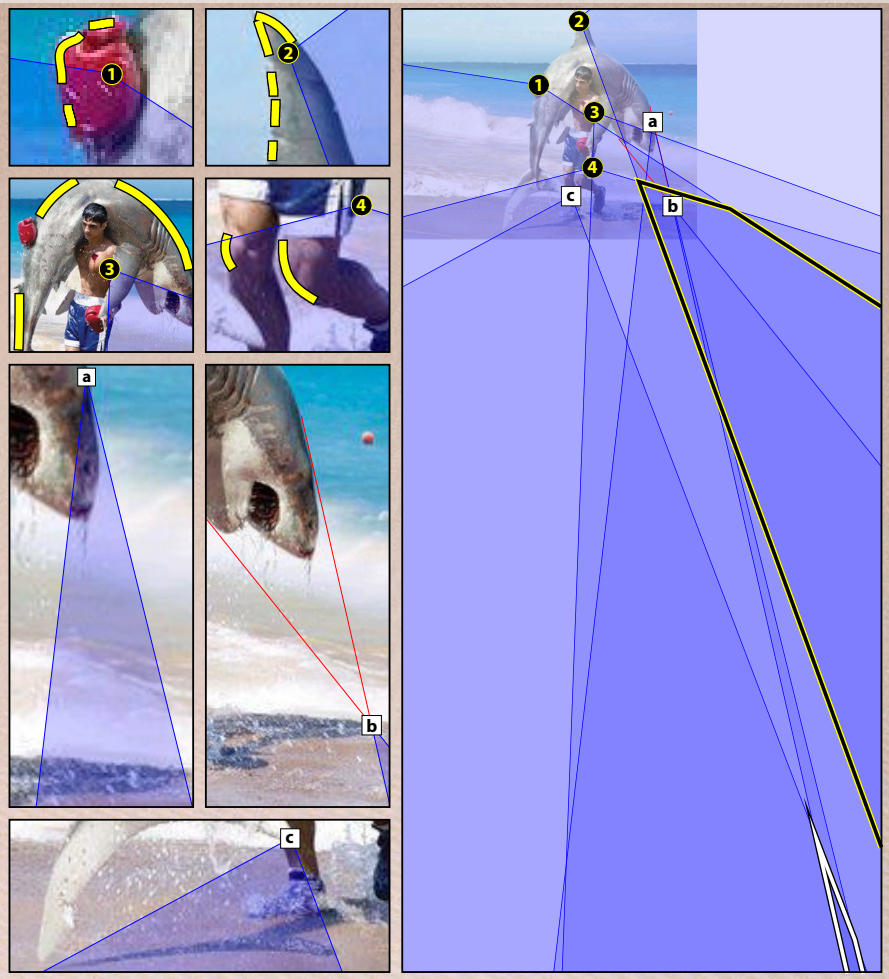








Shading Constraints



Motion in Video

Parabolic Motion in World (Still Camera)

$$\mathbf{p}_\tau = \mathbf{p}_0 + \Delta t\,\tau\,\mathbf{v}_0 + \frac{1}{2}(\Delta t\,\tau)^2\mathbf{g}$$

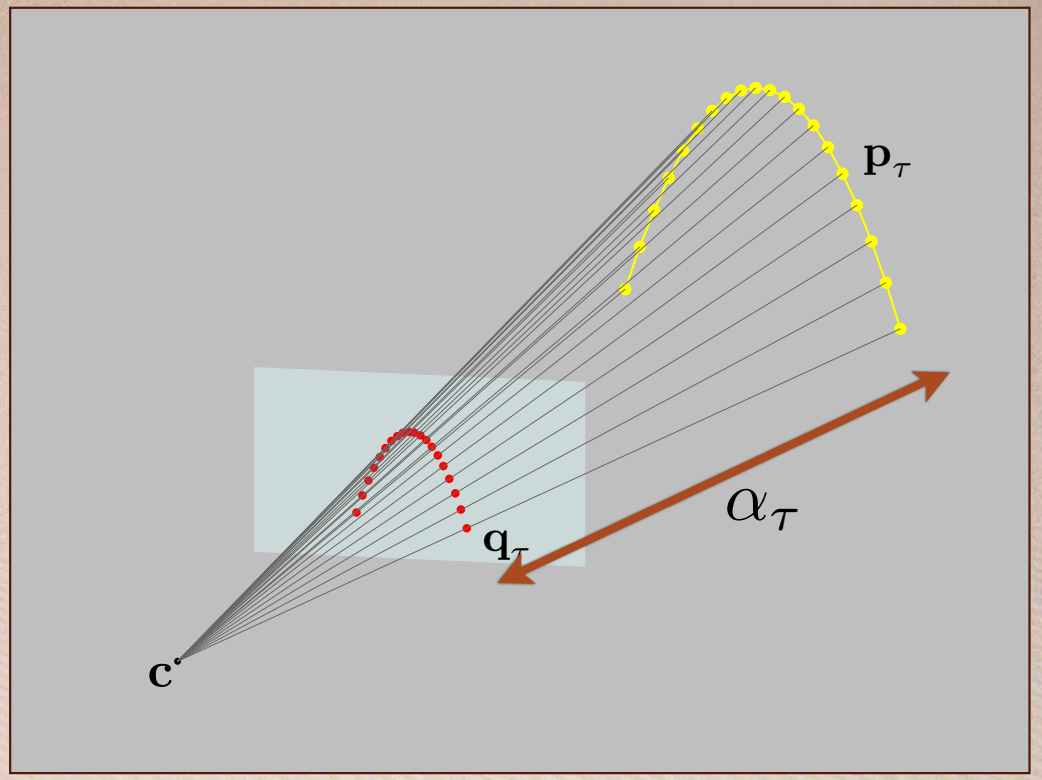
$$\mathbf{p}_\tau = \mathbf{c} + \alpha_\tau(\mathbf{q}_\tau - \mathbf{c})$$

