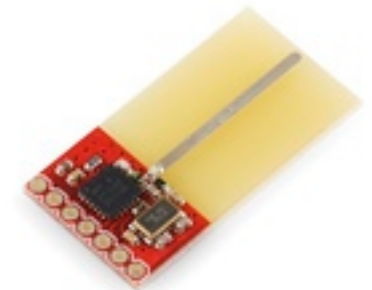


EECS 373

Design of Microprocessor-Based Systems

Thomas Schmid
University of Michigan

Lecture 12: Wireless Communication
October 14, 2010



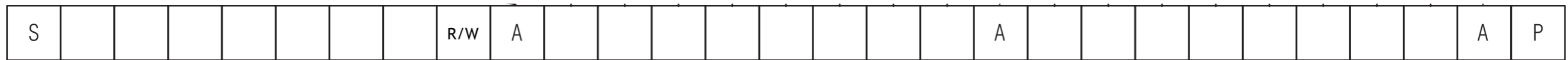
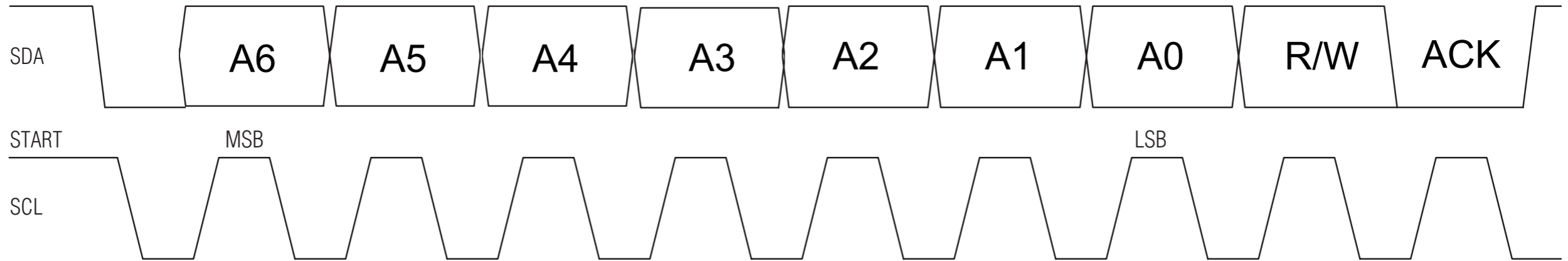
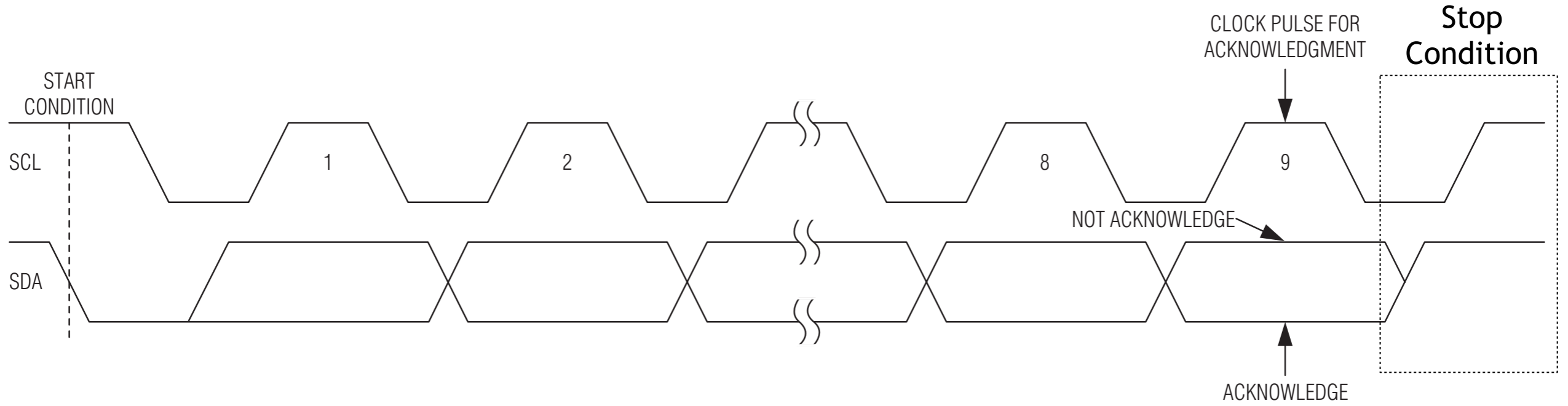


Minute Quiz...

- How do we deal with virtual timers that are close together?
 - Keep time running while executing current handler
 - When handler returns, check for time and the next virtual timer
 - If it is time, execute the next handler. Else, set the HW timer

- What is the simplest way to connect many serial devices with just 2 wires?
- Addressing of chips
- Message acknowledgment
- Single master - multiple slave
- Multiple master - multiple slave

- Two bi-directional open-drain lines SDA, SCL
 - Pull-up resistors to Vcc
- 7-bit address space with 16 addresses reserved



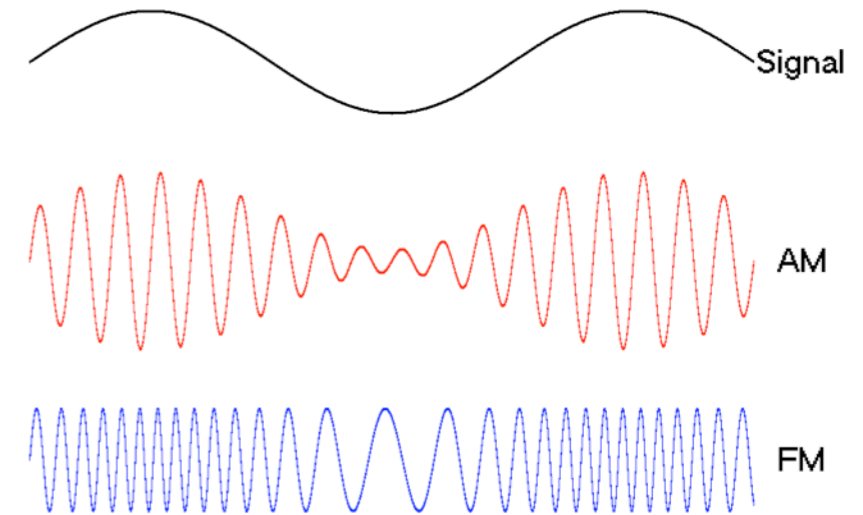


How can we cut the cord?

Modulation is Key to Wireless Communication



- Transmit *information* over an analog pass-band channel
- AM/FM Modulation



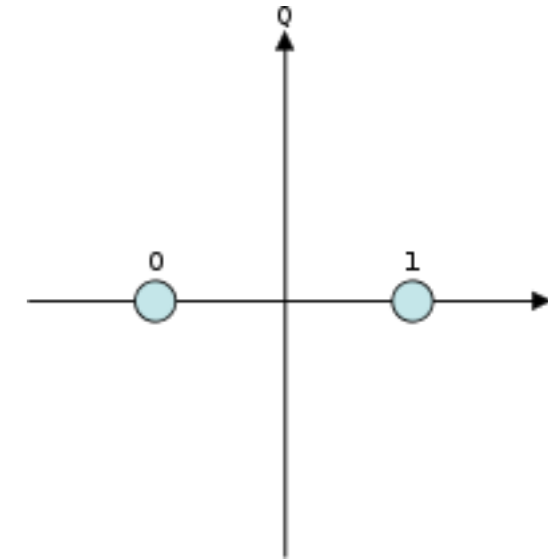
- Alphabet of $M=2^N$ alternative symbols, each of size N
- If we have f_s S/s, the data rate is $N \cdot f_s$ bits/s
- Fundamental Digital Modulation
 - Phase-Shift Keying (PSK)
 - Frequency-Shift Keying (FSK)
 - Amplitude-Shift Keying (ASK)
 - Quadrature Amplitude Modulation (QAM)

