Antisocial Parallelism: Avoiding, Hiding and Managing Communication

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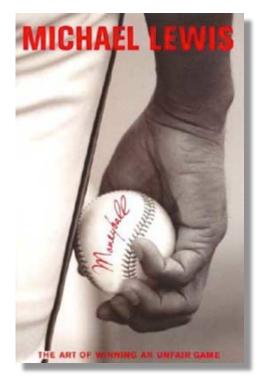




"Big Data" Changes Everything...What about Science?









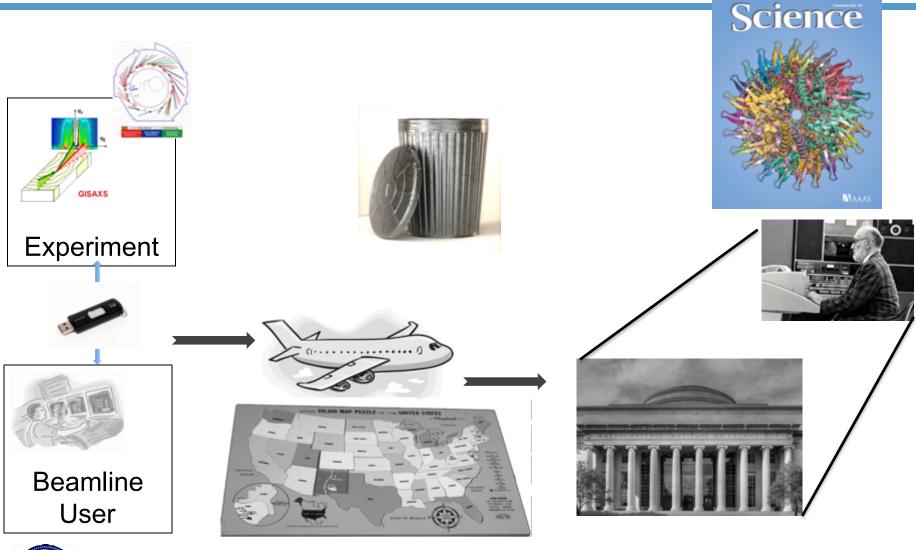


Transforming Science: Finding Data

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- Search for scientific data on the web
- Automated metadata annotation / feature identification
- Data: images, genomes, simulations, MRI, MassSpec,...

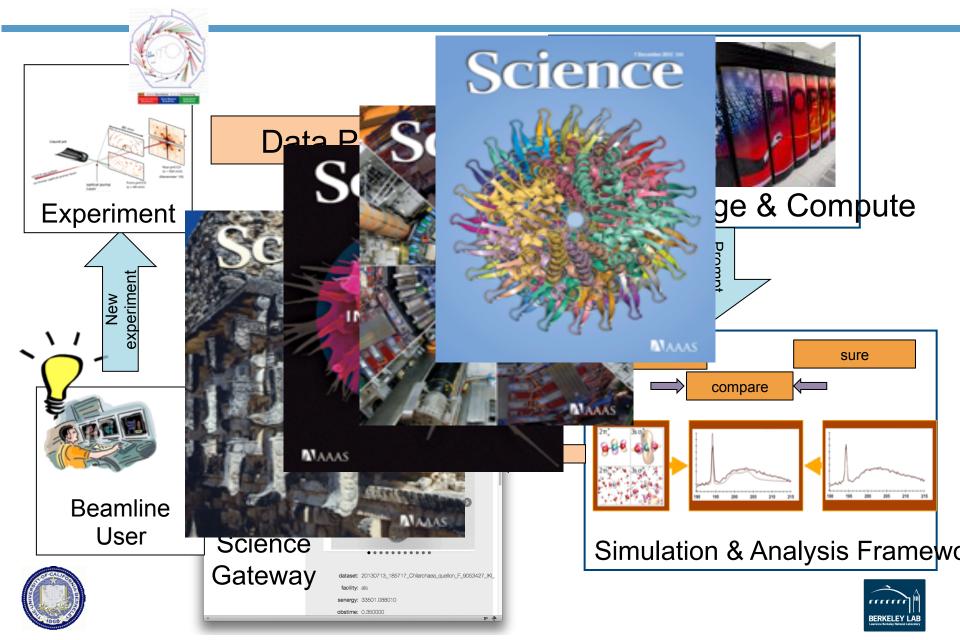
Scientific Workflow Today







The Future of Experimental Science

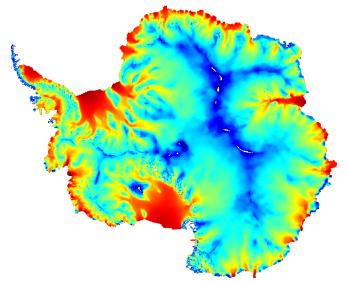


Transforming experimental science: "Superfacility" for Science

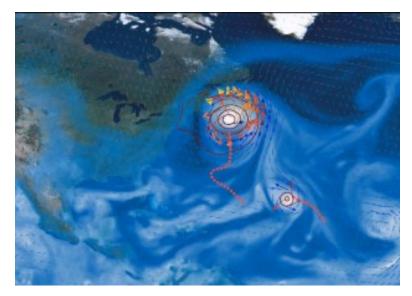


- Robotics, Special purpose processors at experiments
- Mathematics / algorithm for real-time and offline analysis
- Massive numbers of simulations for inverse problems
- Networks and software for data movement, management

Science at the Boundary of Simulation and Observation



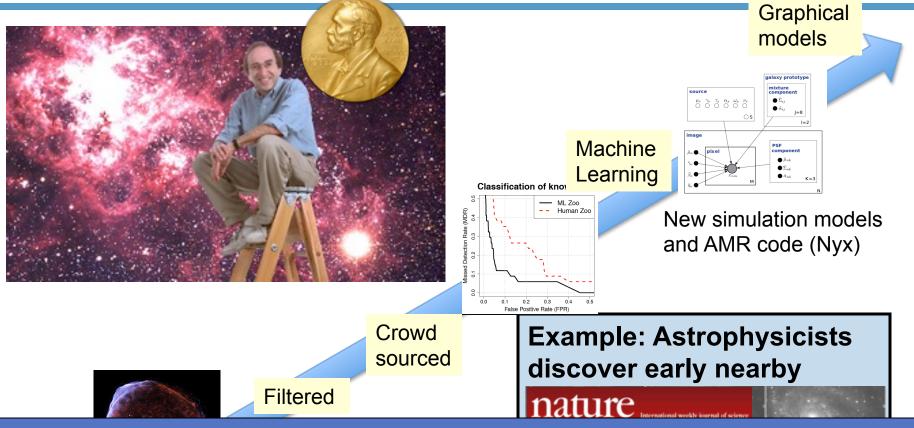
Adaptive Mesh Refinement simulates sea level impacts from melting of West Antarctic Ice Sheet