$\tau \in 1..n$

Solve for: α_τ

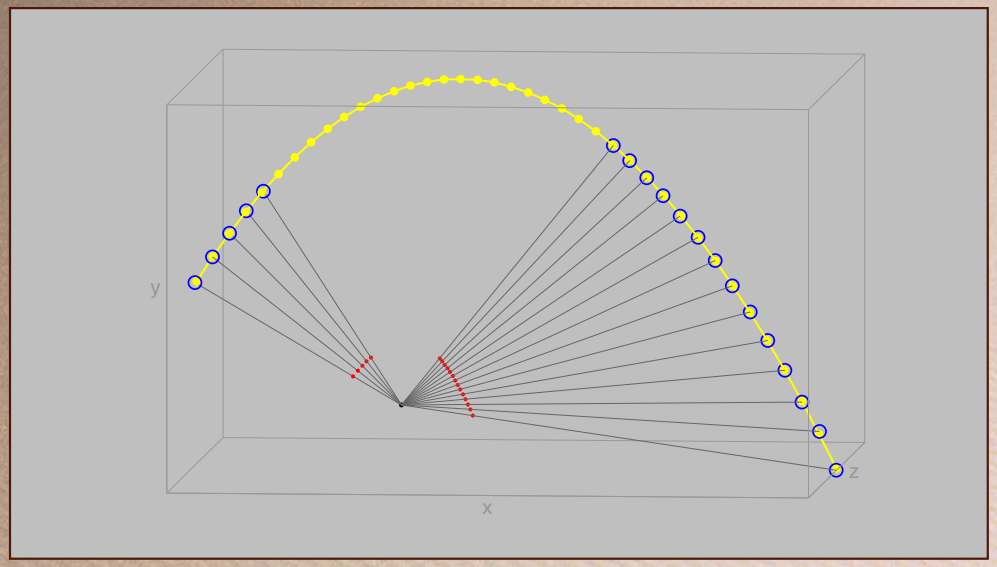
$\mathbf{v}_0$

$\mathbf{g}$

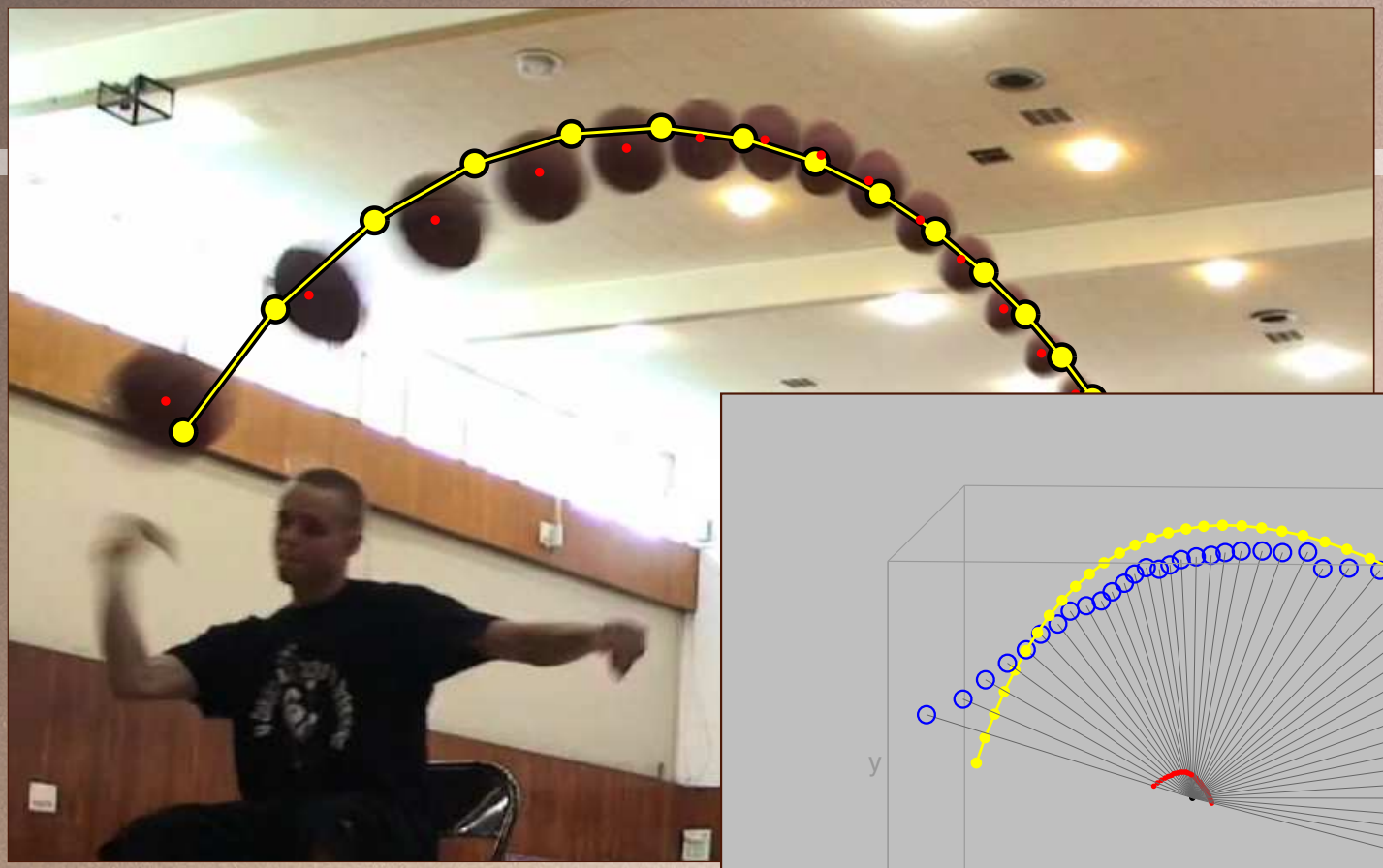


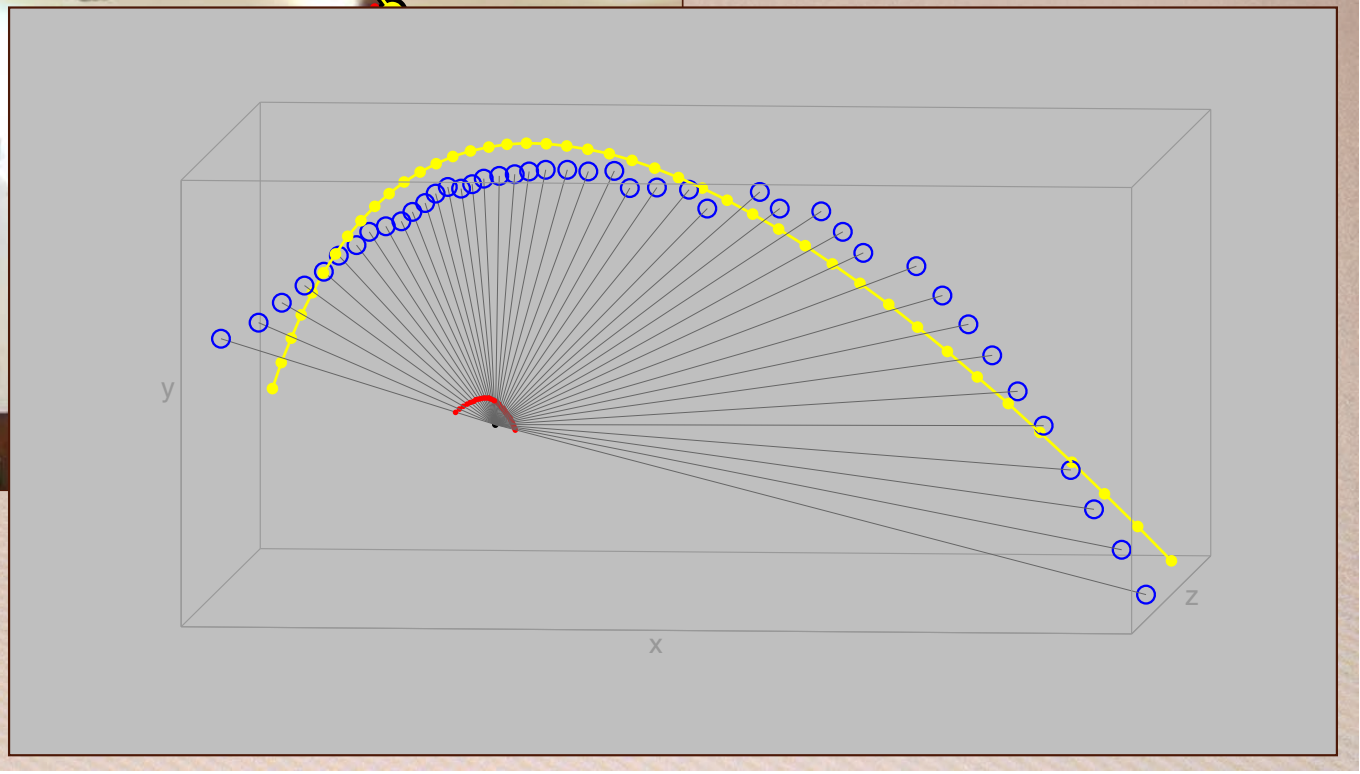
Matching observed motion



http:// www.youtube.com/ watch?v=WbaH52JI3So




y
x
z

Parabolic Motion in World (Moving Camera)

$$\mathbf{p}_\tau = \mathbf{p}_0 + \Delta t\,\tau\,\mathbf{v}_0 + \frac{1}{2}(\Delta t\,\tau)^2\mathbf{g}$$