Phase Shift Keying

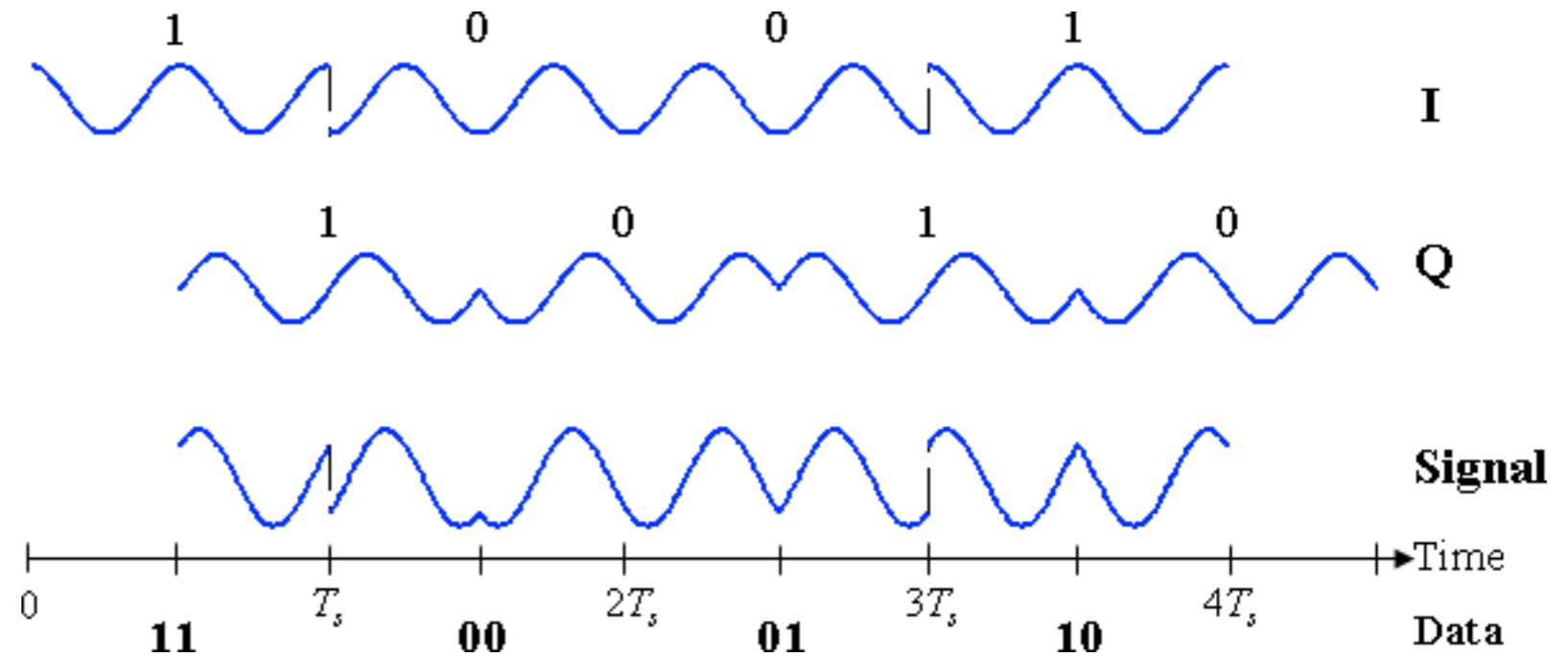
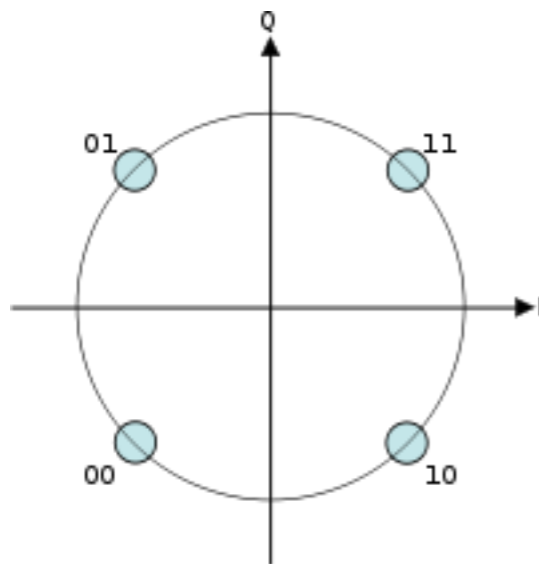


- Binary PSK (BPSK) $M=2$
- Quadrature PSK (QPSK) $M=4$
- 8PSK ($M=8$), 16PSK ($M=16$)
- Differential PSK (DPSK) Differential QPSK (DQPSK)
- Offset QPSK (OQPSK)