Deep learning algorithms identify and help quantify extreme events

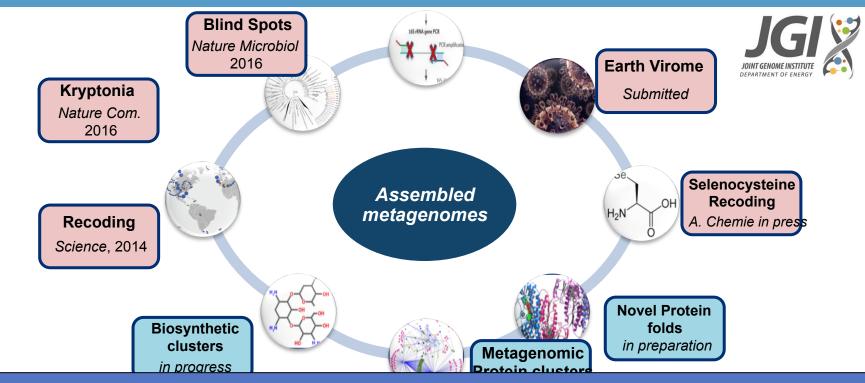
- Multimodal analysis from sensors, genomes, images...
- High performance methods and implementations
- Data-driven simulations to predict regional effects on environment and weather events

Finding smaller signals in noisy, biased data: Removing Systematic Bias in Cosmology



- Better machine learning for event detection
- Removing systematic bias in experimental data
- Simulations to interpret data; data constrain simulations

Finding structure and function in noisy data: Metagenomics data mining



- Distributed memory graph algorithms / hash tables
- Low latency interconnects; low overhead communication
- Algorithms to separate and assembly genomes
- Many-to-Many comparisons against databases

Science Trends

- Science needs (and will always need) more computing
- New science questions at the boundary of simulation and observation
- Changes to computing infrastructure
 needed for open, reproducible science





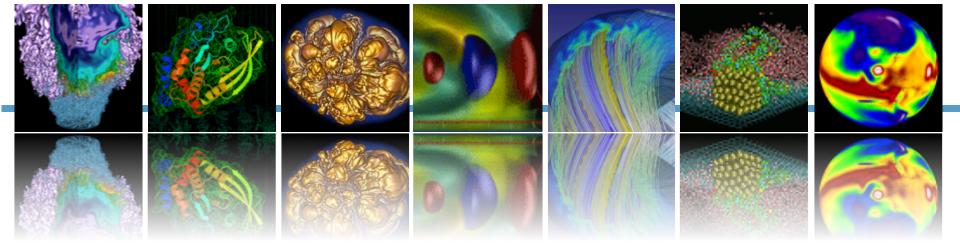
Roadmap

Science Trends

- Political Trends
- Technology Trends
- Algorithmic Challenges







The Politics of High Performance Computing





White House Announces the National Strategic Computing Initiative (NSCI)

THE WHITE HOUSE

Office of the Press Secretary

For Immediate Release

July 29, 2015

EXECUTIVE ORDER

- - - - - - -

CREATING A NATIONAL STRATEGIC COMPUTING INITIATIVE

By the authority vested in me as President by the Constitution and the laws of the United States of America, and to maximize benefits of high-performance computing (HPC) research, development, and deployment, it is hereby ordered as follows:

<u>Section 1. Policy</u>. In order to maximize the benefits of HPC for economic competitiveness and scientific discovery, the United States Government must create a coordinated Federal strategy in HPC research, development, and deployment. Investment in HPC has contributed substantially to national economic prosperity and rapidly accelerated scientific discovery. Creating and deploying technology at the leading edge is vital to advancing my Administration's priorities and spurring innovation. Accordingly, this order establishes the National Strategic Computing Initiative (NSCI). The NSCI is a

[DOE SC and NNSA] will execute a joint program focused on advanced simulation through a capable exascale computing ...

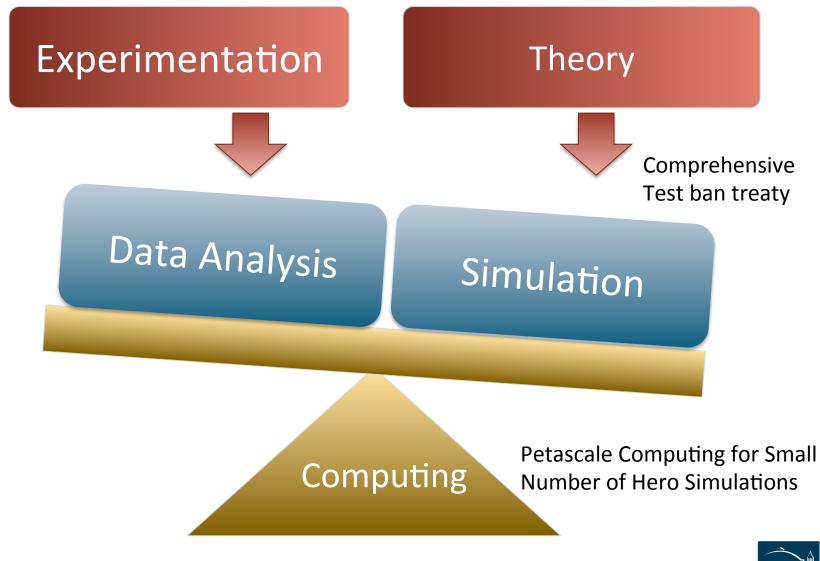
Five goals:

- 1. Create systems that can apply exaflops of computing power to exabytes of data.
- 2. Keep the United States at the forefront of HPC capabilities.
- 3. Improve HPC application developer productivity.
- 4. Make HPC readily available.
- 5. Establish hardware technology for future HPC systems.