$$\mathbf{p}_\tau = \mathbf{c} + \alpha_\tau(\mathbf{q}_\tau - \mathbf{c})$$

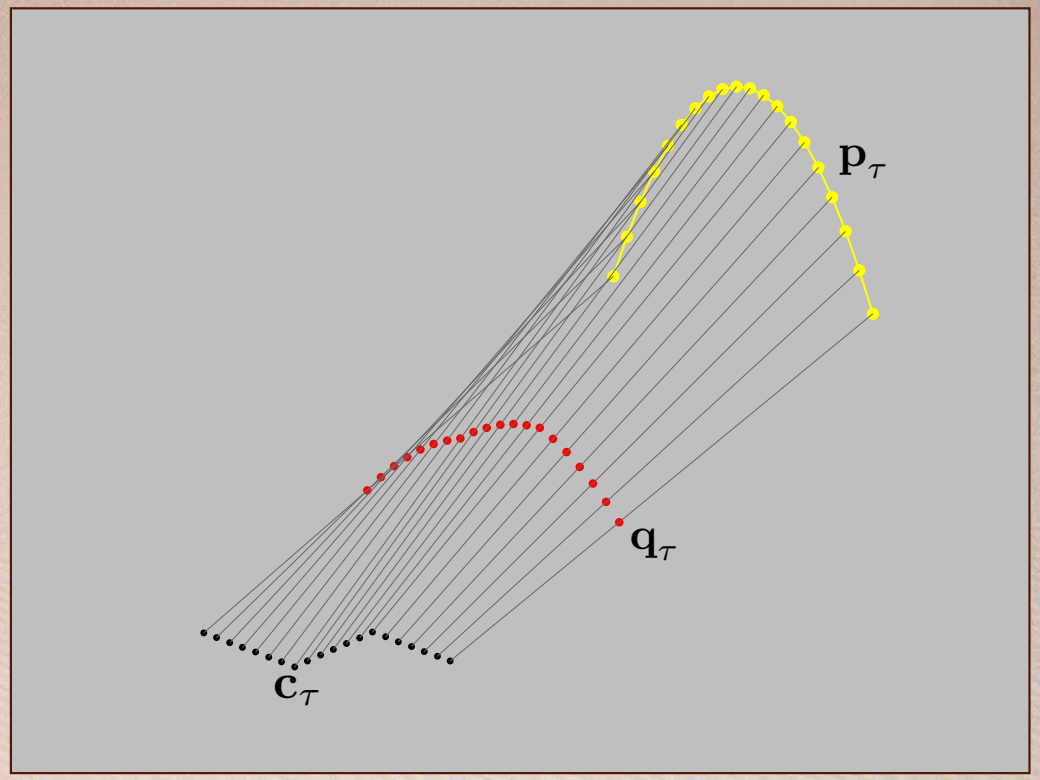
$\tau \in 1..n$

Solve for: α_τ

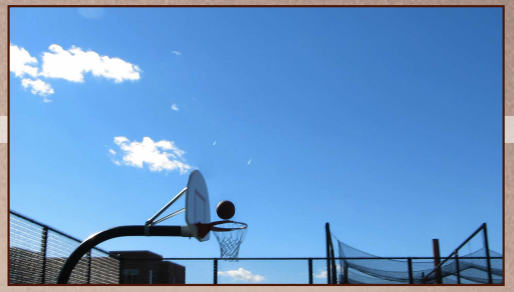
$\mathbf{v}_0$

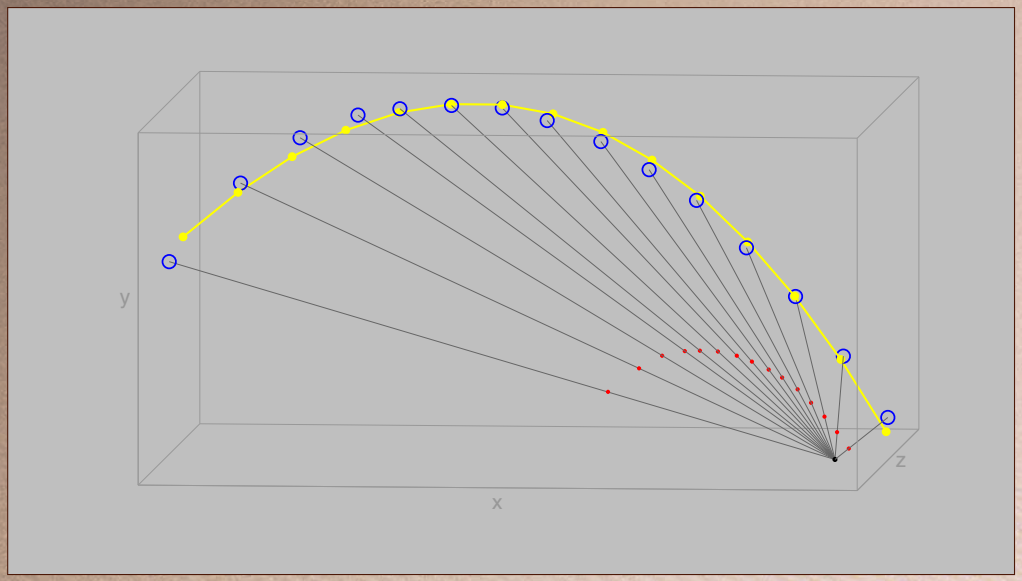
$\mathbf{g}$

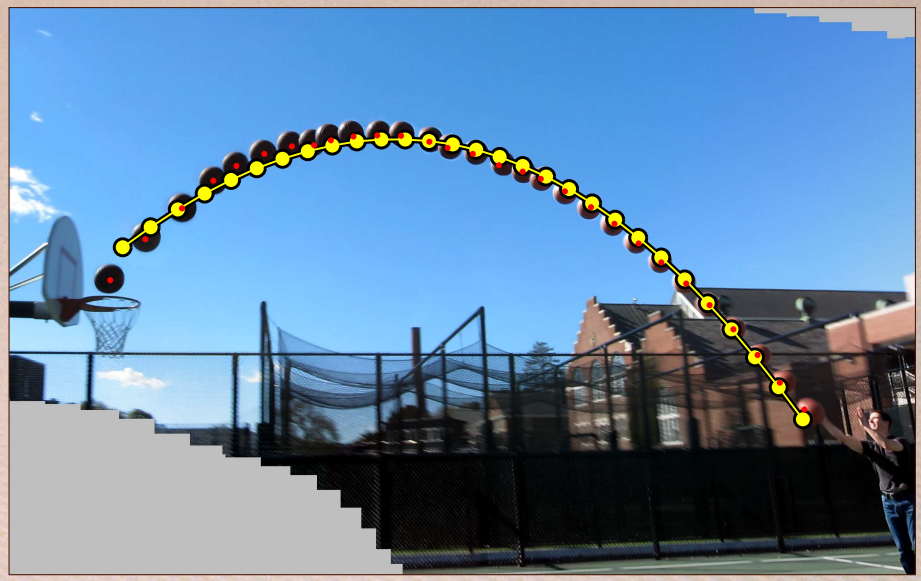
Track camera motion





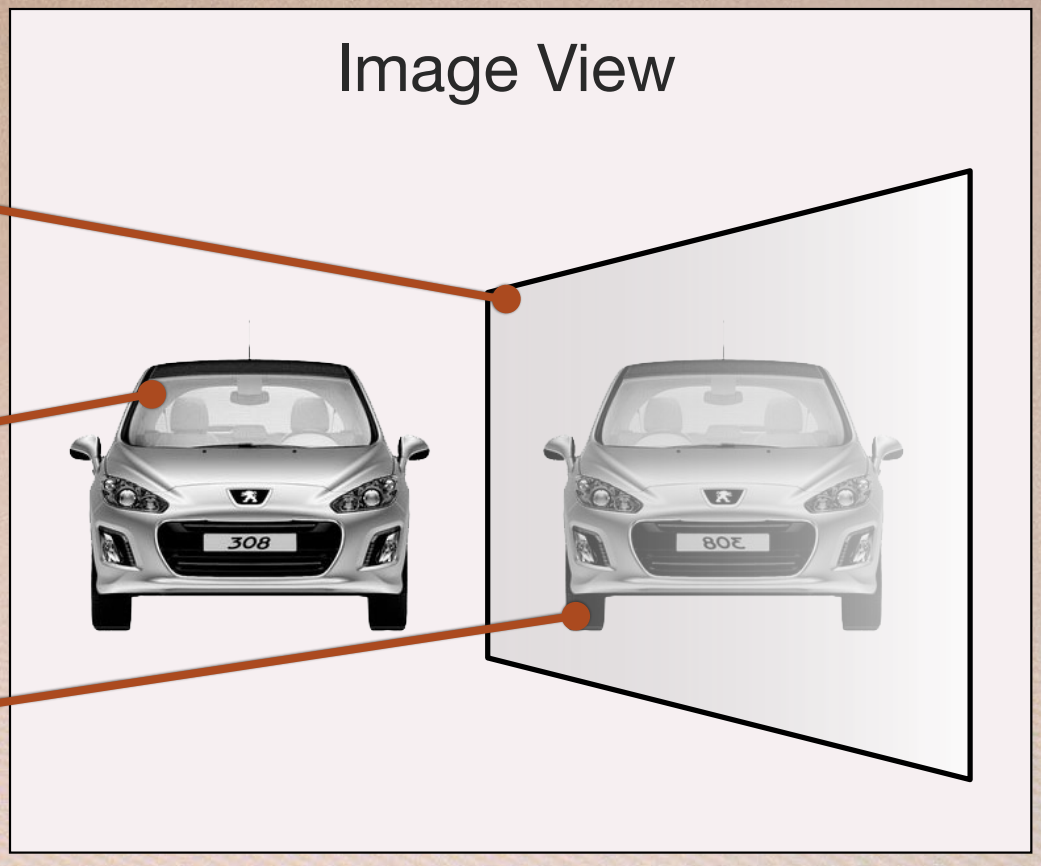




y
x
z



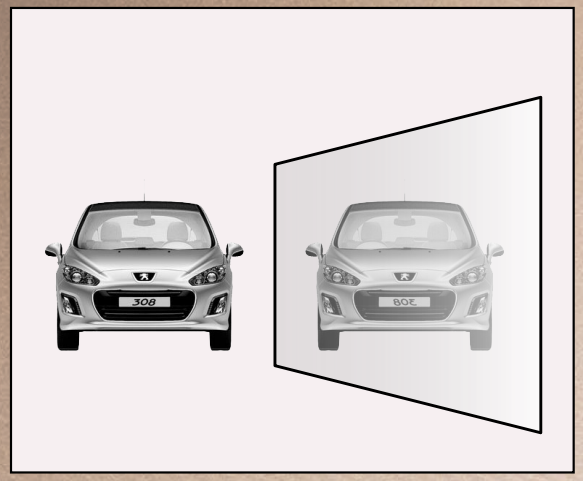
Basic Mirror Geometry

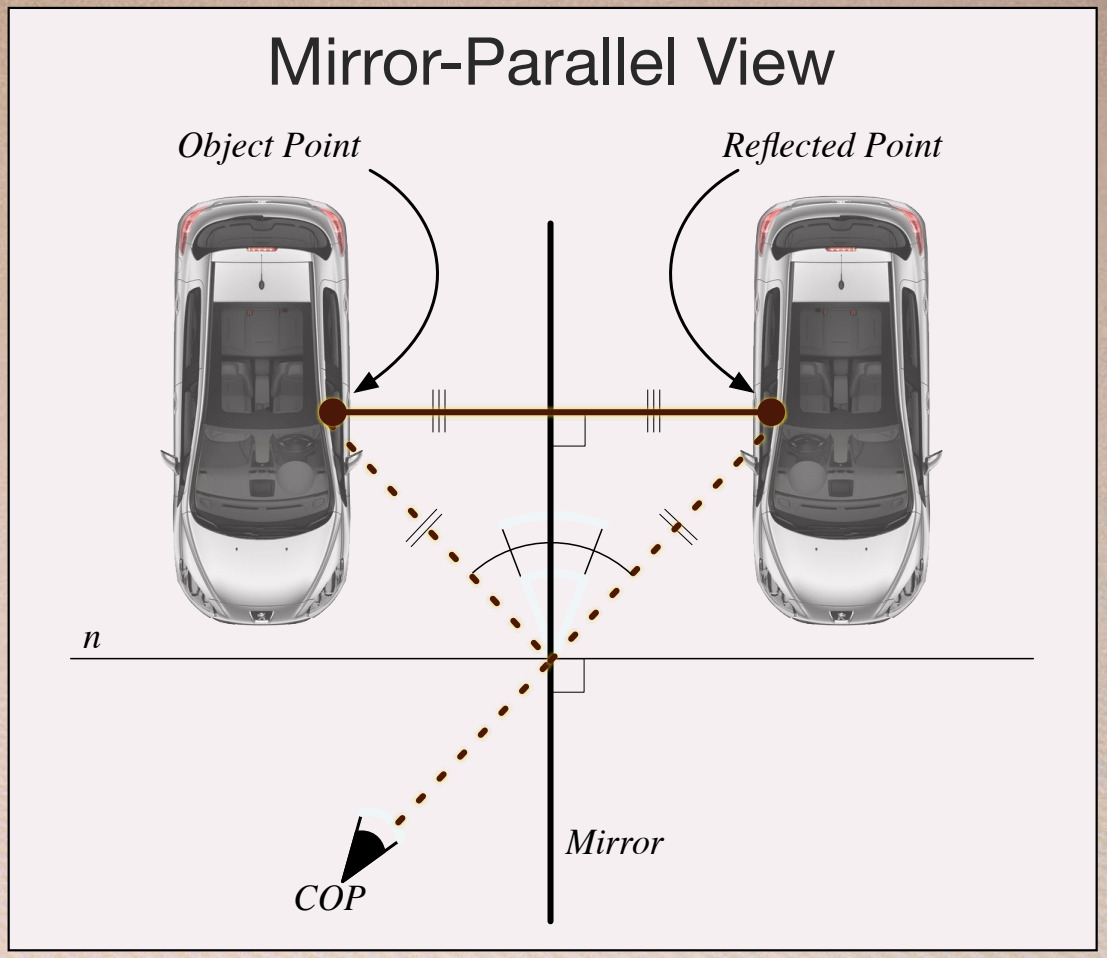
Linear perspective image



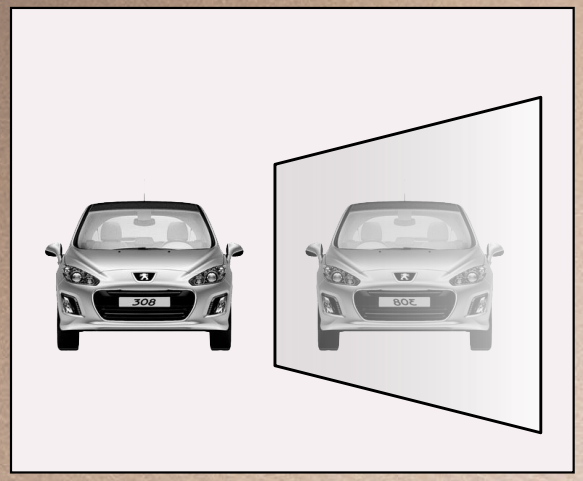
Basic Mirror Geometry

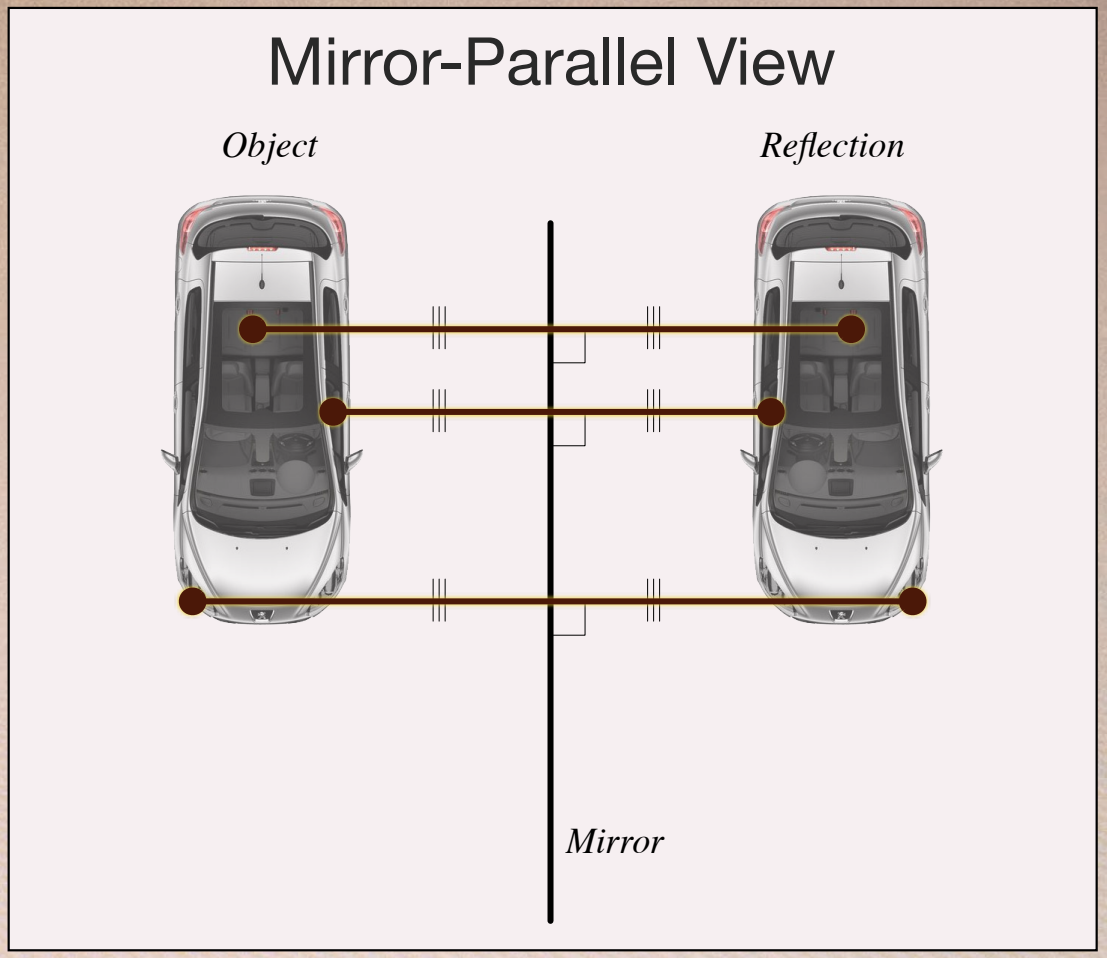
Basic Mirror Geometry





Basic Mirror Geometry



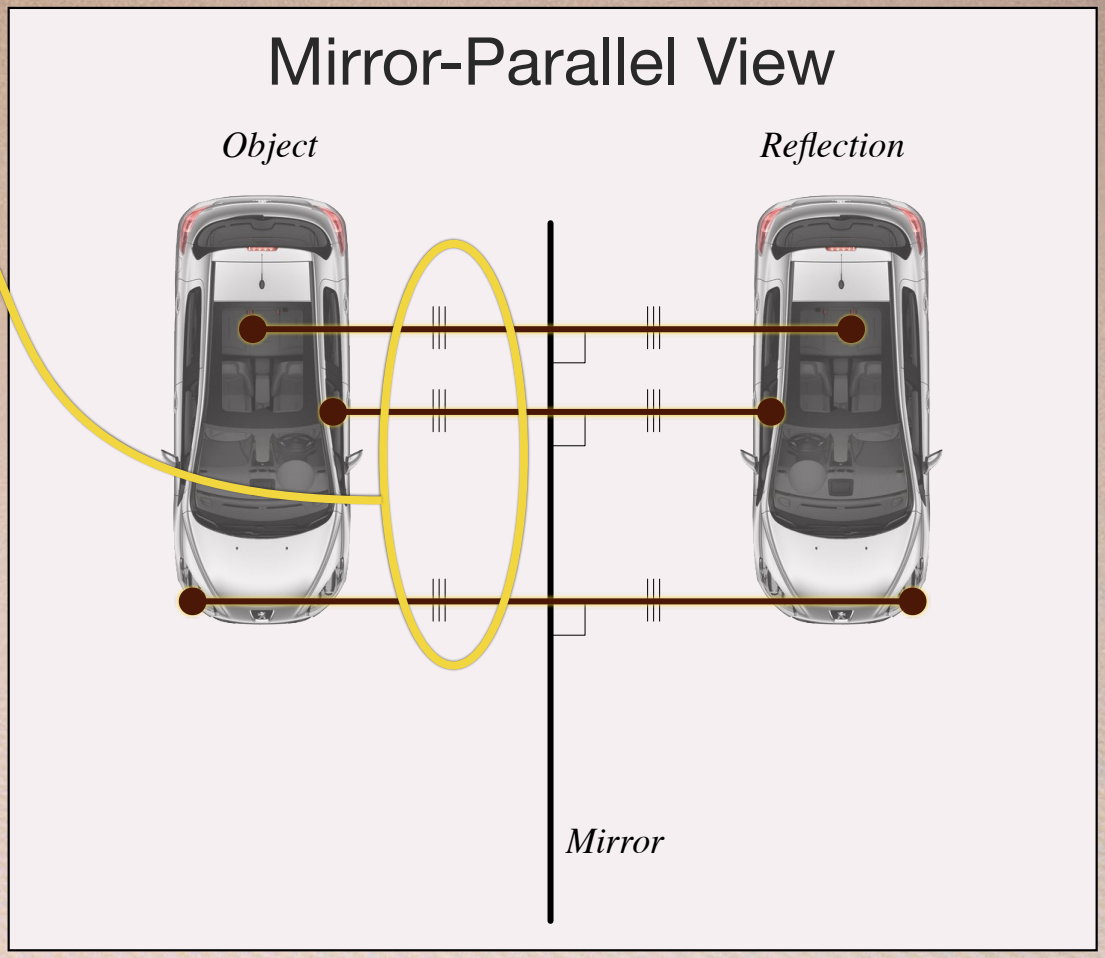


Basic Mirror Geometry

Bundle of parallel lines

In original image they must converge to a common vanishing point.