BPSK Constellation



O-QPSK Constellation

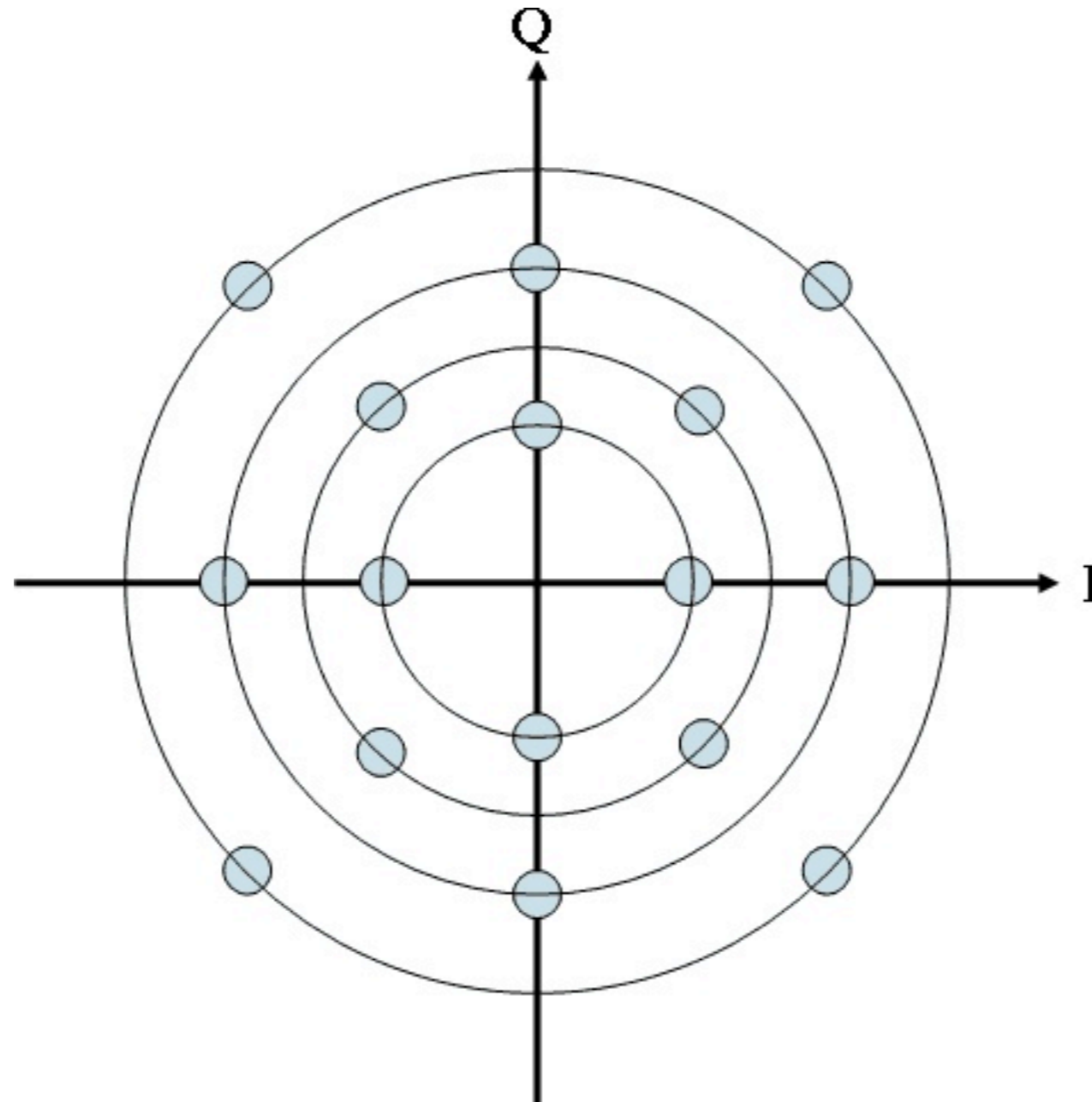


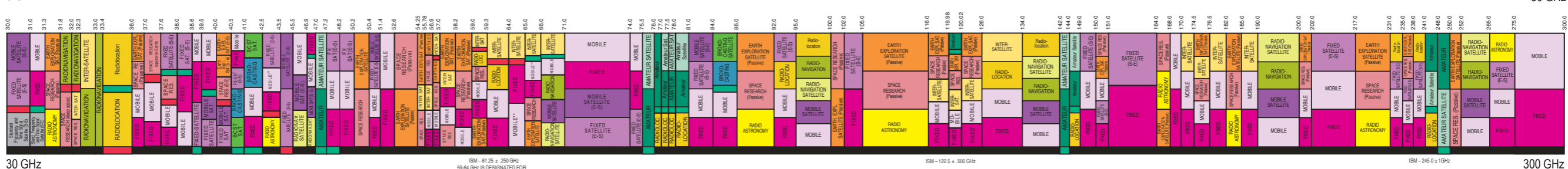
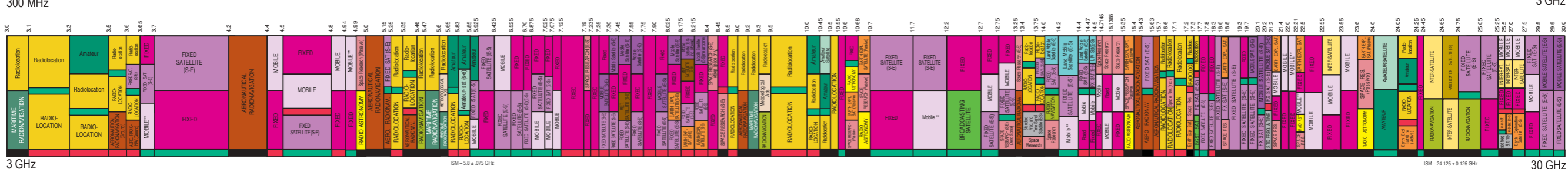
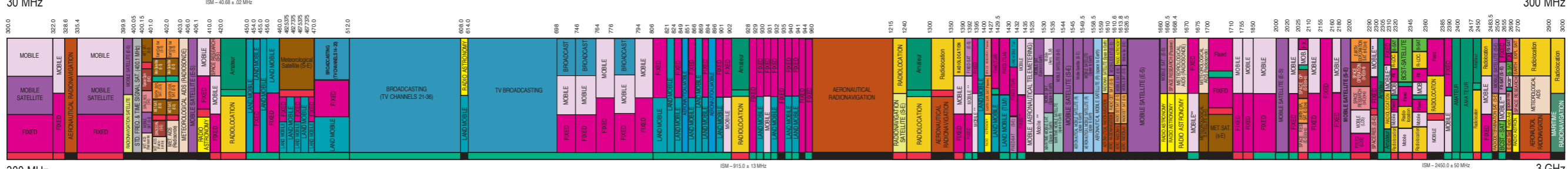
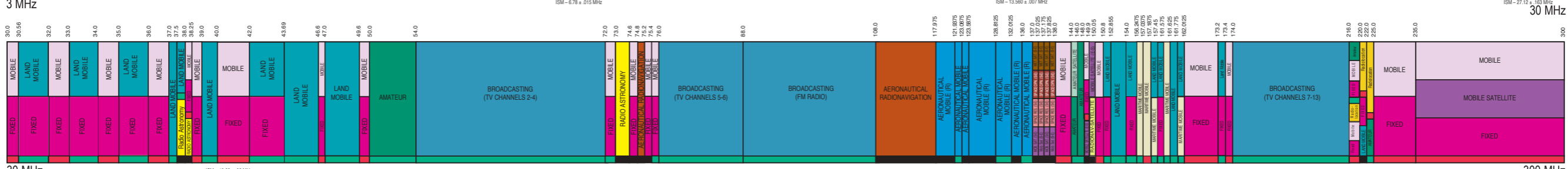
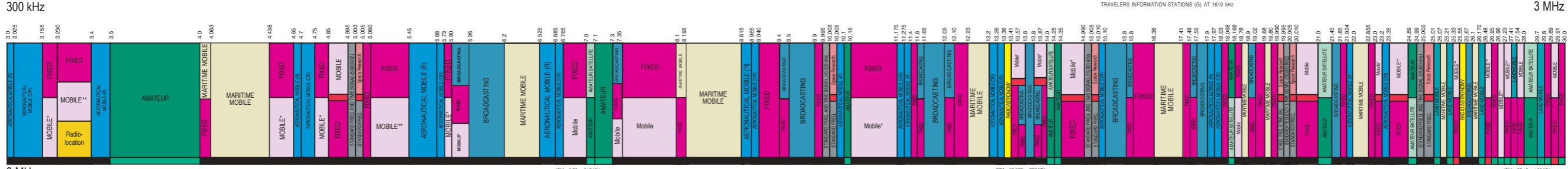
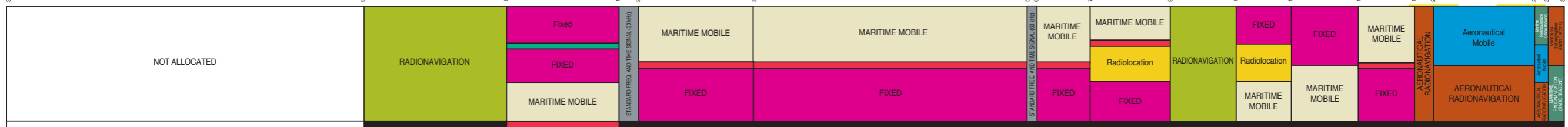
Quadrature Amplitude Modulation



- Adds amplitude modulation to phase shift keying

16-QAM Constellation

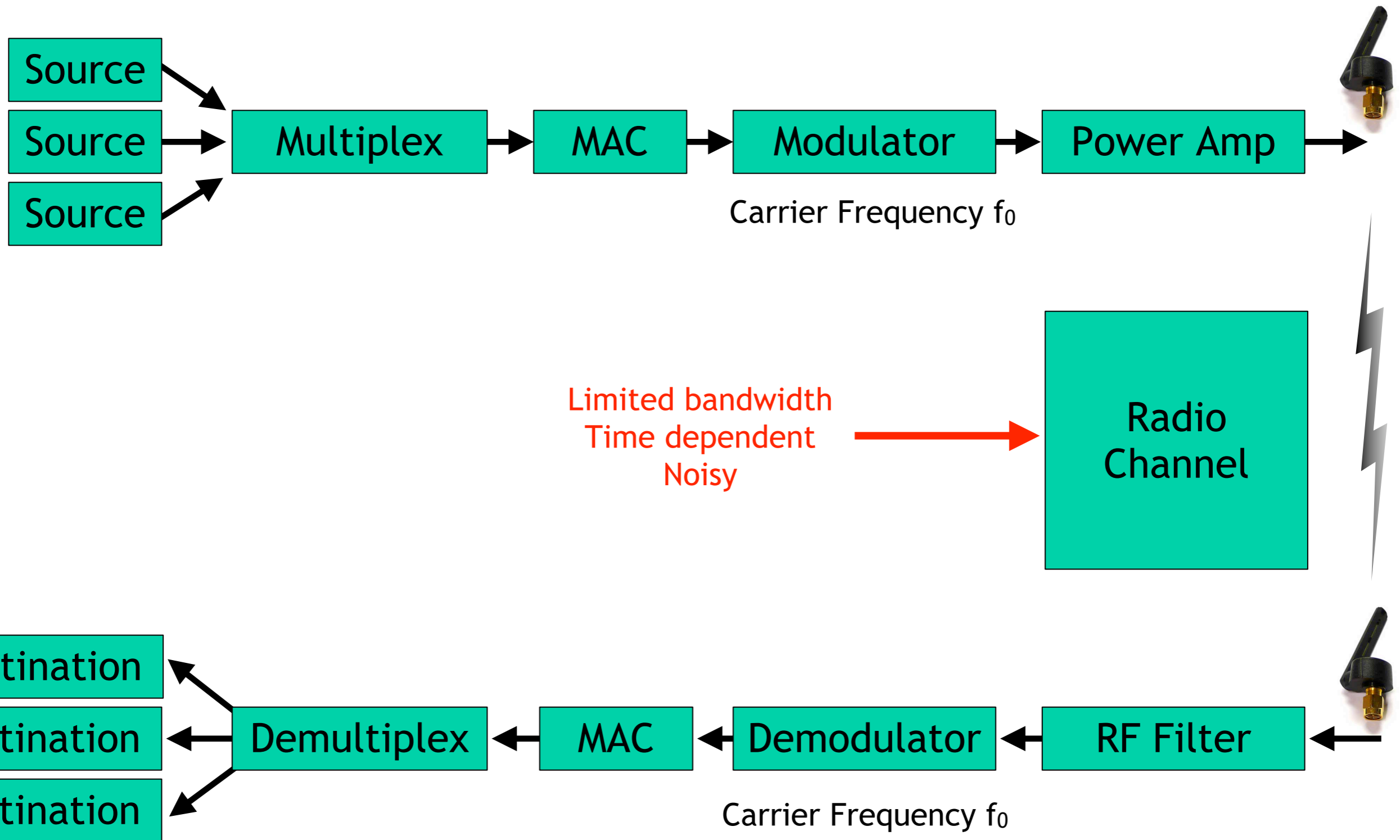






Why should you care about
Wireless Embedded Systems?