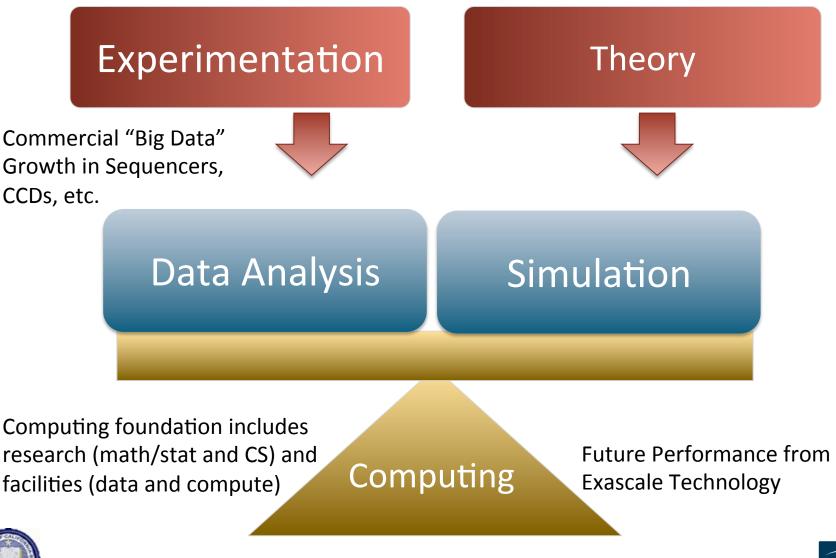


Advanced Computing: Not just for Simulation





Science Needs Computing for Both Experiments (Data) and Theory (Modeling and Simulation)

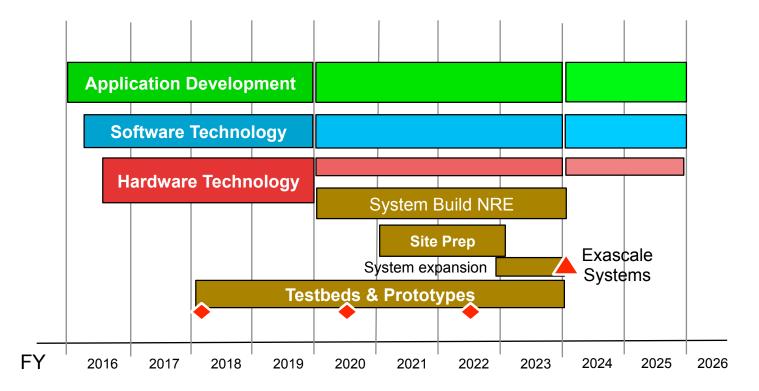




US DOE Exascale Computing Project (ECP)

The Project has three phases:

- Phase 1 R&D before DOE facilities exascale systems RFP in 2019
- Phase 2 Exascale architectures and NRE are known. Targeted development
- Phase 3 Exascale systems delivered. Meet Mission Challenges





Proposed DOE Exascale Science Problems



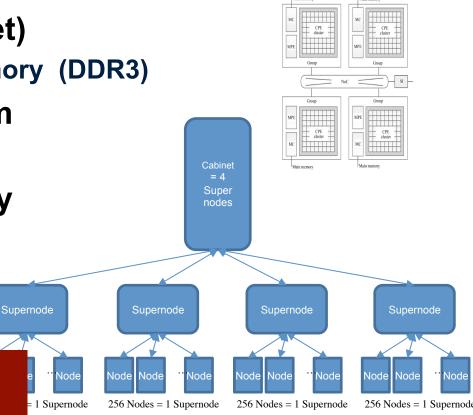
#	Site	Manufacturer	Computer	Country	Cores	Rmax [Pflops]	Power [MW]
1	National Supercomputing Center in Wuxi	NRCPC	Sunway TaihuLight NRCPC Sunway SW26010, 260C 1.45GHz	China	10,649,600	93.0	15.4
2	National University of Defense Technology	NUDT	Tianhe-2 NUDT TH-IVB-FEP, Xeon 12C 2.2GHz, IntelXeon Phi	China	3,120,000	33.9	17.8
3	Oak Ridge National Laboratory	Cray	Titan Cray XK7, Opteron 16C 2.2GHz, Gemini, NVIDIA K20x	USA	560,640	17.6	8.21
4	Lawrence Livermore National Laboratory	IBM	Sequoia BlueGene/Q, Power BQC 16C 1.6GHz, Custom	USA	1,572,864	17.2	7.89
5	RIKEN Advanced Institute for Computational Science	Fujitsu	K Computer SPARC64 VIIIfx 2.0GHz, Tofu Interconnect	Japan	795,024	10.5	12.7
6	Argonne National Laboratory	IBM	Mira BlueGene/Q, Power BQC 16C 1.6GHz, Custom	USA	786,432	8.59	3.95
7	Los Alamos NL / Sandia NL	Cray	Trinity Cray XC40, Xeon E5 16C 2.3GHz, Aries	USA	301,0564	8.10	4.23
8	Swiss National Supercomputing Centre (CSCS)	Cray	Piz Daint Cray XC30, Xeon E5 8C 2.6GHz, Aries, NVIDIA K20x	Switzer- land	115,984	6.27	2.33
9	HLRS – Stuttgart	Cray	Hazel Hen Cray XC40, Xeon E5 12C 2.5GHz, Aries	Germany	185,088	5.64	3.62
10	King Abdullah University of Science and Technology	Cray	Shaheen II Cray XC40, Xeon E5 16C 2.3GHz, Aries	Saudi Arabia	196,608	5.54	2.83

Sunway TaihuLight

- 125.4 Pflop/s theoretical peak
- SW26010 processor, 1.45 GHz
- Node = 260 Cores (1 socket)
 - 4 core groups; 32 GB memory (DDR3)
- 40,960 nodes in the system
 - 10,649,600 cores total
- 1.31 PB of primary memory
- 93 Pflop/s HPL, 74% peak
- 15.3 Mwatts (6 MF/Watt)

One piece of entire computing strategy on applications, fabs, architecture, software





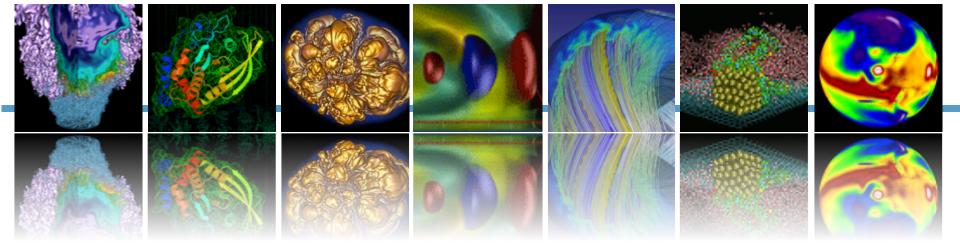


Roadmap

- Science Trends
- Political Trends
- Technology Trends
- Algorithmic Challenges







Technology Trends

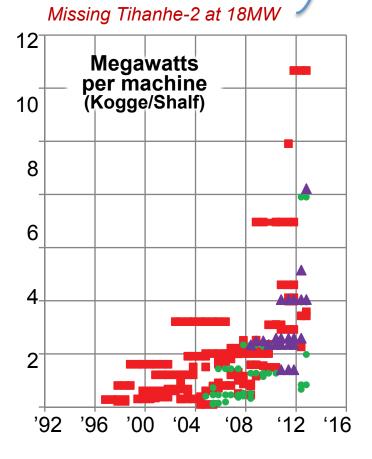




Computing is energy-constrained

At ~\$1M per MW, energy costs are substantial

- 1 petaflop in 2008 used 3 MW
- 1 exaflop in 2018 at 200 MW "usual chip scaling"