(Possibly at infinity)

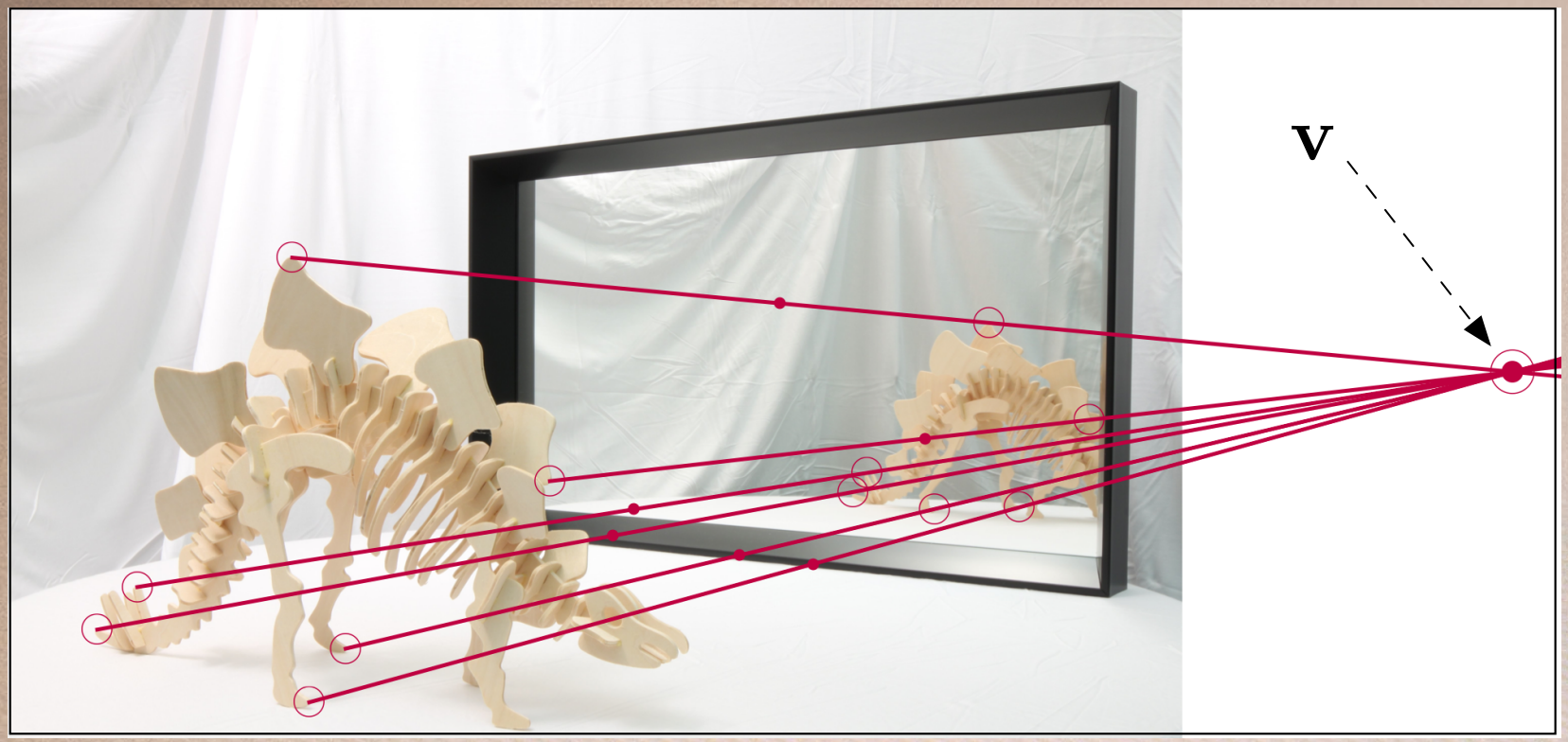


Reflection Vanishing Point

Real Photograph

Reflection Vanishing Point

Real Photograph

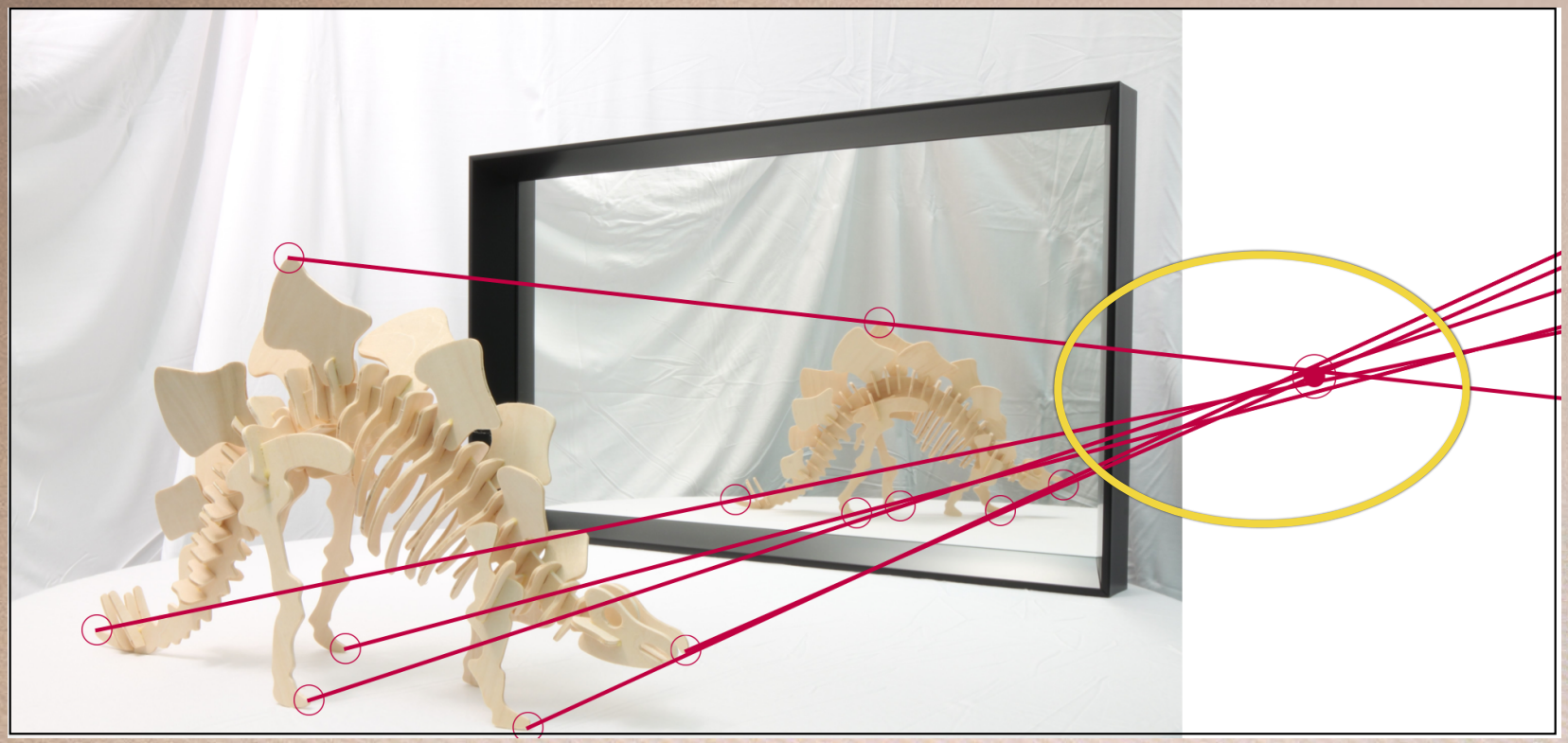


Reflection Vanishing Point

Altered Photograph

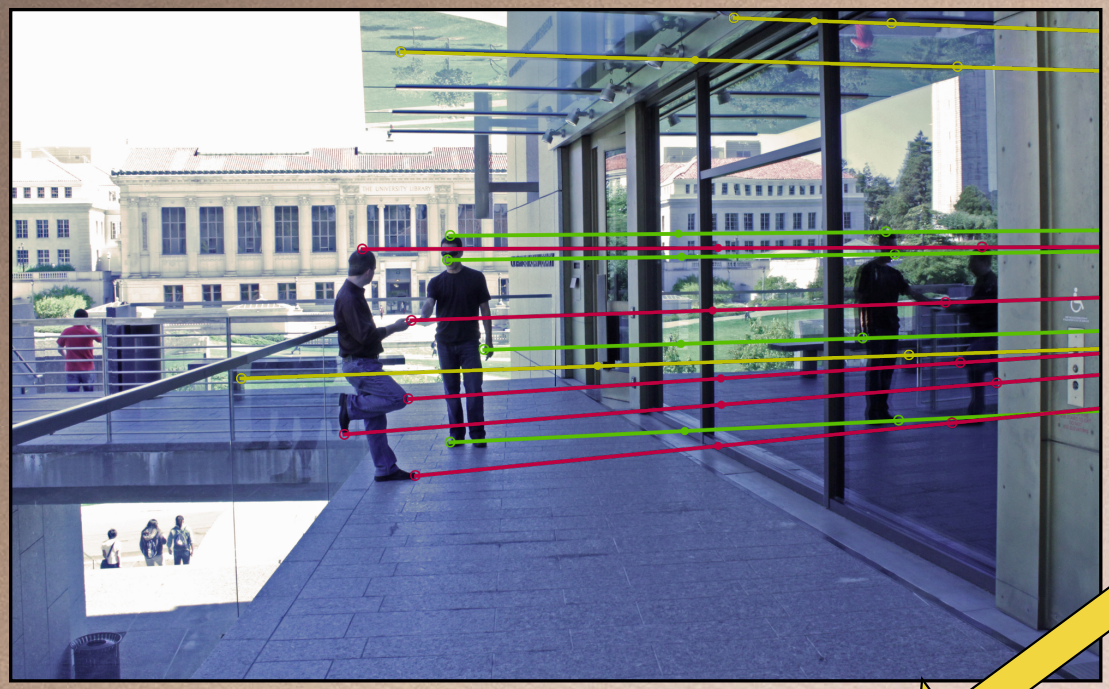
Reflection Vanishing Point

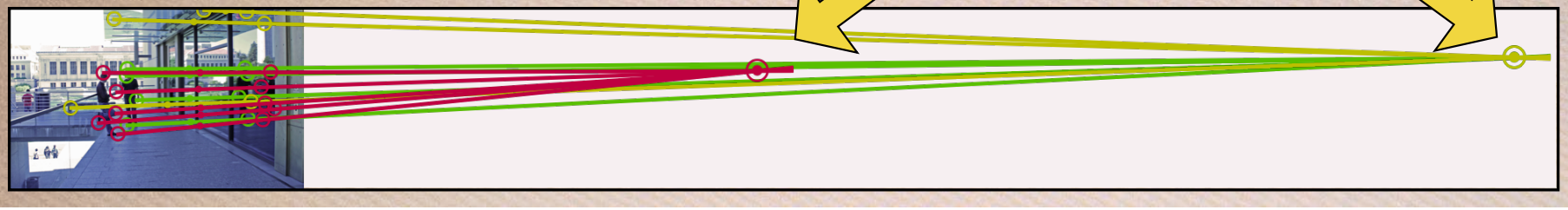
Altered Photograph



Examples

Examples

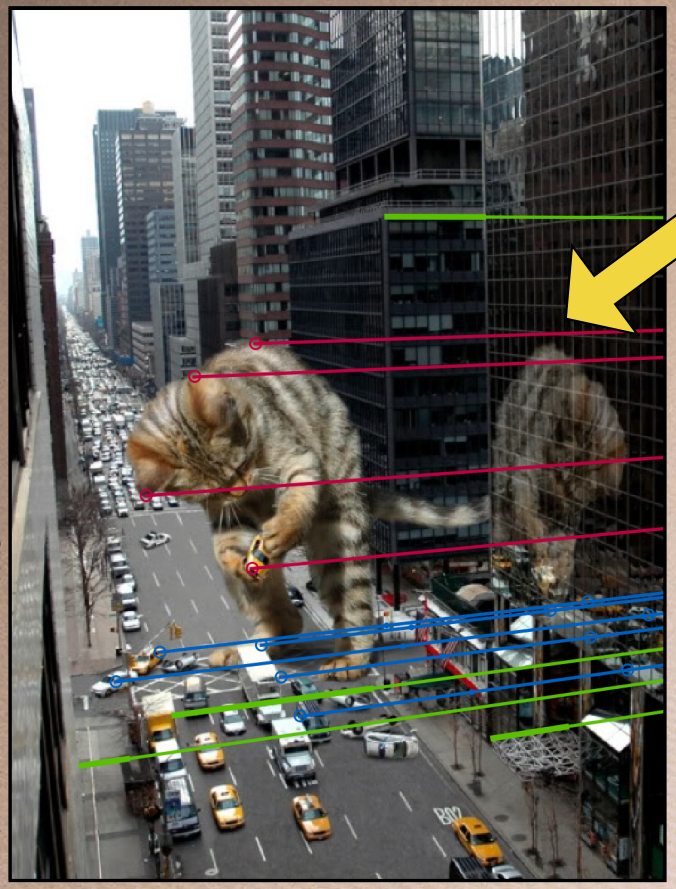


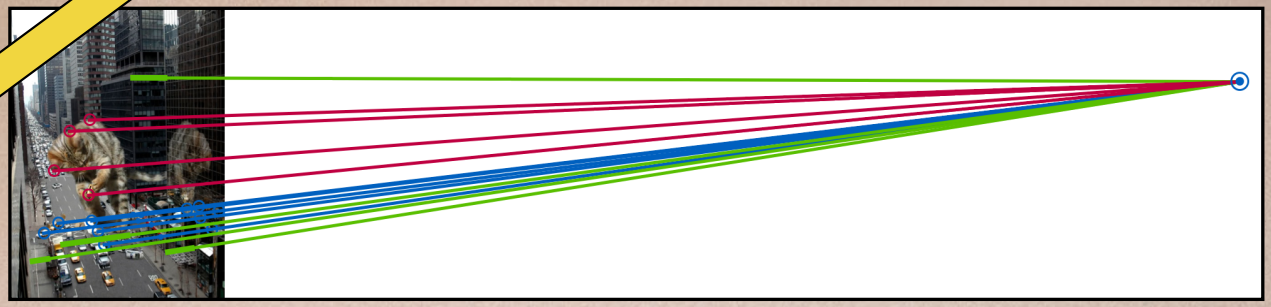


Examples

Composite photo World News, copyright 2006.