Digital Radio



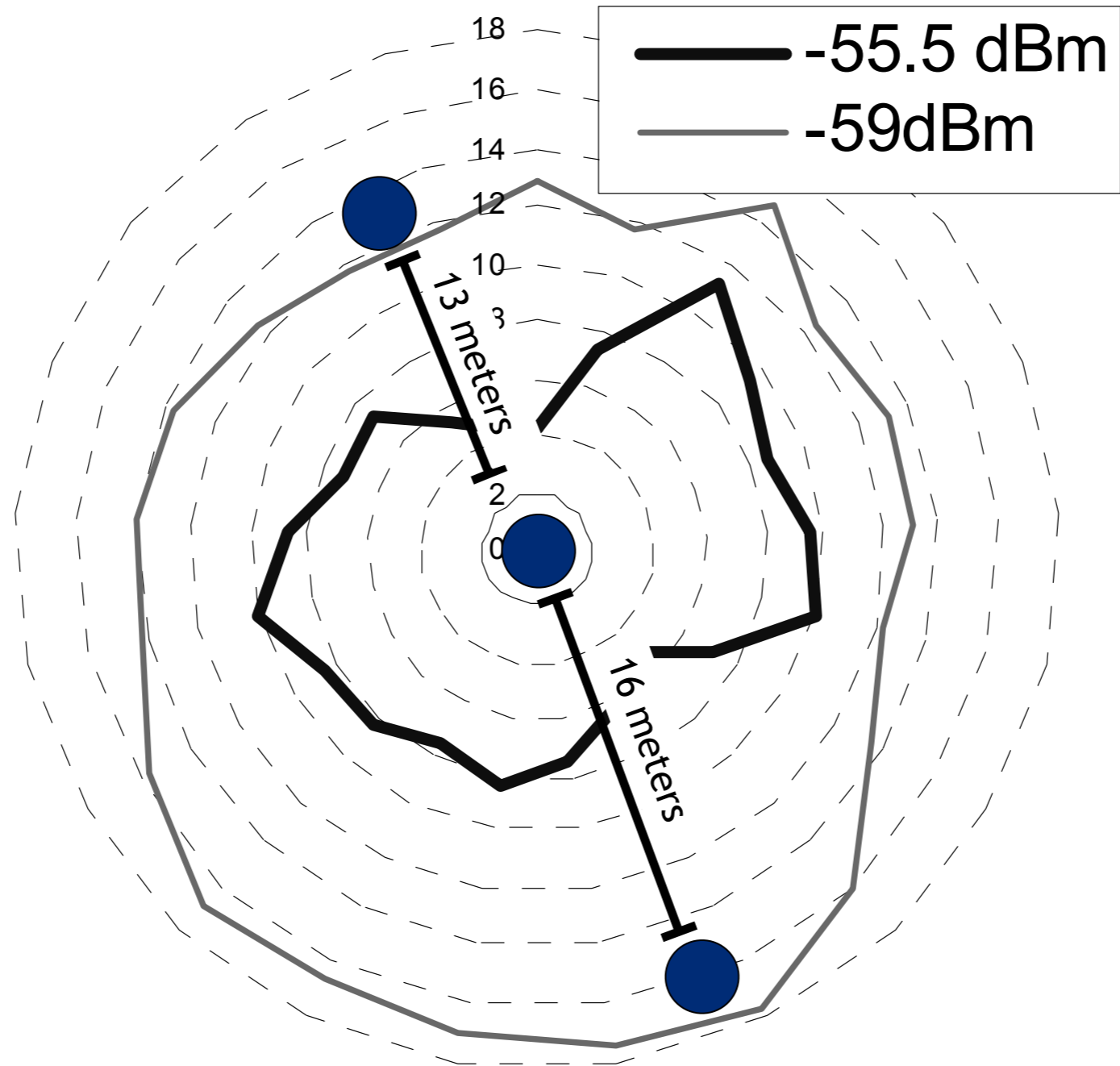
- Path loss proportional to $1/d^n$
- Typical path loss constants

Environment	n
Free Space	2
Urban area cellular radio	2.7-3.5
Shadowed urban cellular radio	3 - 5
In-building Line of Sight	1.6 to 1.8
Obstructed in building	4 to 6
Obstructed in factories	2 to 3

- Problems

- Channel is time-varying and can be significantly different for nodes at the same distance
- Link can even be asymmetric, i.e., the link between node 1 and 2 is different than the one from node 2 to 1

No Disk Model Connectivity

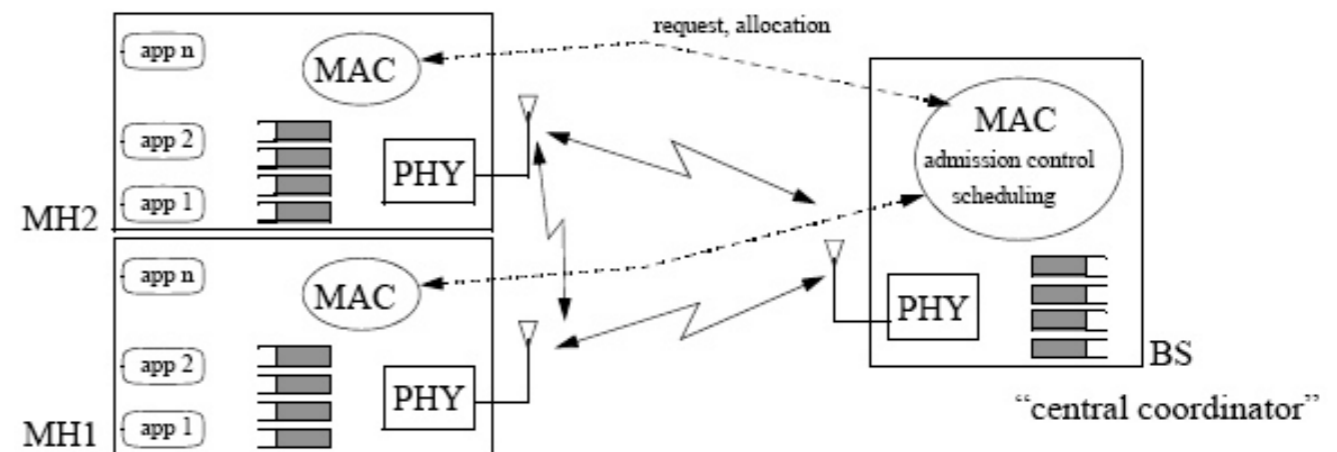
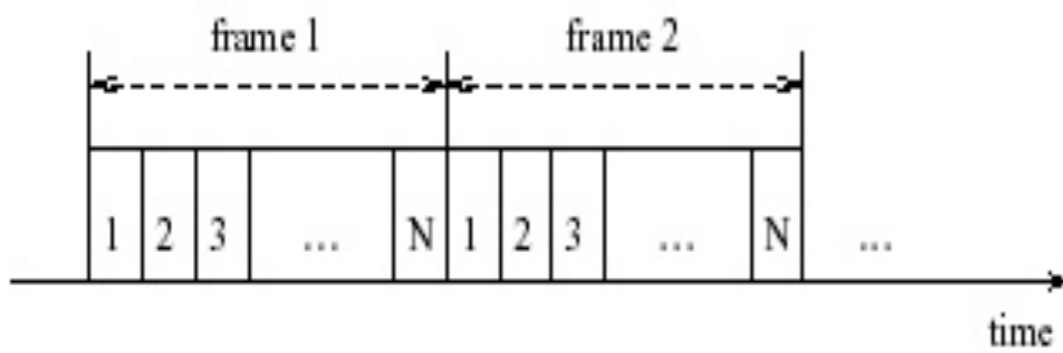
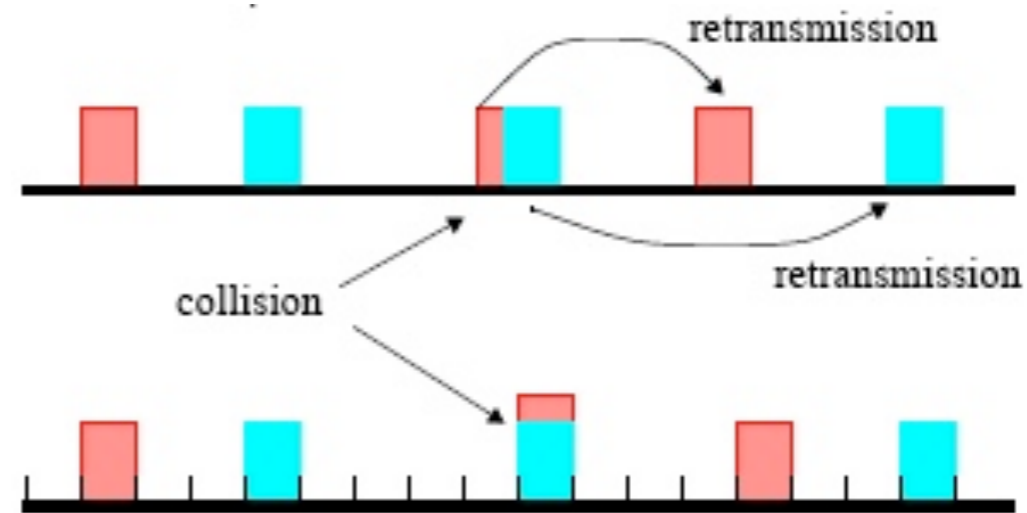
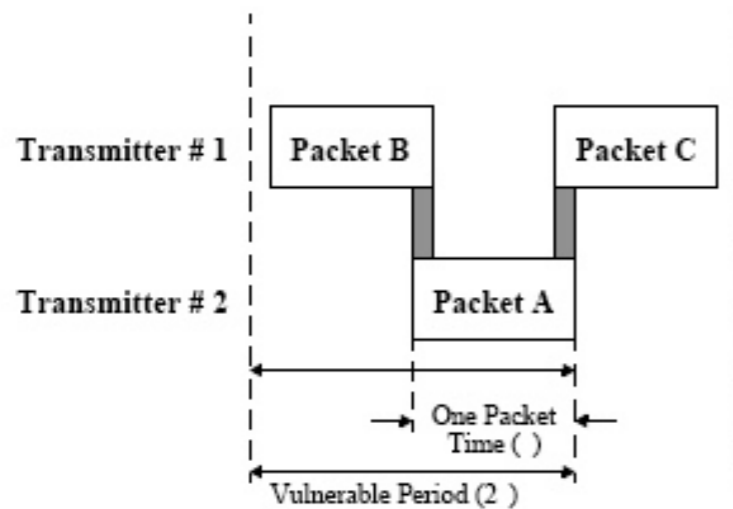