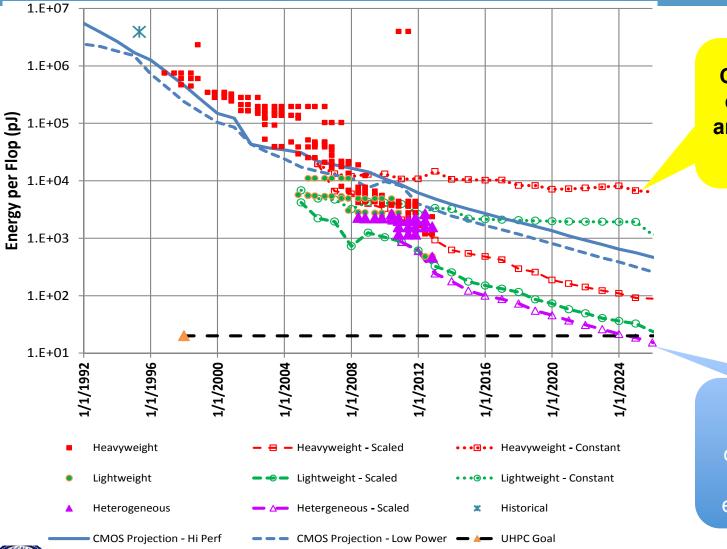
Goal: 1 Exaflop in 20 MW = 20 pJ / operation

Note: The 20 pJ / operation is

- Independent of machine size
- Independent of # cores used per application
- But "operations" need to be useful ones



Multi-Core is NOT good enough! (need to go to simpler cores)

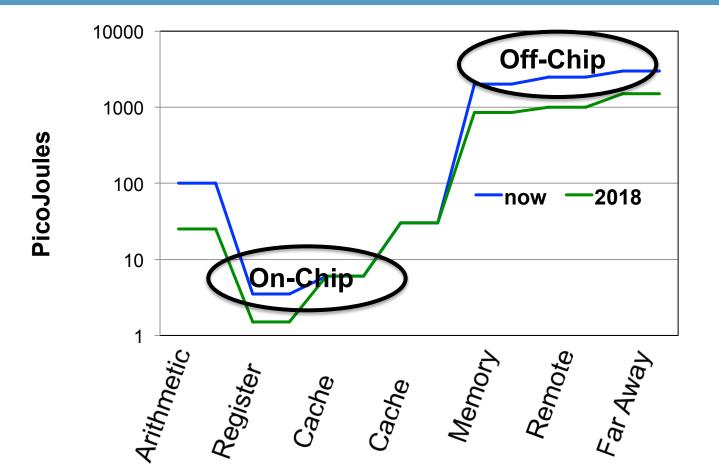


Can continue with conventional x86 architectures if you want.

Lightweight cores OR Hybrid is the only approach that crosses the exascale finish line



Communication Consumes Energy



Latency is physics; bandwidth is money, ... but overhead we can fix



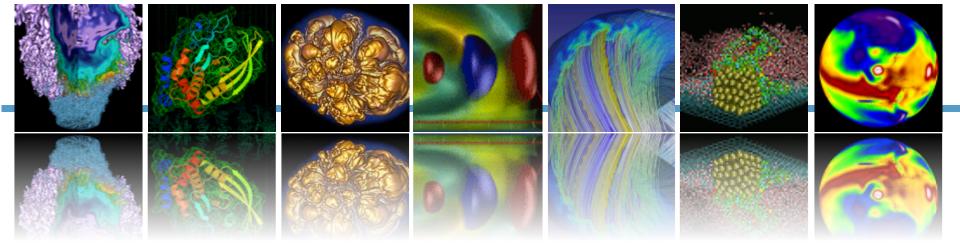
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Roadmap

- Science Trends
- Political Trends
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- Algorithmic Challenges







Algorithm Challenge: Communication





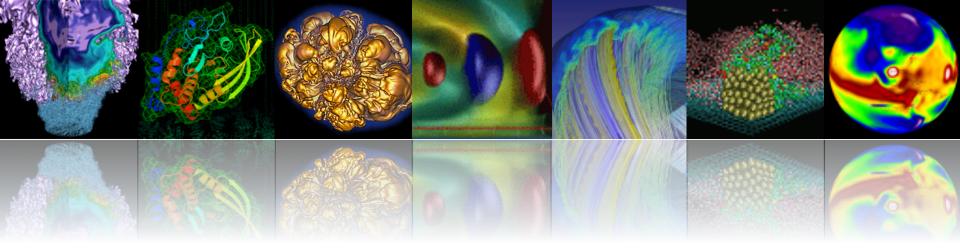
Analytics vs. Simulation Kernels:

7 Giants of Data	7 Dwarfs of Simulation
Basic statistics	Monte Carlo methods
Generalized N-Body	Particle methods
Graph-theory	Unstructured meshes
Linear algebra	Dense Linear Algebra
Optimizations	Sparse Linear Algebra
Integrations	Spectral methods
Alignment	Structured Meshes

There are some differences between data and simulation algorithms, but more similarities than differences. Some of the data algorithms use no arithmetic (genomics) or lower precision (deep learning)

BERKELEY LA





Never Waste Fast Memory

Don't get hung up on the "owner computes" rule.





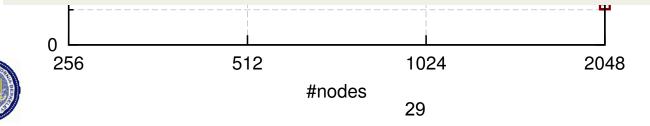
Beyond Domain Decomposition: 2.5D Matrix Multiply

- Conventional "2D algorithms" use $P^{1/2} \times P^{1/2}$ mesh and minimal memory
- New "2.5D algorithms" use (P/c)^{1/2} x (P/c)^{1/2} x c^{1/2} mesh and c-fold memory

Surprises:

- Even Matrix Multiply had room for improvement
- Idea: make copies of C matrix (as in prior 3D algorithm, but not as many)
- Result is provably optimal in communication
 Lesson: Never waste fast memory

Can we generalize for compiler writers?