Examples

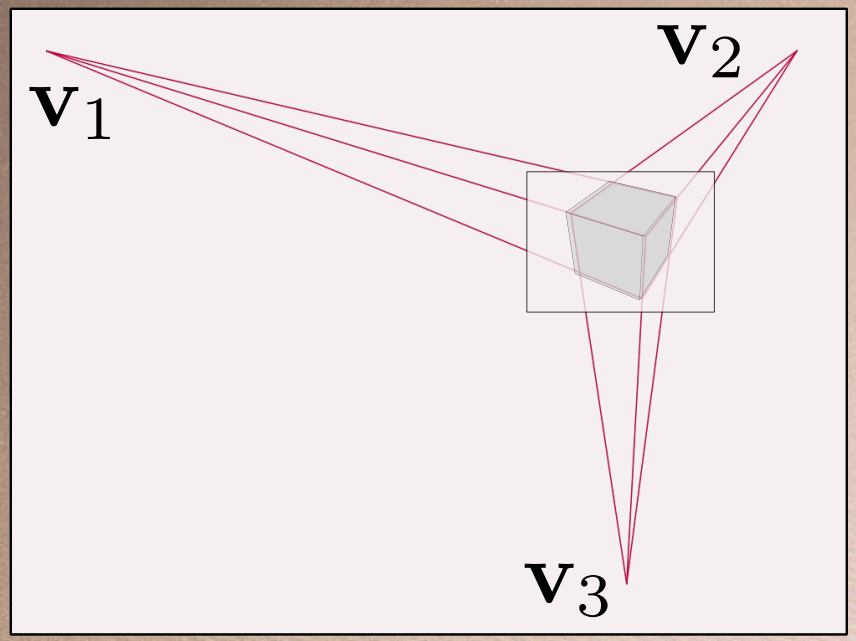




Composite photo World News, copyright 2006.

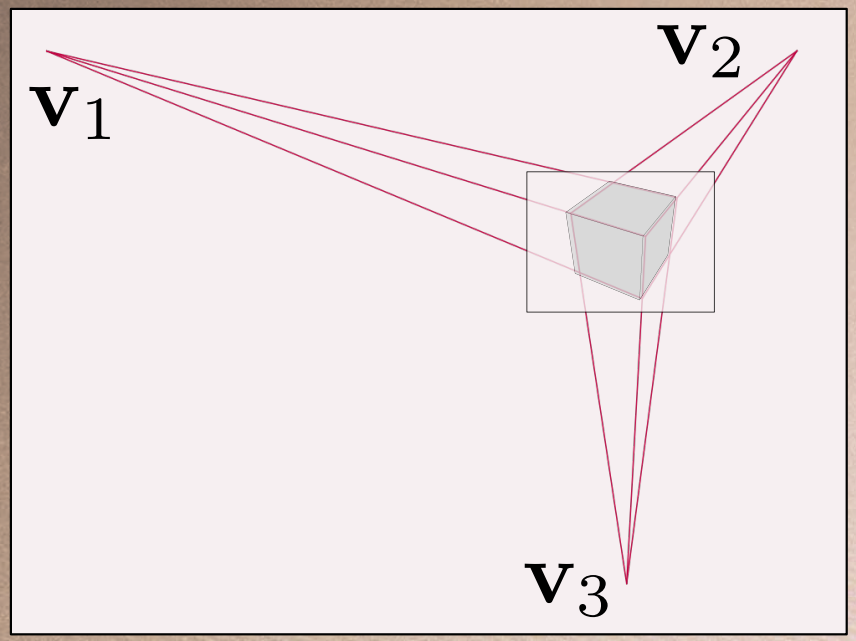
Center of Projection

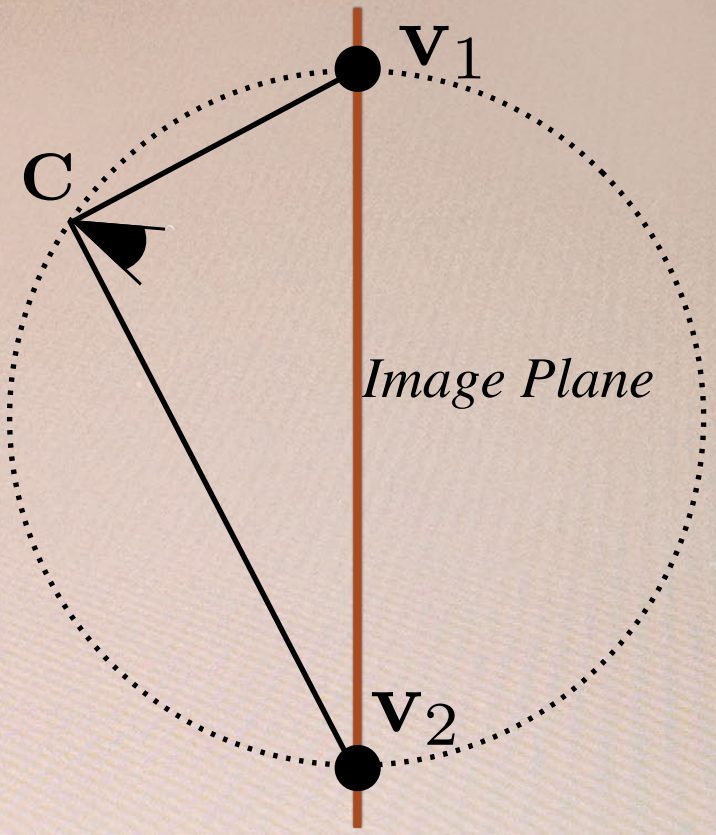
- COP determined by 3 orthogonal vanishing points



Center of Projection

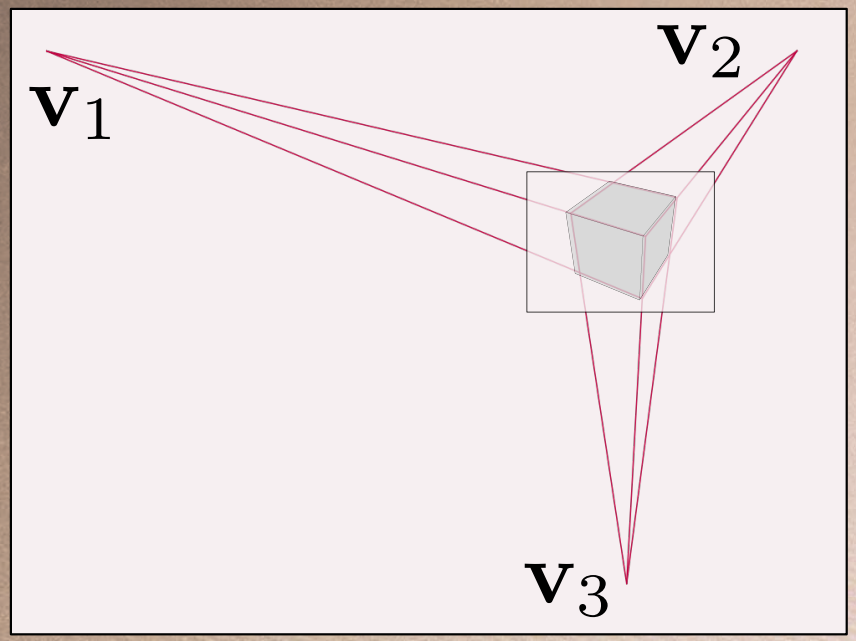
- COP determined by 3 orthogonal vanishing points

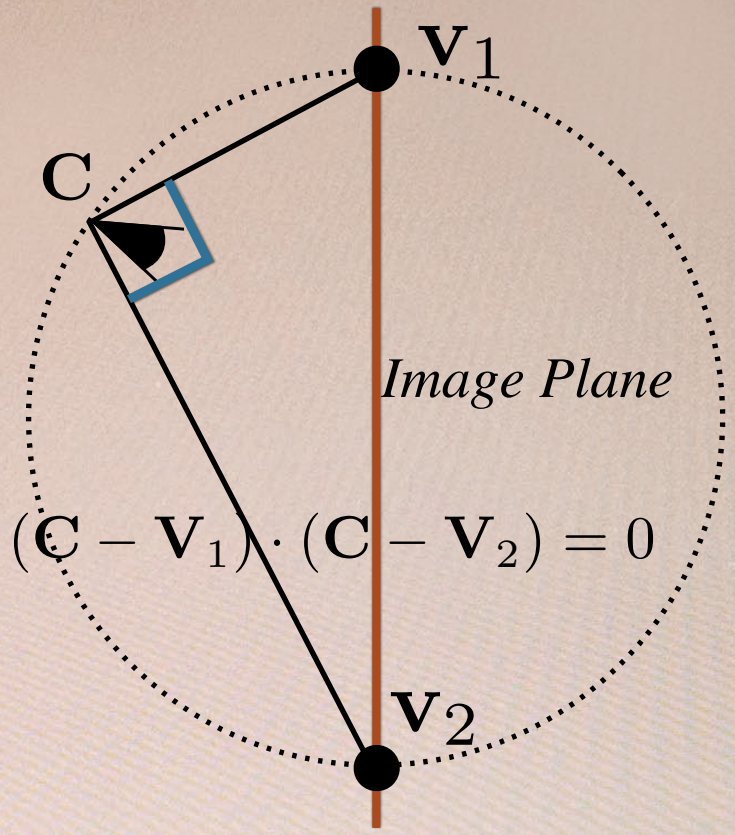




Center of Projection

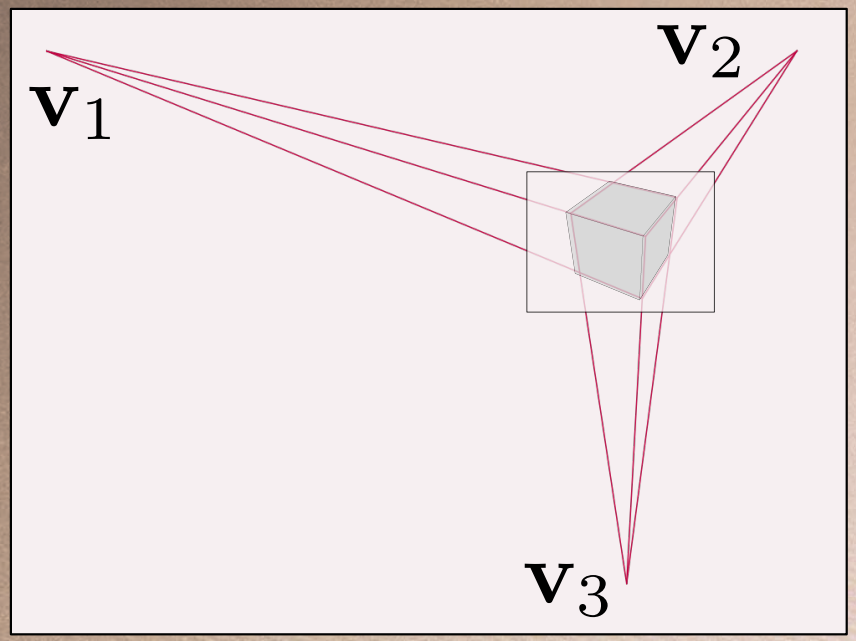
- COP determined by 3 orthogonal vanishing points