- Hidden Terminal Problem

Taxonomy of MAC Protocols



- Random-access vs. Scheduled
- Time Slotted vs. Non-slotted
- Peer-to-peer vs. Master-slave
- MAC level retransmission

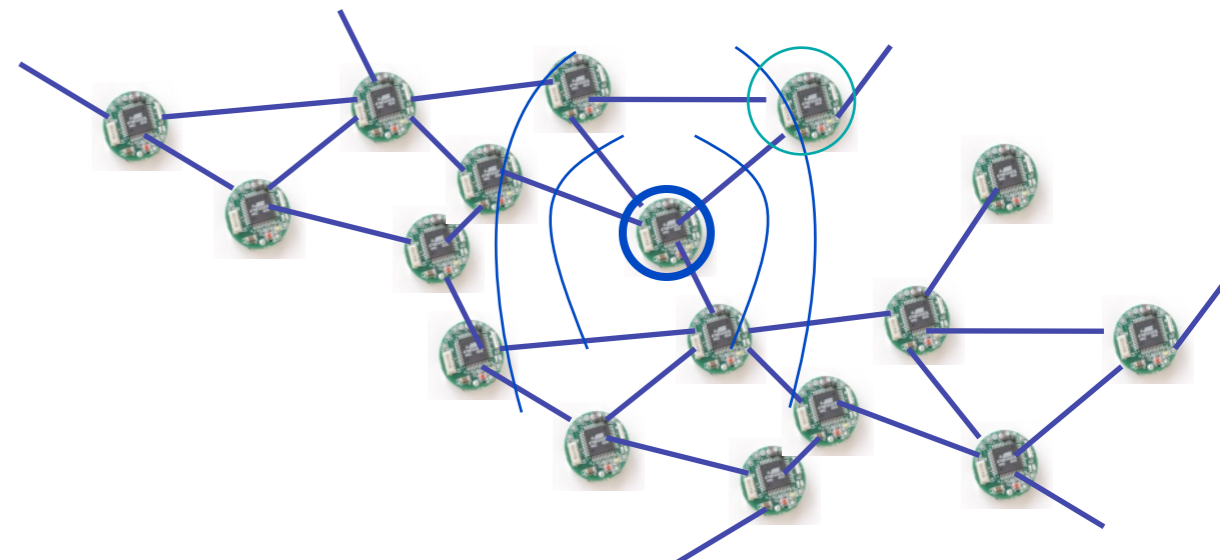


Some Common Examples

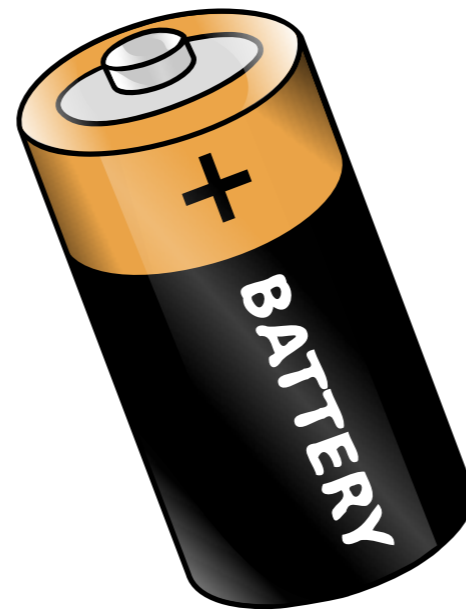


- ALOHA
 - Random, slot-less or slotted, peer-to-peer
- IEEE 802.11 infrastructure DCF and ad-hoc mode
 - Carrier Sense Multiple Access With Collision Avoidance (CSMA/CA)
 - Random, slot-less, peer-to-peer
- IEEE 802.11 infrastructure PCF
 - Scheduled (polling), slot-less, master
- Bluetooth Piconets
 - Scheduled (polling), time-slot (with frequency hopping), master
- Time Division Multiple Access (TDMA)
- Code Division Multiple Access (CDMA)

- Different protocols and algorithms for different goals
- Any-to-any routing
 - DSDV, DSR, AODV
- Geographic Routing
 - Nodes know their own and their neighbor location
 - Address is physical location of node
 - Forward to neighbor closest to address
- Directed Diffusion
 - Data, not node, centric
 - Nodes publish data, users subscribe
- Flooding, Gossiping, Trickle
- Collection
- IPv6 LoWPAN RPL ('ripple')
 - proactive distance vector approach
 - optimized for low-power networks



Power Aware MAC Protocols

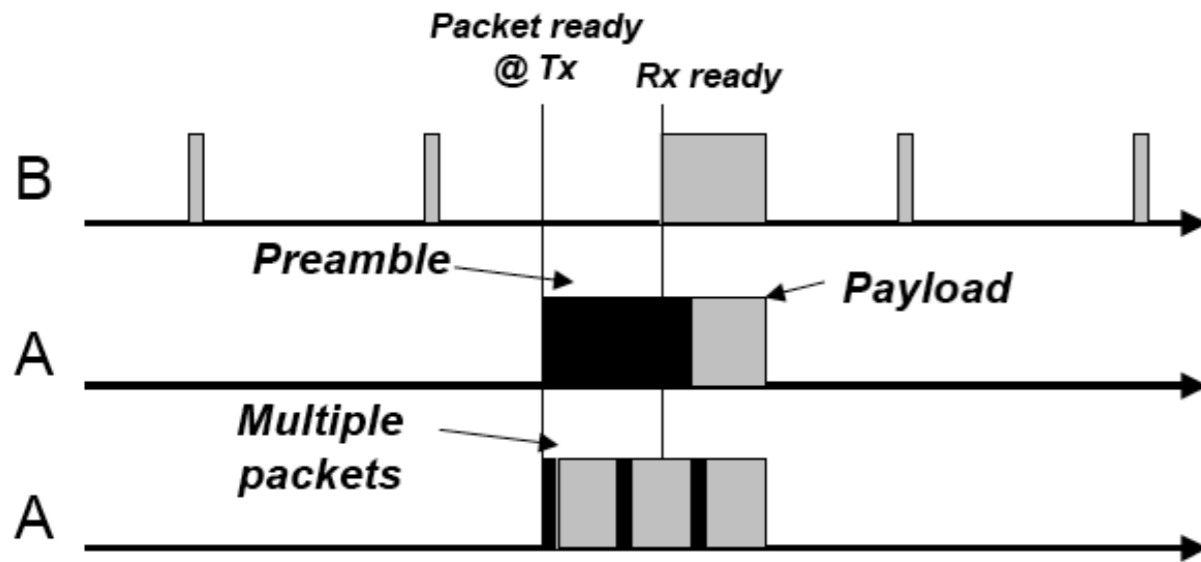
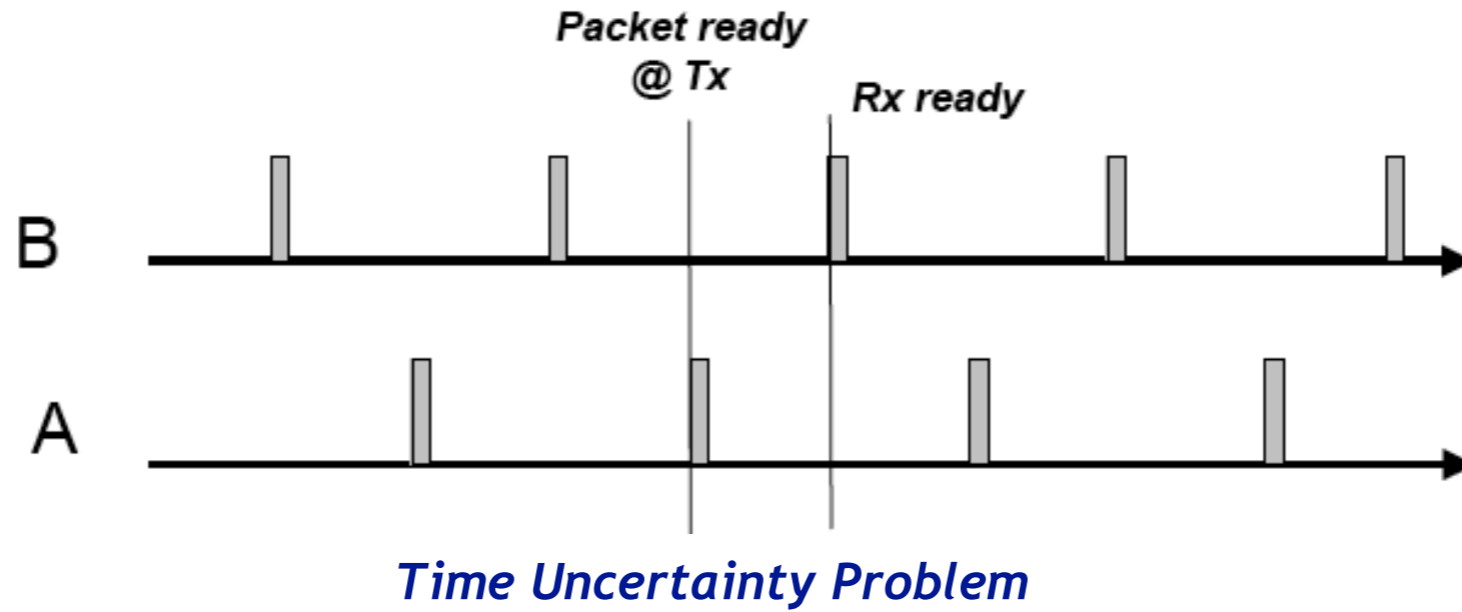