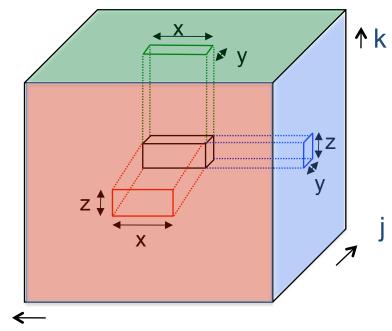




caling

Percentage of machine peak

Deconstructing 2.5D Matrix Multiply Solomonick & Demmel



- Tiling the iteration space
- 2D algorithm: never chop k dim
- 2.5 or 3D: Assume + is associative; chop k, which is → replication of C matrix

Matrix Multiplication code has a 3D iteration space Each point in the space is a constant computation (*/+)

```
for i
for j
for k
C[i,j] ... A[i,k] ... B[k,j] ...
```

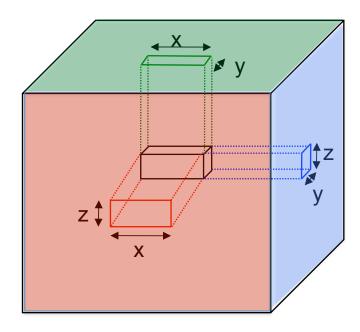


i



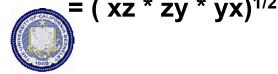
Lower Bound Idea on C = A*B

Iromy, Toledo, Tiskin



Cubes in black box with side lengths x, y and z = Volume of black box = x*y*z

$$= (#A_{\Box}s * #B_{\Box}s * #C_{\Box}s)^{1/2}$$



(i,k) is in **"A shadow"** if (i,j,k) in 3D set (j,k) is in **"B shadow"** if (i,j,k) in 3D set (i,j) is in **"C shadow"** if (i,j,k) in 3D set

Thm (Loomis & Whitney, 1949) # cubes in 3D set = Volume of 3D set

≤ (area(A shadow) * area(B shadow) *

area(C shadow)) ^{1/2}



Generalizing Communication Lower Bounds and Optimal Algorithms

- For serial matmul, we know #words_moved = Ω (n³/M^{1/2}), attained by tile sizes M^{1/2} x M^{1/2}
- Thm (Christ,Demmel,Knight,Scanlon,Yelick): For any program that "smells like" nested loops, accessing arrays with subscripts that are linear functions of the loop indices

 $\#words_moved = \Omega$ ($\#iterations/M^e$)

for some e we can determine

- Thm (C/D/K/S/Y): Under some assumptions, we can determine the optimal tiles sizes
 - E.g., index expressions are just subsets of indices
- Long term goal: All compilers should generate communication optimal code from nested loops





Implications for Arithmetic

ſ	 Much of the work on compilers is based on owner-computes
X +=	 For MM: Divide C into chunks, schedule movement of A/B
X +=	 Data-driven domain decomposition partitions data; but we can partition work instead
x +=	 Ways to compute C "pencil"
	1. Serially
x +=	2. Parallel reduction Standard vectorization trick
	3. Parallel asynchronous (atomic) updates
	4. Or any hybrid of these
\downarrow	• For what types / operators does this work?

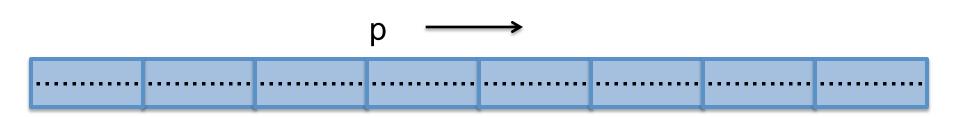
Using x for C[i,j] here

- "+" is associative for 1,2 rest of RHS is "simple"



– and commutative for 3

Traditional (Naïve n²) Nbody Algorithm (using a 1D decomposition)

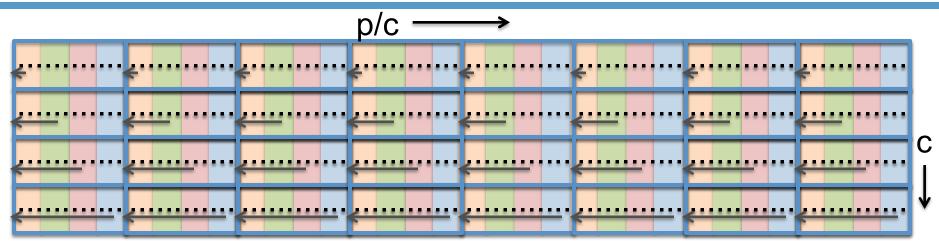


- Given n particles and p processors, size M memory
- Each processor has n/p particles
- Algorithm: shift copy of particles to the left p times, calculating all pairwise forces
- Computation cost: n²/p
- Communication cost: O(p) messages, O(n) words





Communication Avoiding Version (using a "1.5D" decomposition)



- Divide p into c groups. Replicate particles within group. – First row responsible for updating all by orange, second all by green,...
- Algorithm: shift copy of n/(p*c) particles to the left
 - Combine with previous data before passing further level (log steps)
- Reduce across c to produce final value for each particle
- Total Computation: O(n²/p);
- Total Communication: O(log(p/c) + log c) messages,