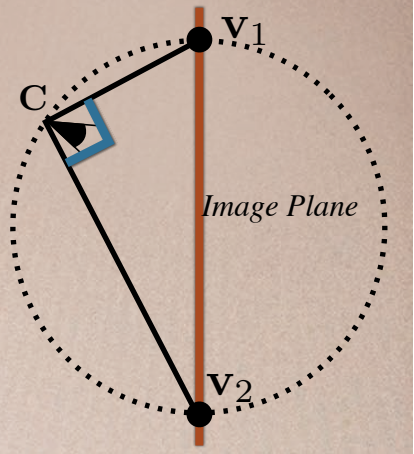




Center of Projection

- COP determined by 3 orthogonal vanishing points

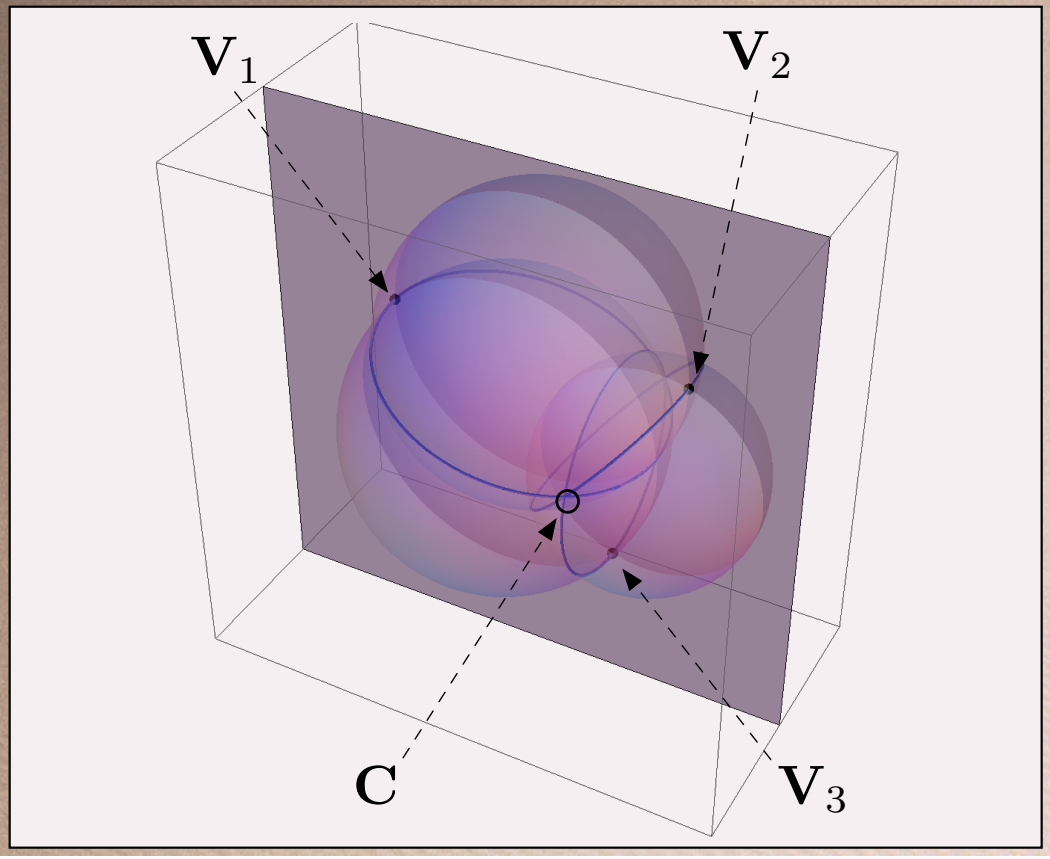


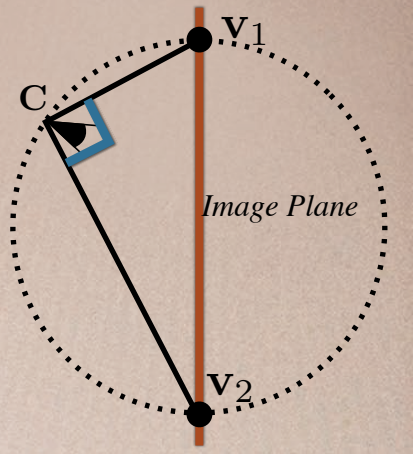


$$(\mathbf{C} - \mathbf{V}_1) \cdot (\mathbf{C} - \mathbf{V}_2) = 0$$
$$(\mathbf{C} - \mathbf{V}_2) \cdot (\mathbf{C} - \mathbf{V}_3) = 0$$
$$(\mathbf{C} - \mathbf{V}_3) \cdot (\mathbf{C} - \mathbf{V}_1) = 0$$

Center of Projection

- COP determined by 3 orthogonal vanishing points





$$(\mathbf{C} - \mathbf{V}_1) \cdot (\mathbf{C} - \mathbf{V}_2) = 0$$
$$(\mathbf{C} - \mathbf{V}_2) \cdot (\mathbf{C} - \mathbf{V}_3) = 0$$
$$(\mathbf{C} - \mathbf{V}_3) \cdot (\mathbf{C} - \mathbf{V}_1) = 0$$

Center of Projection

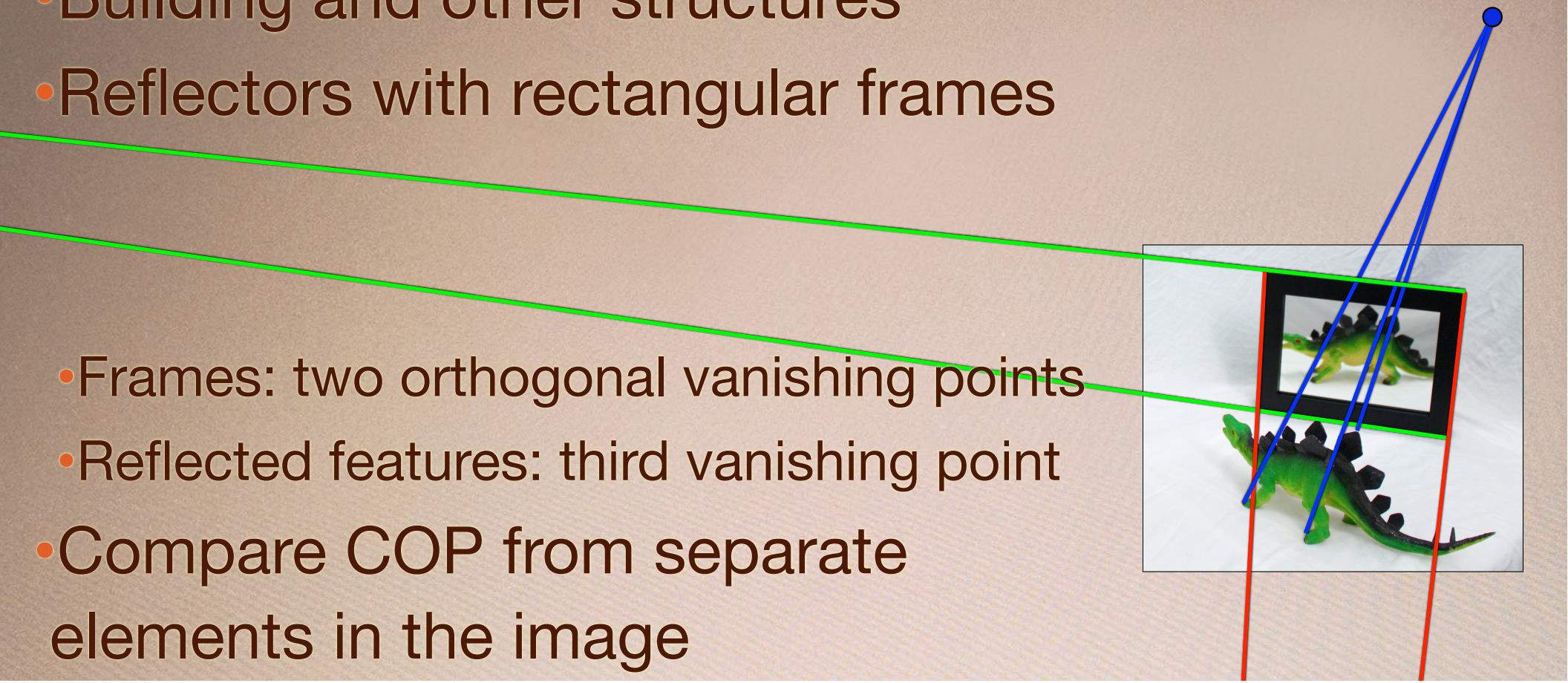
- COP determined by 3 orthogonal vanishing points
- System of quadratic equations

$$(\mathbf{C} - \mathbf{V}_1) \cdot (\mathbf{C} - \mathbf{V}_2) = 0$$
$$(\mathbf{C} - \mathbf{V}_2) \cdot (\mathbf{C} - \mathbf{V}_3) = 0$$
$$(\mathbf{C} - \mathbf{V}_3) \cdot (\mathbf{C} - \mathbf{V}_1) = 0$$

- Easy to solve by change of variables

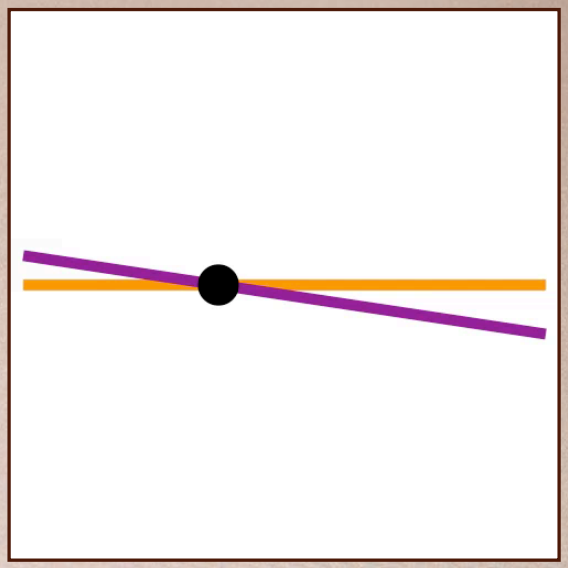
Center of Projection

- Building and other structures
- Reflectors with rectangular frames
  - Frames: two orthogonal vanishing points
  - Reflected features: third vanishing point
- Compare COP from separate elements in the image



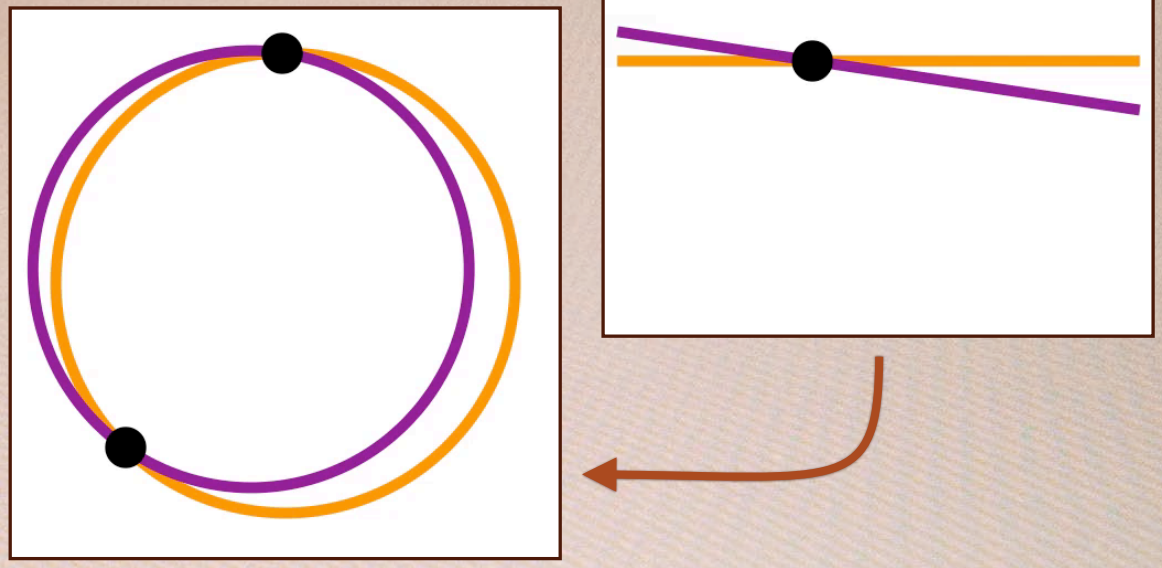
Center of Projection

- Computation is unstable
  - Step 1: intersect [nearly parallel] lines
  - Step 2: intersect spheres



Center of Projection

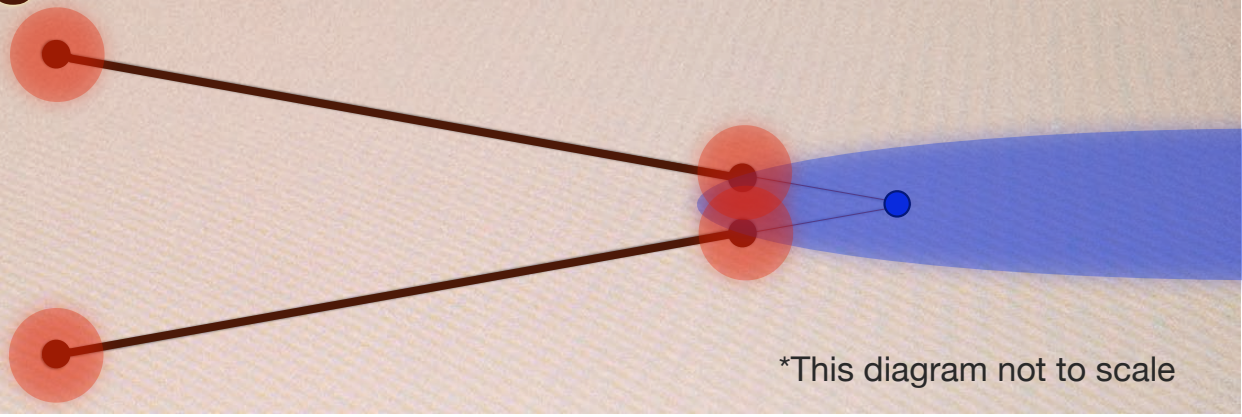
- Computation is unstable
  - Step 1: intersect [nearly parallel] lines
  - Step 2: intersect spheres
- "Instability squared"



Center of Projection

- Error sources:
  - Image resolution
  - User pointing accuracy
  - Features from different perspectives
- COP calculation magnifies error
  - Structure in instability