TI CC2520, TI MSP430, Actel SmartFusion Power Comparison

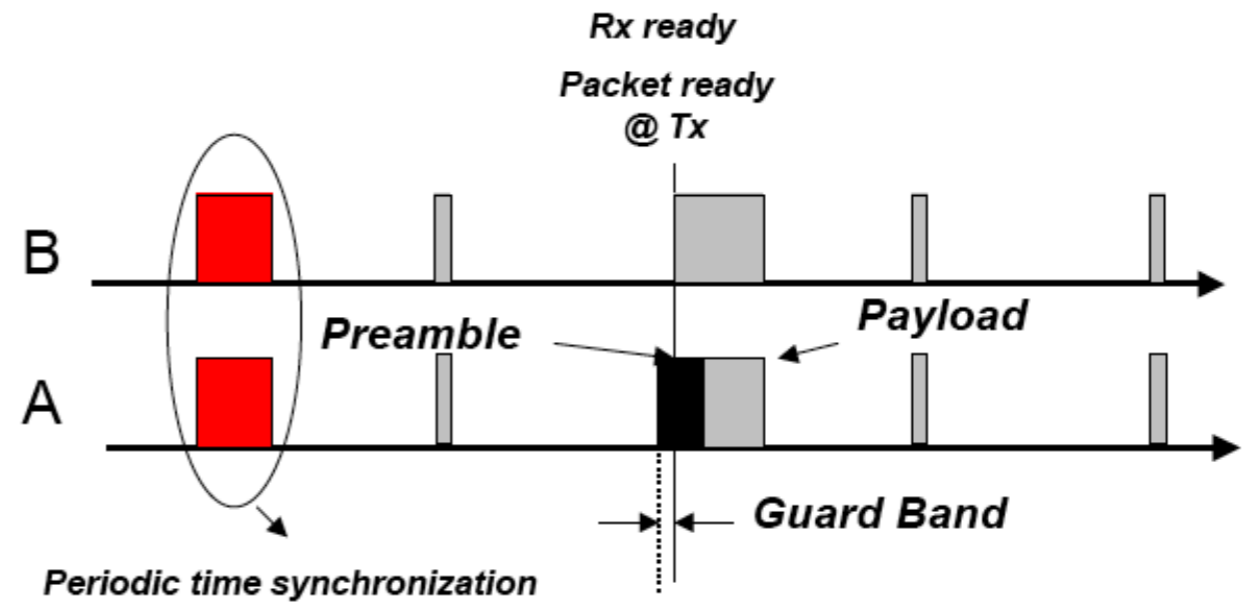


- TI CC2520
 - RX 18.5mA
 - TX 33.6 mA @ +5 dBm, 25.8 mA @ 0 dBm
 - < 1 uA in power down
- TI MSP430F5437A
 - Active Mode: 5.7 mA, 3.0 V @ 25 MHz
 - Standby Mode: 2.1 uA, 3.0 V
- Actel SmartFusion
 - MSS running at 100 MHz, 40 mA
 - MSS in WFI at 100 MHz, 20 mA
 - Stand By: 3 mA on 1.5 V, 1 mA on 3.3 V
 - Time Keeping: 10 uA on 3.3 V

Time is Energy

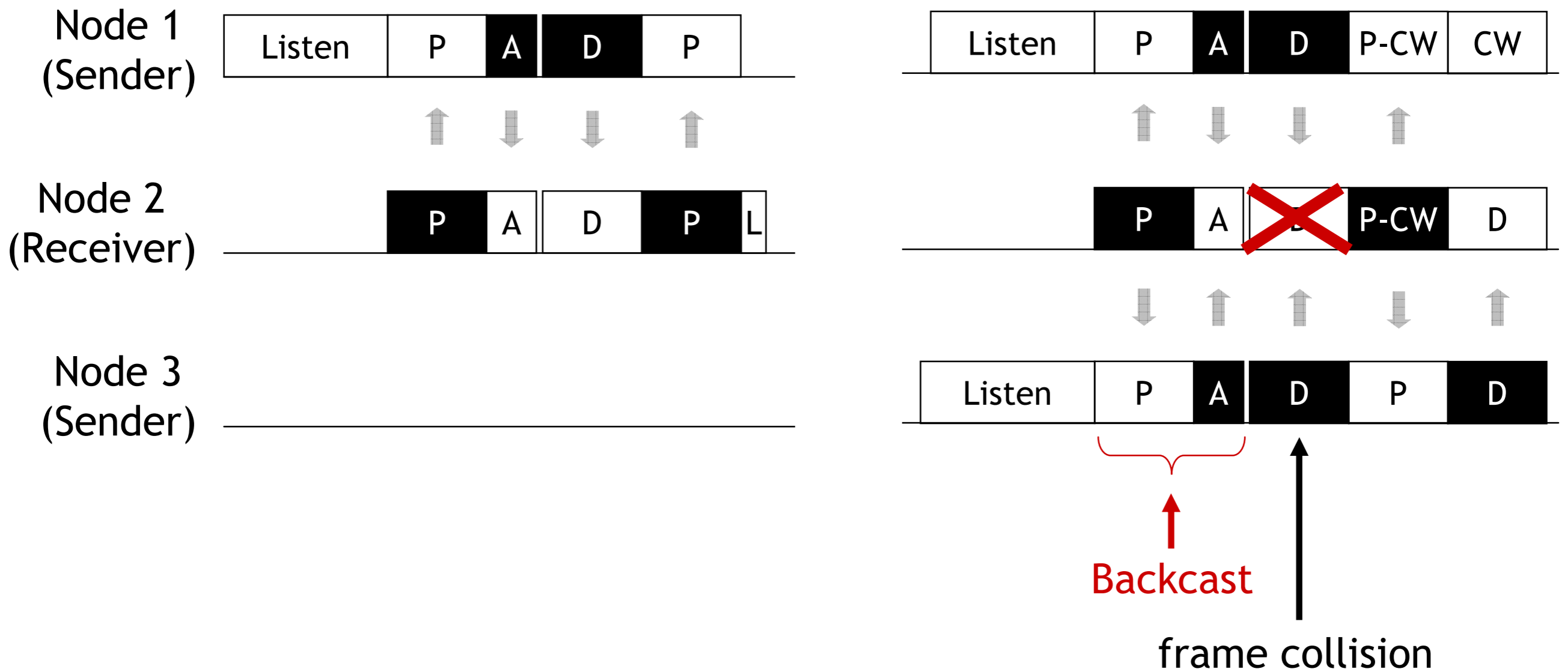


Asynchronous Approach
(long preambles: e.g. 1212B @ 2.2%)