O(n*(c/p+1/c)) words

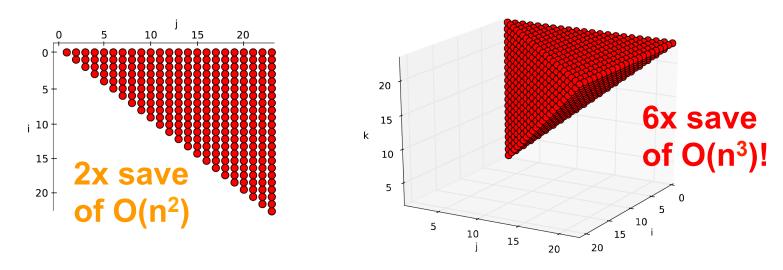


Limit: $c \le p^{1/2}$



Challenge: Symmetry & Load Balance

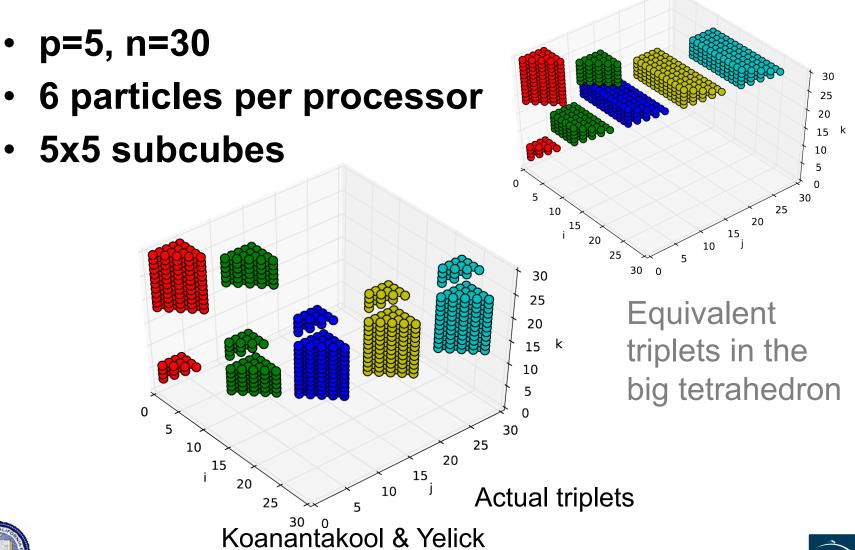
- Force symmetry (f_{ij} = -f_{ji}) saves computation
- 2-body force matrix vs 3-body force cube



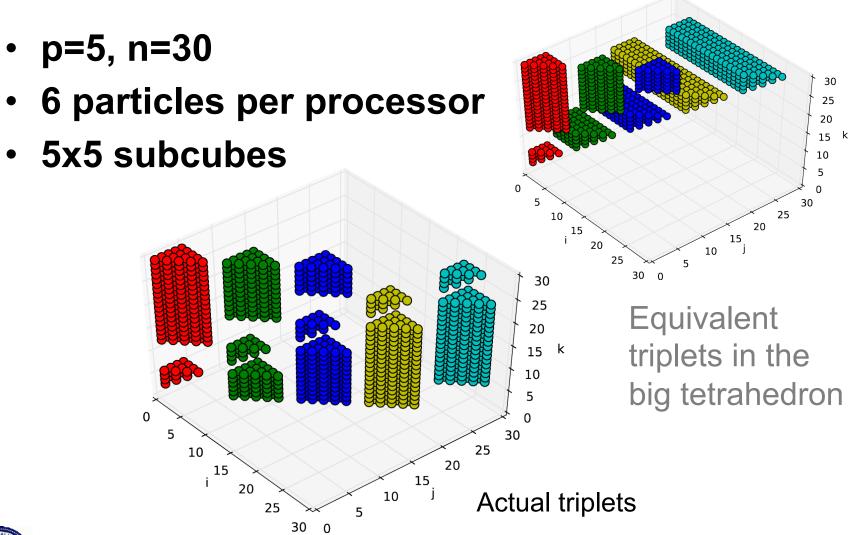
How to divide work equally?