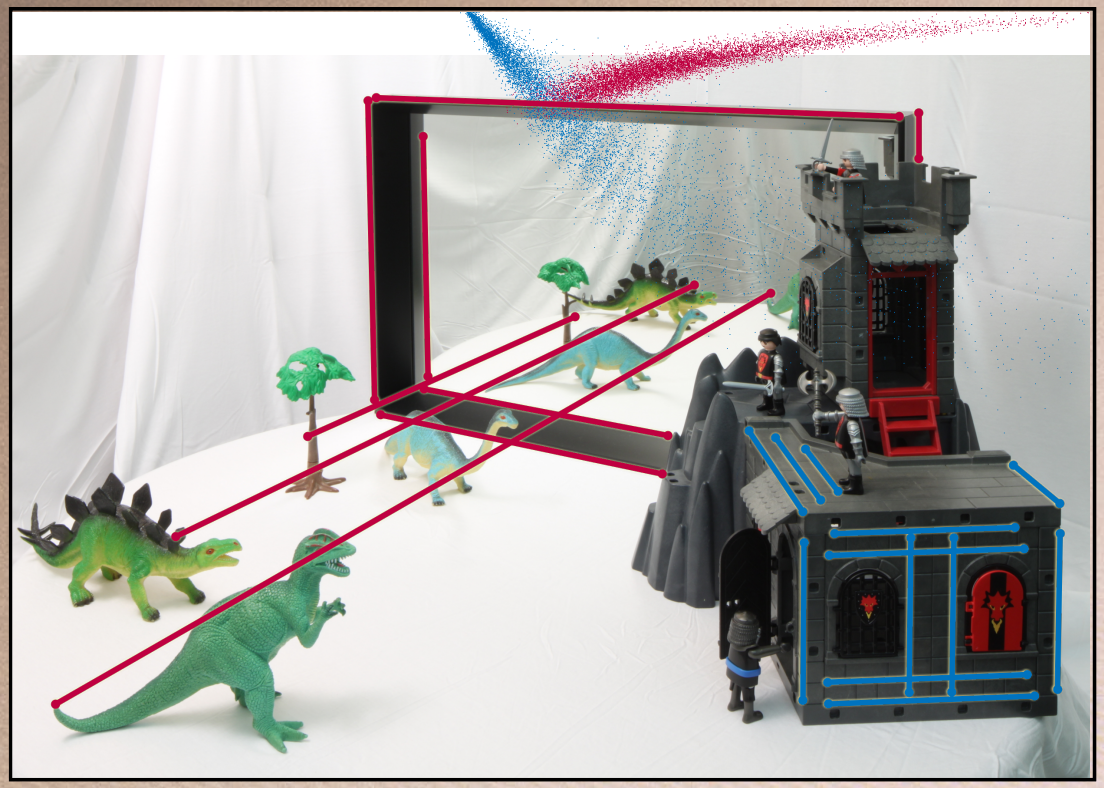
Specify regions, not points

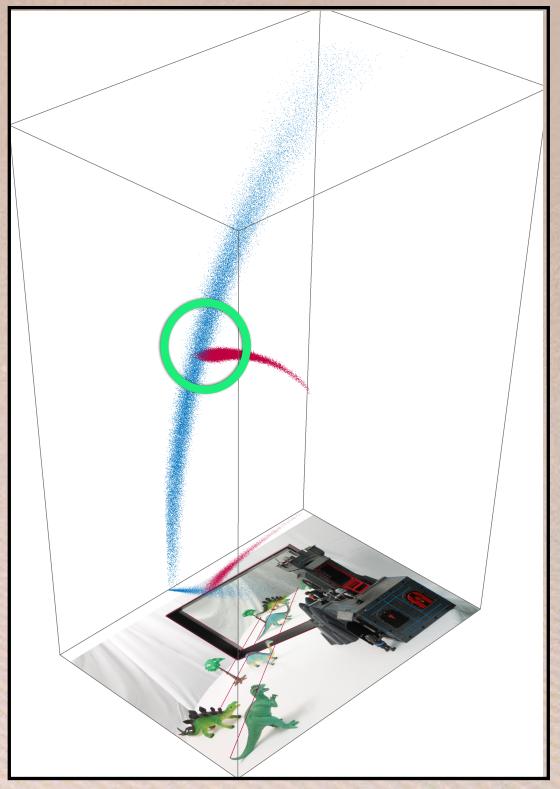


*This diagram not to scale

Center of Projection

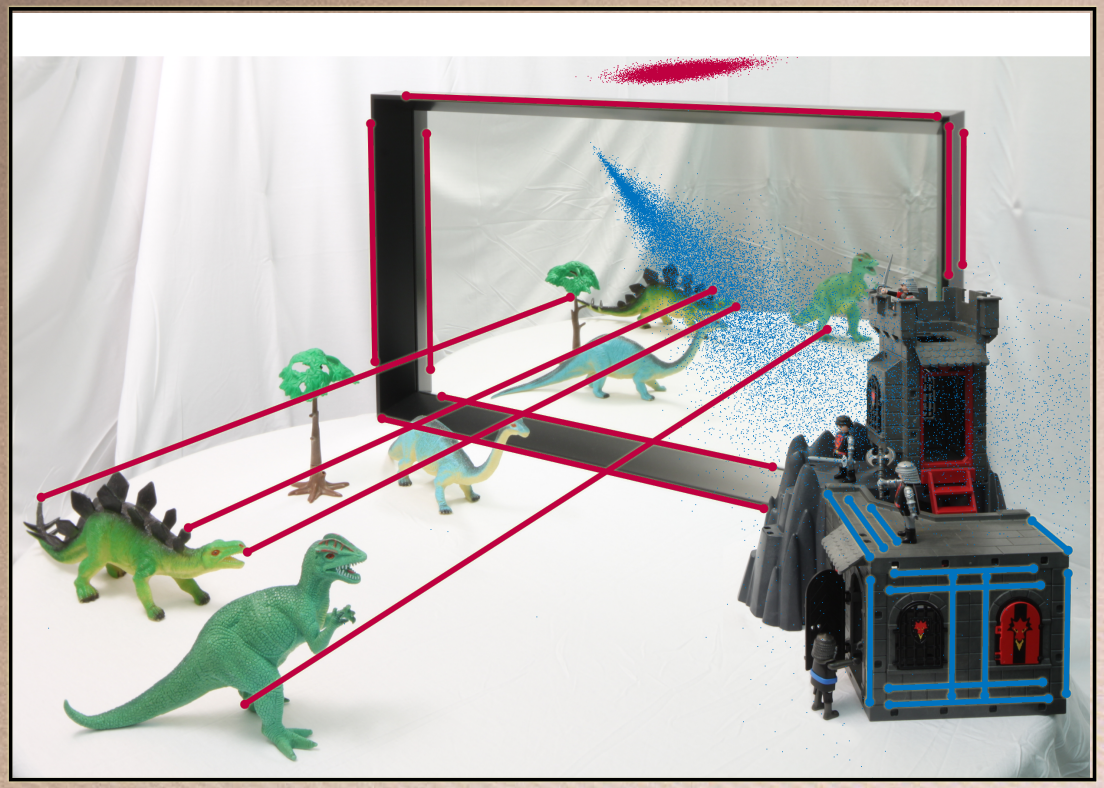
Real Photograph

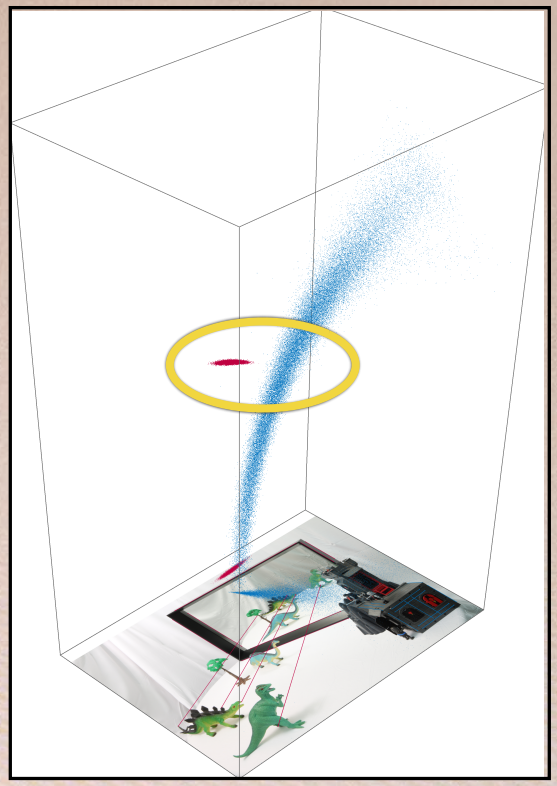




Center of Projection

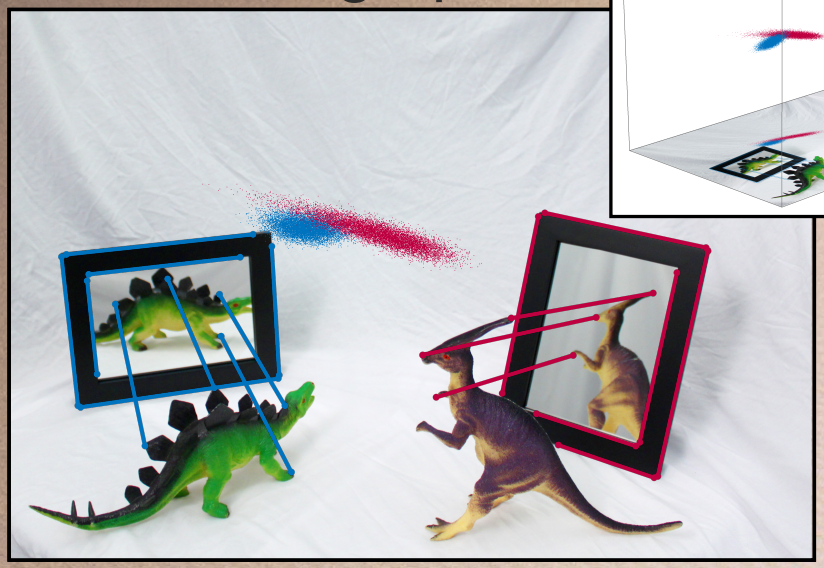
Altered Photograph

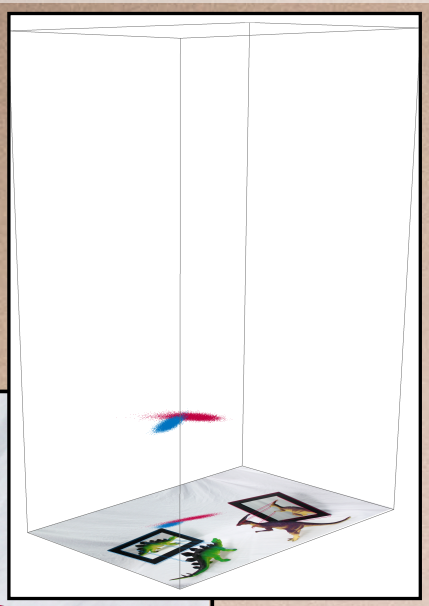




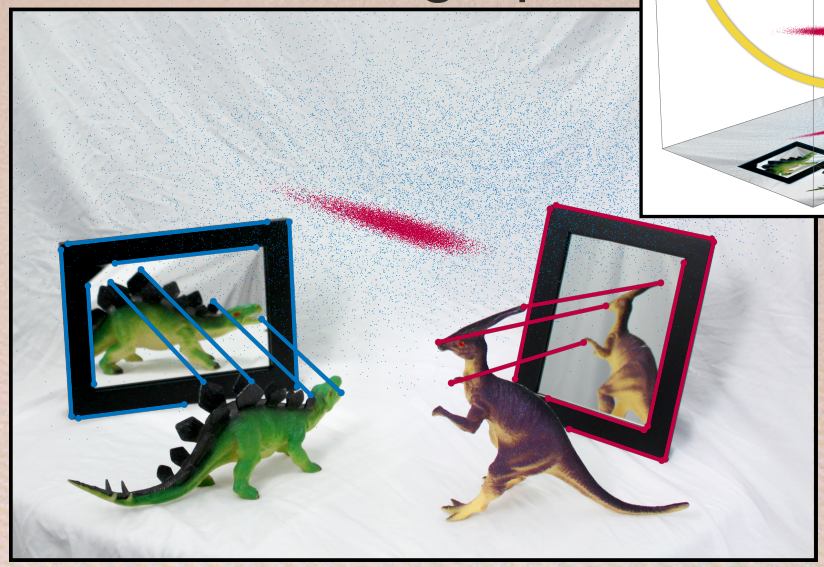
Center of Projection

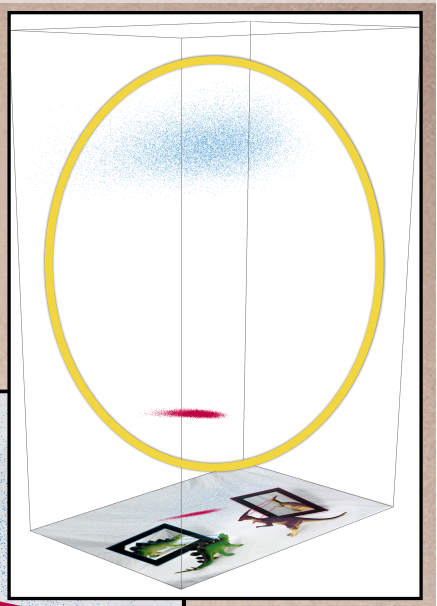
Real Photograph





Altered Photograph

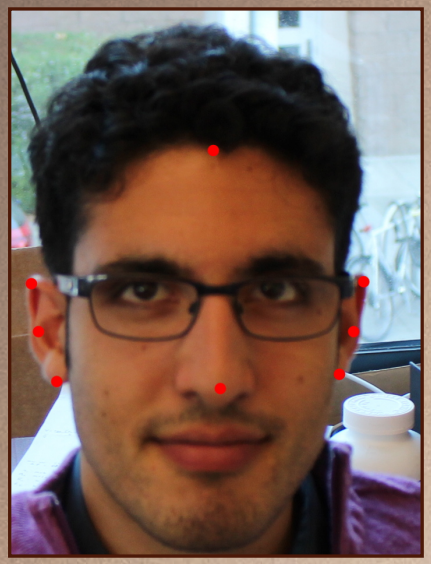




CoP from Faces

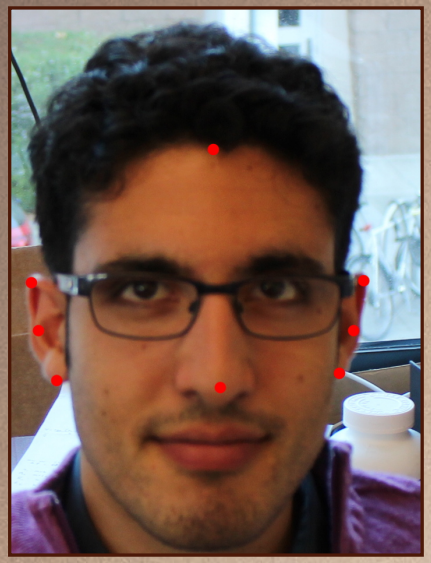
Work in progress

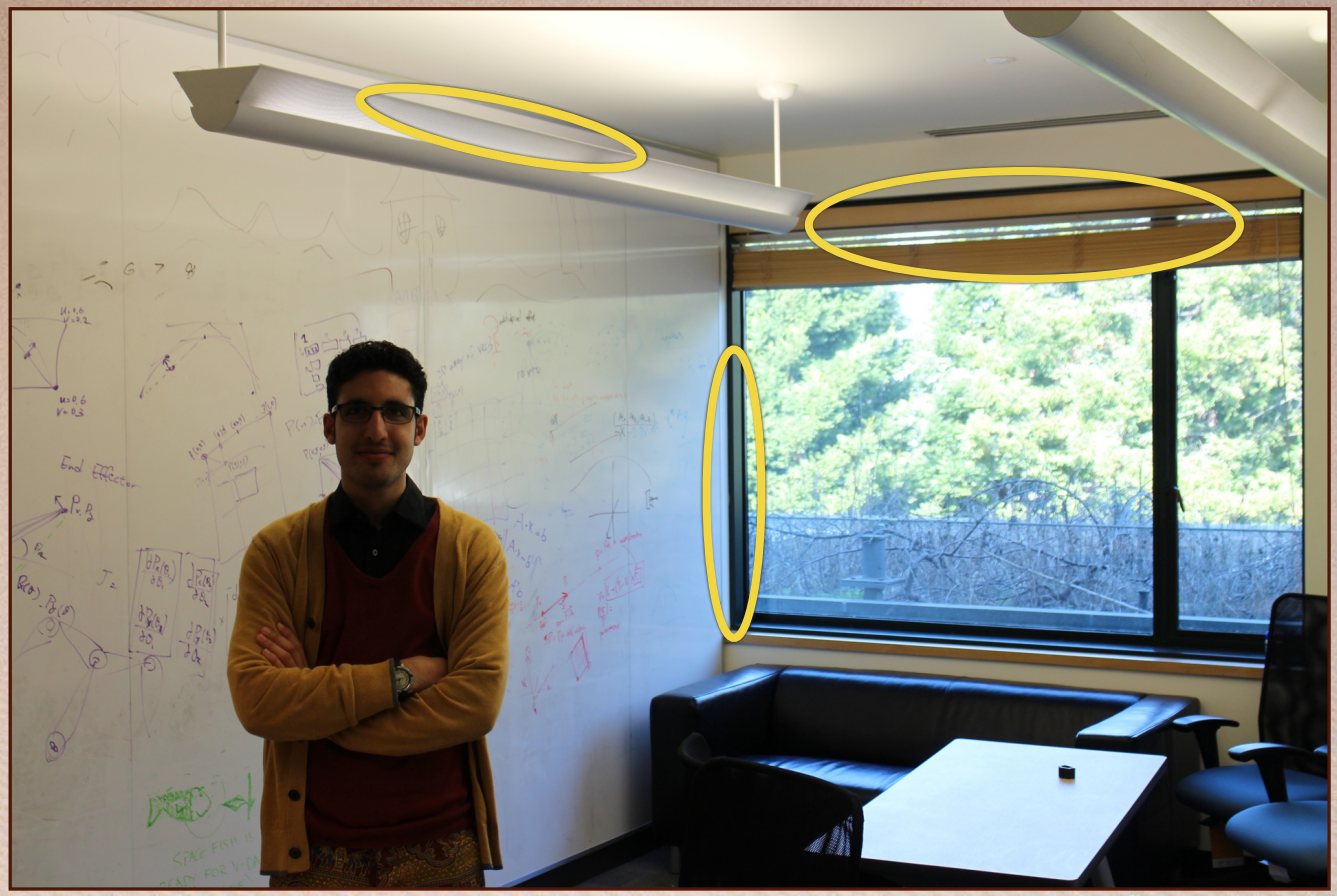
CoP from Faces



Work in progress

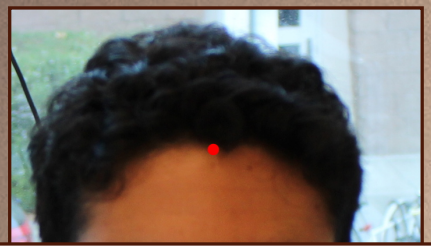
CoP from Faces

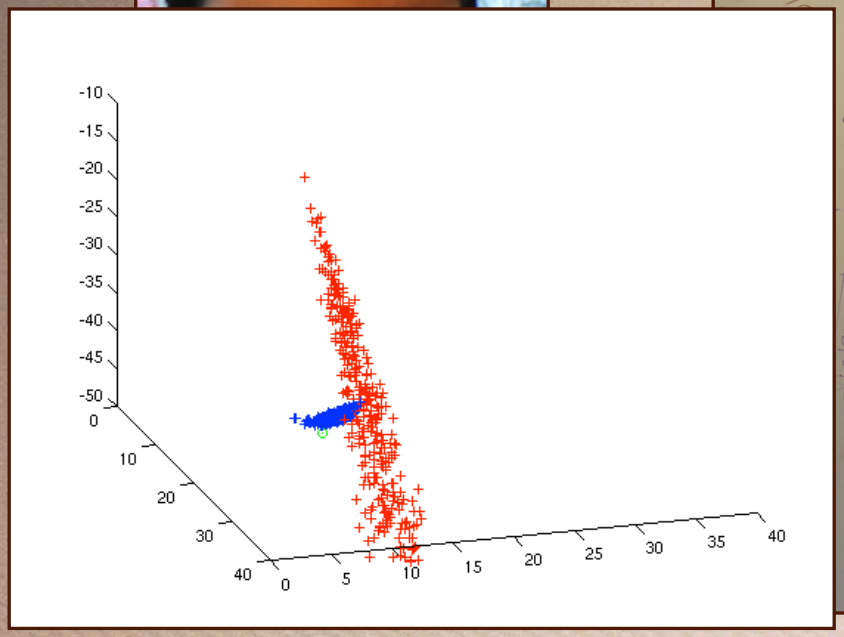


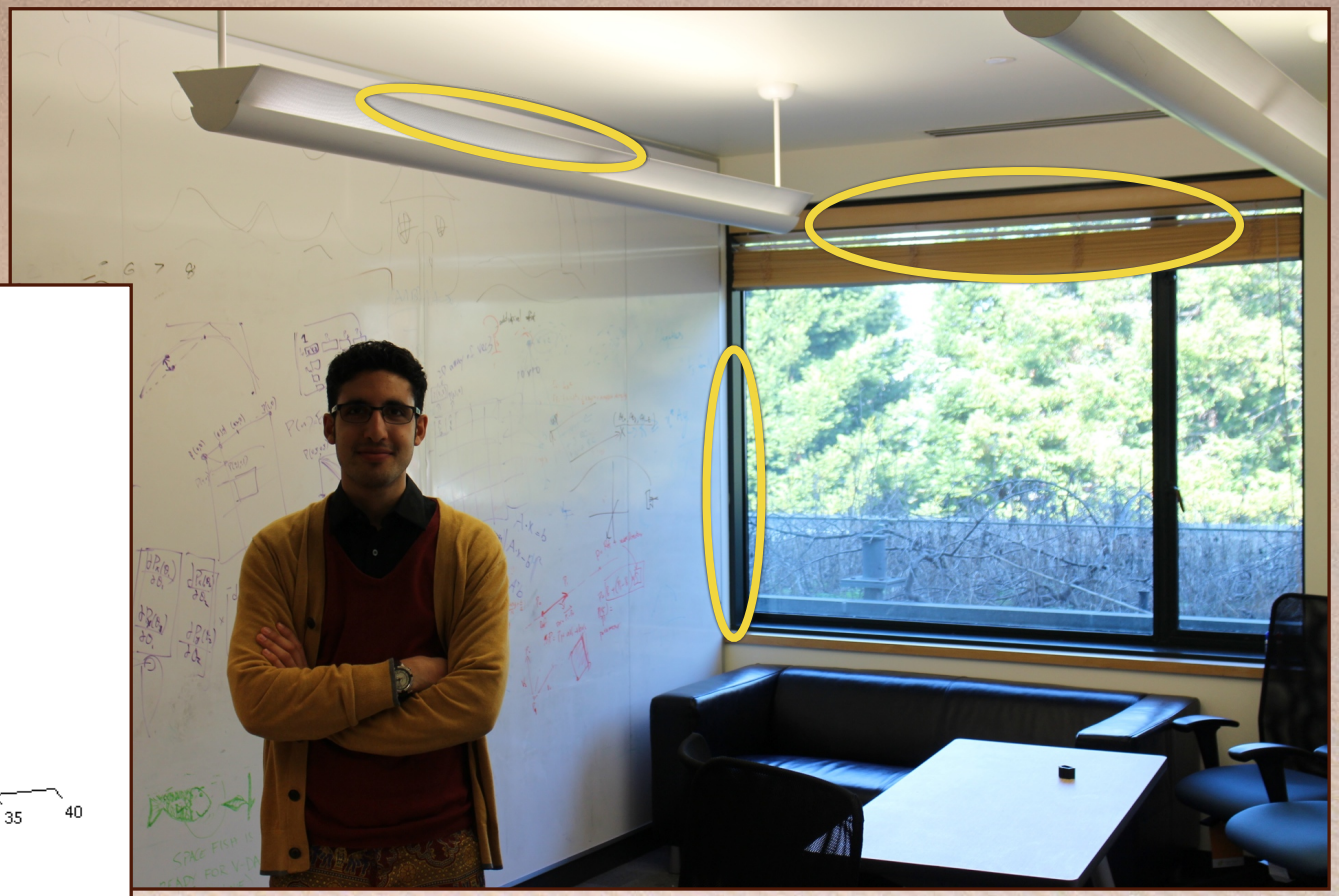


Work in progress

CoP from Faces







Relevant Papers

- Eric Kee, James F. O'Brien, and Hany Farid. “Exposing Photo Manipulation from Shadows and Shading”. ACM Transactions on Graphics, too appear. To be presented at SIGGRAPH 2014.
http://graphics.berkeley.edu/papers/Kee-EPM-2014-XX

- Eric Kee, James F. O'Brien, and Hany Farid. “Exposing Photo Manipulation with Inconsistent Shadows”. ACM Transactions on Graphics, 32(4):28:1–12, September 2013. Presented at SIGGRAPH 2013.
http://graphics.berkeley.edu/papers/Kee-EPM-2013-09

- Valentina Conotter, James F. O'Brien, and Hany Farid. “Exposing Digital Forgeries in Ballistic Motion”. IEEE Transactions on Information Forensics and Security, 7(1):283 – 296, February 2012.
http://graphics.berkeley.edu/papers/Conotter-EDF-2012-02

- James F. O'Brien and Hany Farid. “Exposing Photo Manipulation with Inconsistent Reflections”. ACM Transactions on Graphics, 31(1):4:1–11, January 2012. Presented at SIGGRAPH 2012.
http://graphics.berkeley.edu/papers/Obrien-EPM-2012-01

Thank You