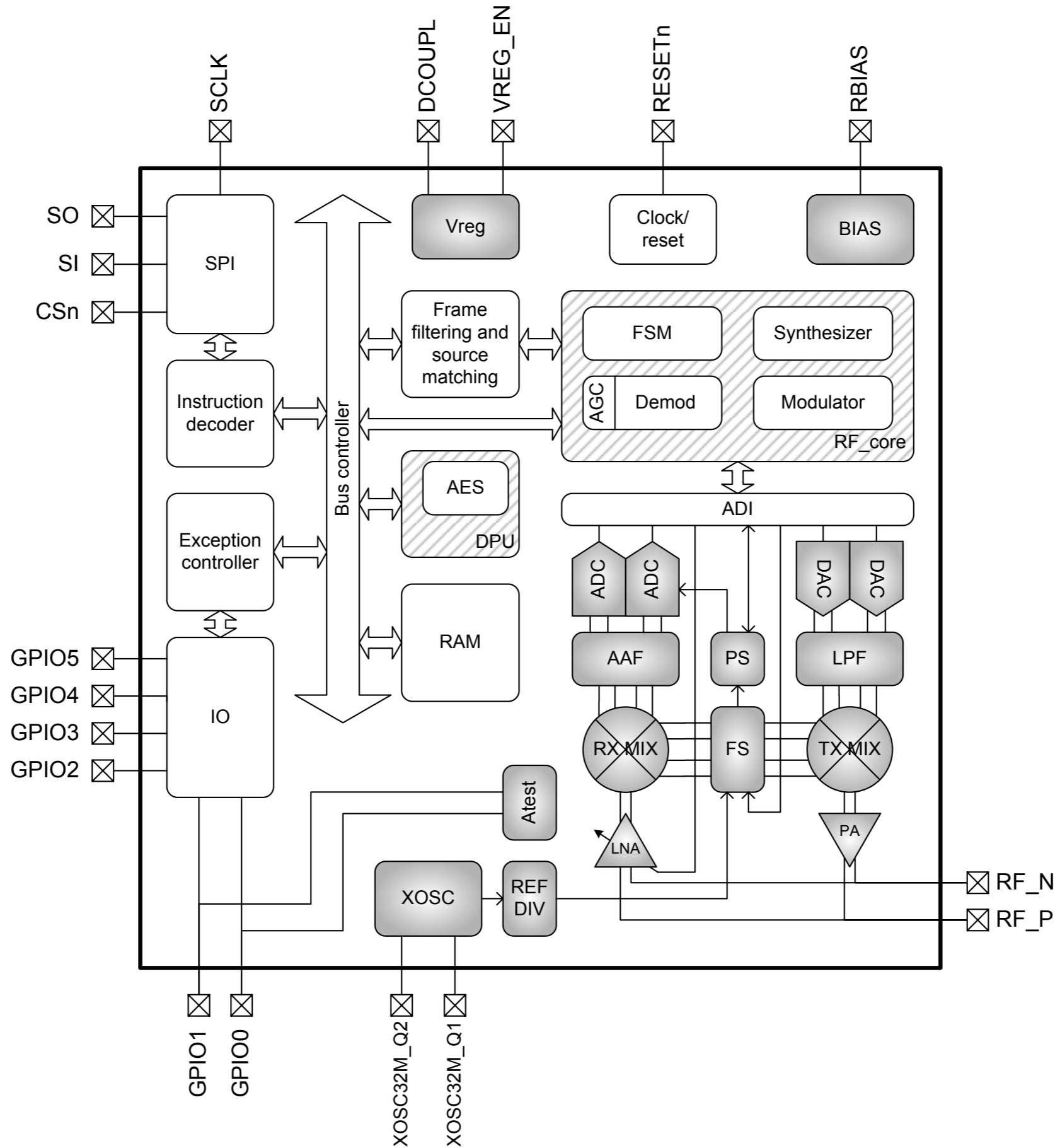


Synchronous Approach
(frequent sync packets: e.g. every 15s)

Receiver Initiated MACs



Talking to a Radio, TI CC2520

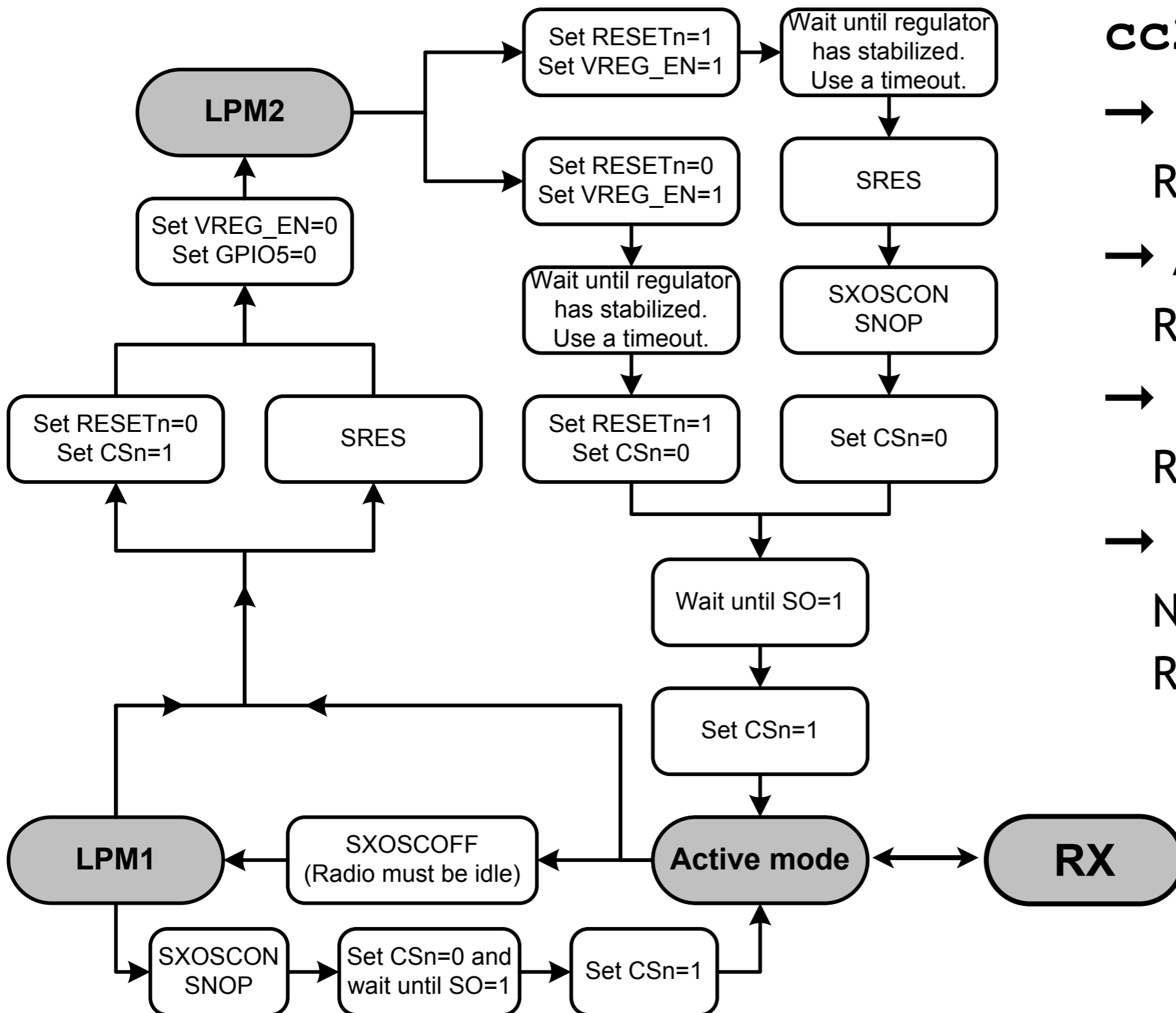


TI CC2520 GPIO Configuration



GPIO pin	Dir	Value	Pull up	Extra drive	Polarity	Signal	GPIOCTRLn value (hex)	Description
0	Out	0	No	No	Positive	clock	0x00	1MHz clock signal with 50/50 duty cycle.
1	Out	0	No	No	Positive	fifo	0x27	High when one or more bytes are in the RX FIFO. Low during RX FIFO overflow.
2	Out	0	No	No	Positive	fifop	0x28	High when the number of bytes in the RX FIFO exceeds the programmable threshold or at least one complete frame is in the RX FIFO. Also high during RX FIFO overflow.
3	Out	0	No	No	Positive	cca	0x29	Clear channel assessment. See FSMSTAT1 register for details on how to configure the behavior of this signal.
4	Out	0	No	No	Positive	sfd	0x2A	Pin is high when SFD has been received or transmitted. Cleared when leaving RX/TX respectively.
5	In	Tie to ground or VDD	No	No	Positive		0x90	No function

TI CC2520 Power States



cc2520driver.h

→ RX

RadioState_turnOn()

→ Active

RadioState_standby()

→ LPM1

RadioState_turnOff()