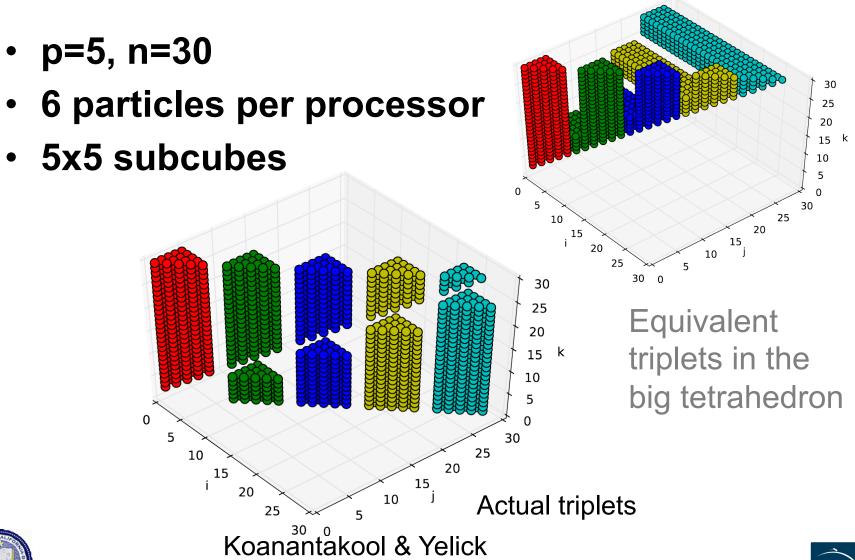




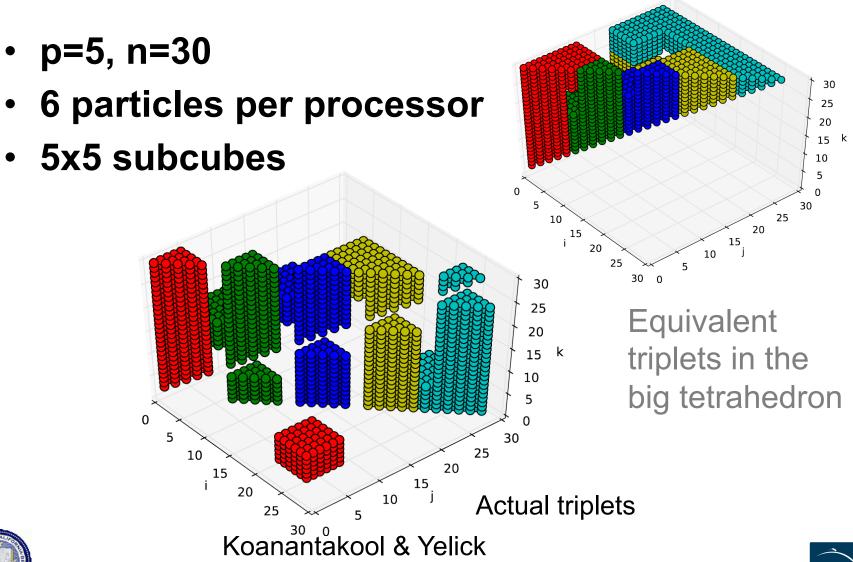








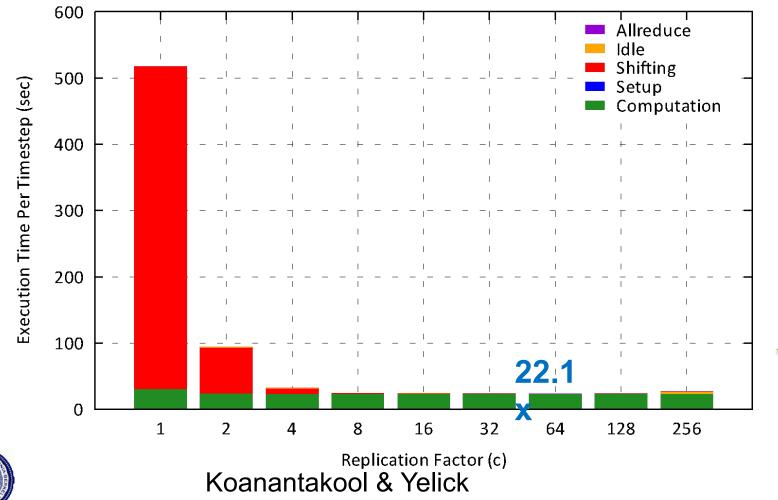






3-Way N-Body Speedup

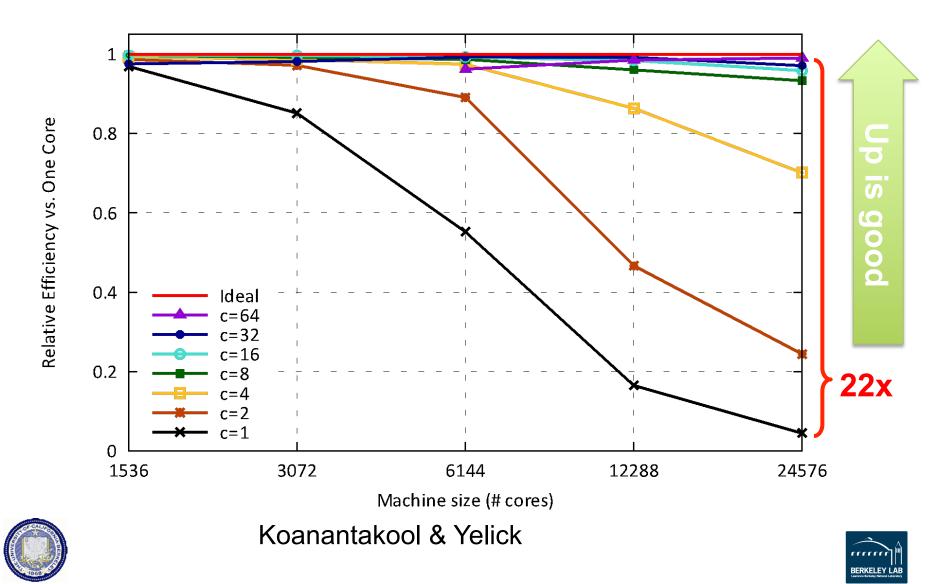




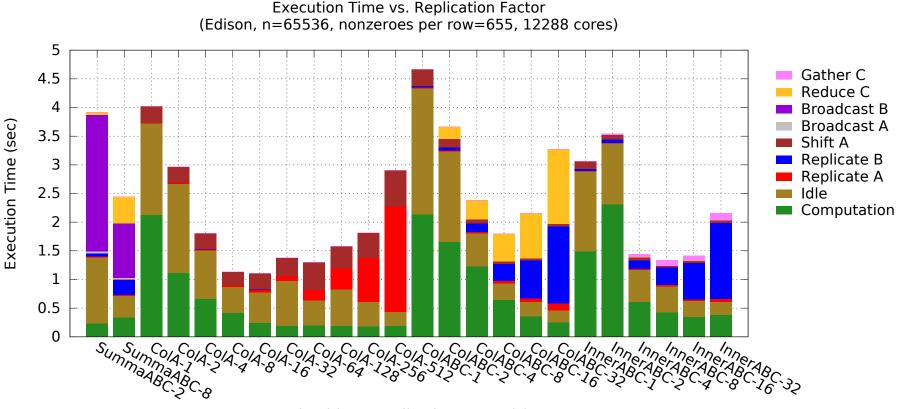
Down is

<u>gooc</u>

Strong Scaling of .5D Algorithns



Sparse-Dense Matrix Multiply Too!



Algorithm - Replication Factor (c)

Variety of algorithms that divide in or 2 dimensions



Koanantakool & Yelick



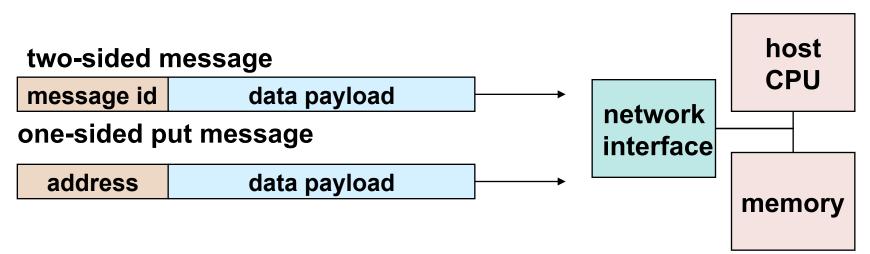
Have We Seen this Idea Before?

- These algorithms also maximize parallelism beyond "domain decomposition"
 - SIMD machine days
- Automation depends on associative operator for updates (e.g., M. Wolfe)
- Also used for "synchronization avoidance" in Particle-in-Cell code (Madduri, Su, Oliker, Yelick)
 - Replicate and reduce optimization given p copies
 - Useful on vectors / GPUs





Avoid Latency and Implicit Synchronization in Communication



- Two-sided message passing (e.g., send/receive in MPI) requires matching a send with a receive to identify memory address to put data
 - Couples data transfer with synchronization, which is sometimes what you want
- Using global address space decouples synchronization
 - Pay for what you need!