→ LPM2

Not implemented yet

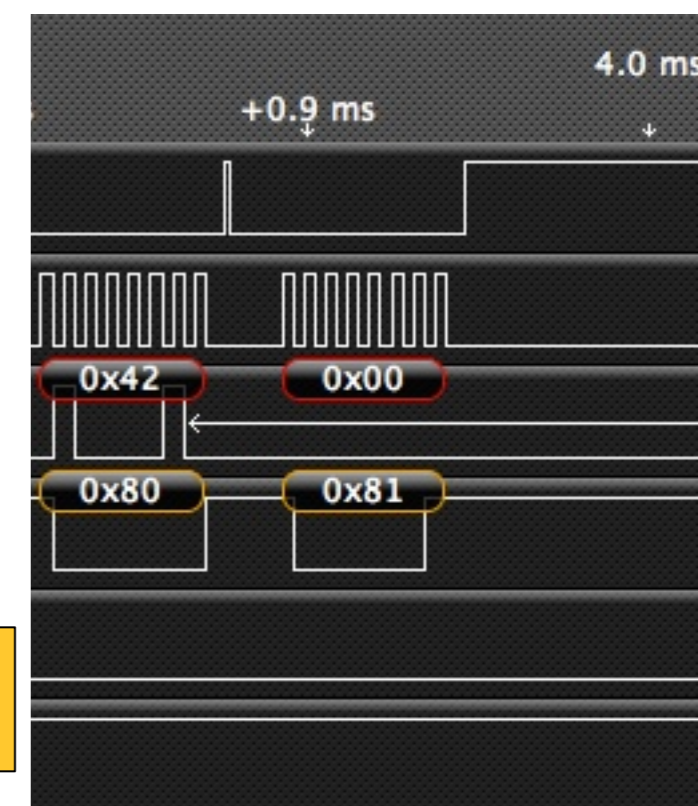
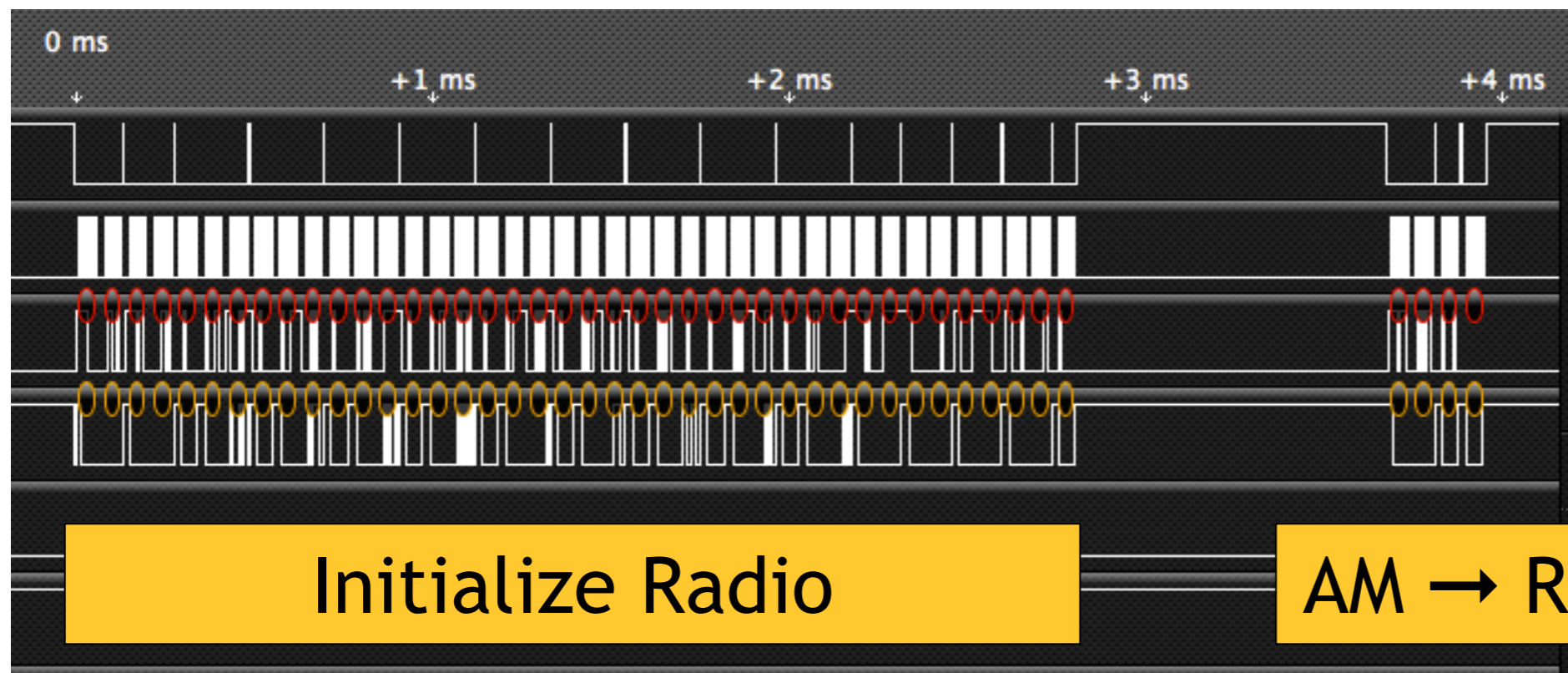
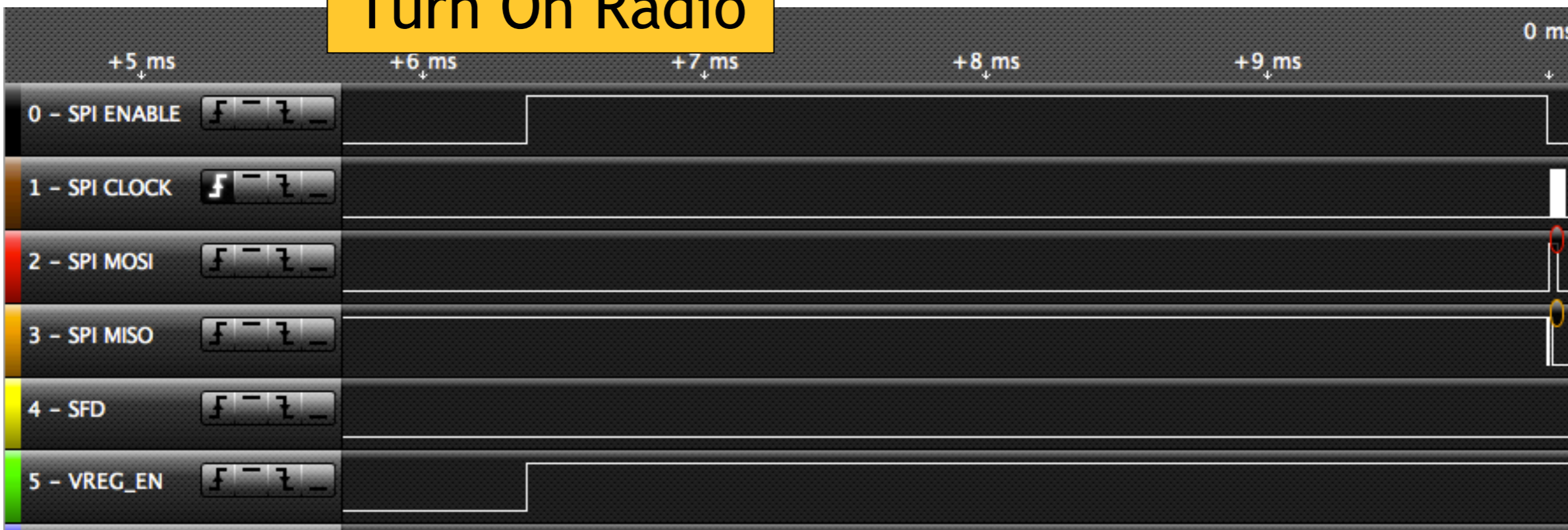
RadioState_shutdown()

- Switching state is **NOT** instantaneous
- Depends on
 - Radio hardware switch on/off times (e.g. crystal bootup)
 - SPI communication speed for initial configuration after shutdown
- Power Draw
 - RX: 18.5mA
 - TX: 33.6 mA @ +5 dBm
 - Active Mode: 1.6 mA
 - LPM1: 175 uA
 - LPM2: 30 nA
- Wake-Up and Timing
 - LPM2 → Active Mode: 0.3 ms (regulator + XOSC startup time)
 - LPM1 → Active Mode: 0.2 ms (XOSC startup time)
 - AM → RX or TX: 192 us
 - **DOES NOT INCLUDE SPI TRANSFERS!**

TI 2520 Driver Bootup



Turn On Radio



Mostly driver limitations, and slow SPI Clock @ 160kHz

- Received Signal Strength RSSI

- 8-bit signed
- Calculated for every packet received

```
void Radio_receive(uint8_t seqn, uint16_t panid, uint16_t saddr,  
uint16_t daddr, uint8_t* payload, uint8_t length, int8_t rssi);
```

- Approximately related to received signal power as
 $P = \text{RSSI} - \text{OFFSET} [\text{dBm}]$
where $\text{OFFSET} \approx 76 \text{ dBm}$

- CCA

- Clear channel assessment
- Measures noise level of RF channel
- High noise level indicates on-going communication
- Implemented, but not exported in current driver

- Many many more features

- See TI CC2520 Datasheet

<http://focus.ti.com/lit/ds/symlink/cc2520.pdf>

Radio Modules



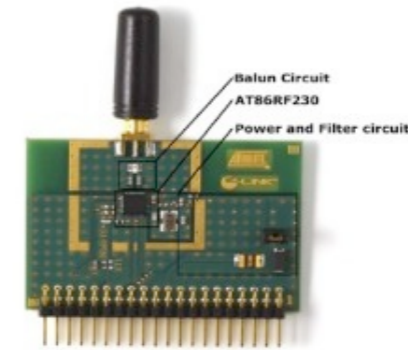
- IEEE 802.15.4 Radios

- X-Bee

- Out-of-the-box RF communication
 - Serial UART interface (API or AT Commands)

- Atmel AT86RF230

- STM32W (Cortex-M3 & Radio on a chip)



- ANT

- e.g. Nordic nRF24AP1 or nRF24AP2
 - Nike+ and in many iPhones/iPods

- WiFi

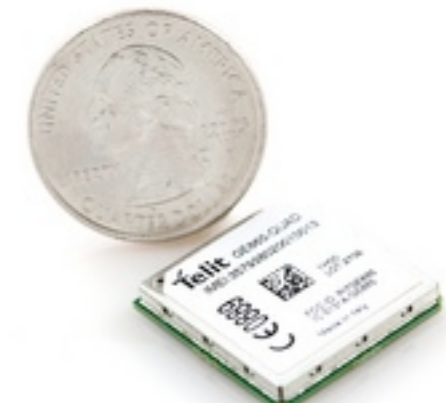
- DigiConnect ME WiFi

- Cellular

- Telit GM862, GSM/GPRS & GPS
 - Runs Python Scripts



- RFID, DASH7, Bluetooth, Z-wave, RuBee, NFC



Some References



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