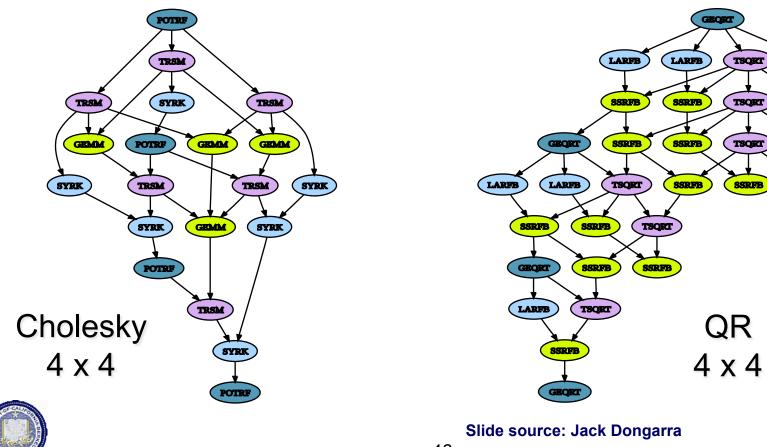




Avoid Synchronization from Applications

Computations as DAGs

View parallel executions as the directed acyclic graph of the computation





LARFB

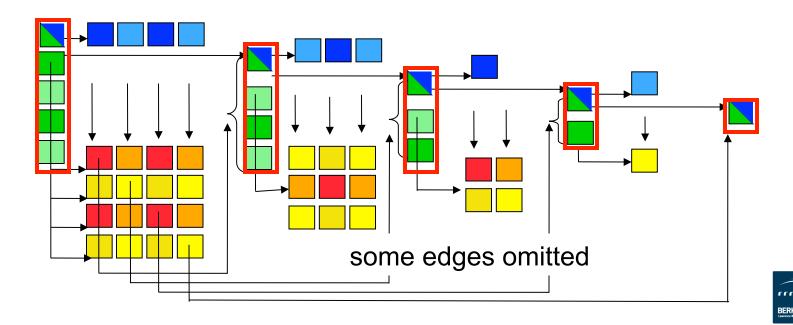
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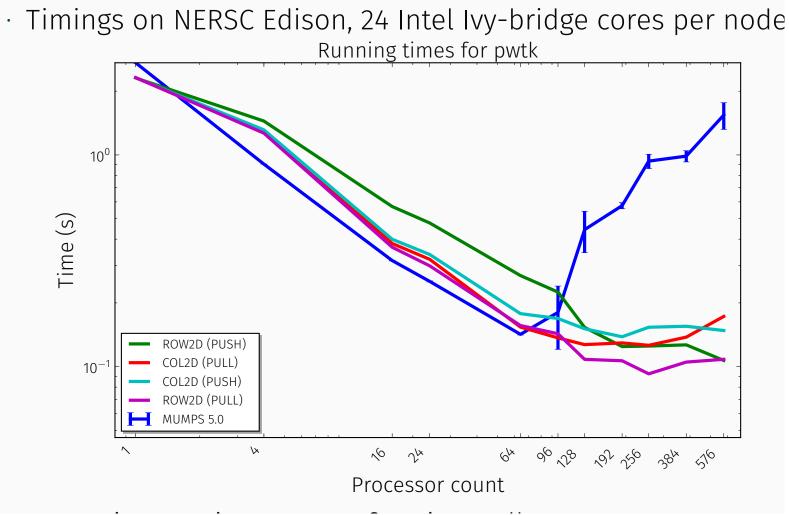
Event Driven LU in UPC

- Assignment of work is static; schedule is dynamic
- Ordering needs to be imposed on the schedule
 Critical path operation: Panel Factorization
- General issue: dynamic scheduling in partitioned memory
 - Can deadlock in memory allocation
 - "memory constrained" lookahead





Sparse Cholesky





Fan-both algorithm by Jacquelin & Ng, in UPC++



OpenMP Loop Parallelism is the Wrong Level

- OpenMP is popular for its convenient loop parallelism
- Loop level parallelism is too coarse and too fine:
 - Too coarse: Implicit synchronization between loops limits parallelism and adds overhead
 - Too fine: Need to create larger chunks of serial work by combining across loops (fusion) to minimize data movement

```
!$OMP PARALLEL DO
DO I=2,N
B(I) = (A(I) + A(I-1)) / 2.0
ENDDO
!$OMP END PARALLEL DO
```





Sources of Unnecessary Synchronization

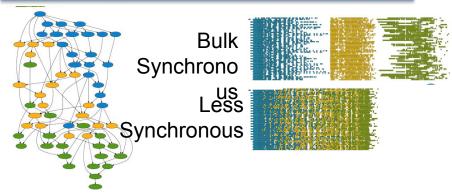
Loop Parallelism

!\$OMP PARALLEL DO DO I=2,N B(I) = (A(I) + A(I-1)) / 2.0 ENDDO !\$OMP END PARALLEL DO

"Simple" OpenMP parallelism implicitly synchronized between loops

Libraries		
Analysi s	% barriers	Speedu p
Auto	42%	13%
Guided IWChem: most Corvette)	63% t of barriers are u	14% nnecessary

Abstraction



LAPACK: removing barriers ~2x faster (PLASMA)

Accelerator Offload

!\$acc data copyin(cix,ci1,ci2,ci3,ci4,ci5,ci6,ci7,ci8,ci9,ci10,ci11,& !\$acc& ci12,ci13,ci14,r,b,uxyz,cell,rho,grad,index_max,index,& !\$acc& ciy, ciz, wet, np, streaming sbuf1, & !\$acc& streaming sbuf1,streaming sbuf2,streaming sbuf4,streaming sbuf5,& !\$acc& streaming_sbuf7s,streaming_sbuf8s,streaming_sbuf9n,streaming_sbuf10s,& !\$acc& streaming sbufl1n, streaming sbufl2n, streaming sbufl3s, streaming sbufl4n, & !\$acc& streaming sbuf7e, streaming sbuf8w, streaming sbuf9e, streaming sbuf10e, & !\$acc& streaming sbufllw, streaming sbufl2e, streaming sbufl3w, streaming sbufl4w, & !\$acc& streaming_rbuf1, streaming_rbuf2, streaming_rbuf4, streaming_rbuf5, & !\$acc& streaming rbuf7n, streaming rbuf8n, streaming rbuf9s, streaming rbuf10n, & !\$acc& streaming rbuflls, streaming rbufl2s, streaming rbufl3n, streaming rbufl4s, & !\$acc& streaming rbuf7w, streaming rbuf8e, streaming rbuf9w, streaming rbuf10w, & !\$acc& streaming rbuflle, streaming rbufl2w, streaming rbufl3e, streaming rbufl4e, send e, send w, send n, send s, recv e, recv w, recv n, recv s)

The transfer between host and GPU can be slow and cumbersome, and may (if not careful) get synchronized



Thanks to many Collaborators!

- Jim Demmel
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- Carelton Miyamoto
- Mani Narayanan
- Rajesh Nishtala Steve
- Steinberg Jimmy Su
- Randi Thomas
- Noah Treuhaft
- Chih-Po Wen
- Siu-Man Yau



