# **Linear Dimensionality Reduction**

Practical Machine Learning (CS294-34) September 24, 2009

Percy Liang

# Lots of high-dimensional data...



face images

Zambian President Levy Mwanawasa has won a second term in office in an election his challenger Michael Sata accused him of rigging, official results showed on Monday. According to media reports. a pair of hackers said on Saturday that the Firefox Web browser, commonly perceived as the safer and customizable more alternative to market leader Internet Explorer, is critically flawed. А presentation on the flaw was shown during the ToorCon hacker conference in San Diego.

#### documents



MEG readings



gene expression data

Why do dimensionality reduction?

• Computational: compress data  $\Rightarrow$  time/space efficiency

Why do dimensionality reduction?

- Computational: compress data  $\Rightarrow$  time/space efficiency
- Statistical: fewer dimensions  $\Rightarrow$  better generalization

Why do dimensionality reduction?

- Computational: compress data  $\Rightarrow$  time/space efficiency
- Statistical: fewer dimensions  $\Rightarrow$  better generalization
- Visualization: understand structure of data

Why do dimensionality reduction?

- Computational: compress data  $\Rightarrow$  time/space efficiency
- Statistical: fewer dimensions  $\Rightarrow$  better generalization
- Visualization: understand structure of data
- Anomaly detection: describe normal data, detect outliers

Why do dimensionality reduction?

- Computational: compress data  $\Rightarrow$  time/space efficiency
- Statistical: fewer dimensions  $\Rightarrow$  better generalization
- Visualization: understand structure of data
- Anomaly detection: describe normal data, detect outliers

Dimensionality reduction in this course:

- Linear methods (this week)
- Clustering (last week)
- Feature selection (next week)
- Nonlinear methods (later)

 $\bullet$  Prediction  $\mathbf{x} \rightarrow \mathbf{y}:$  classification, regression

• Prediction  $\mathbf{x} \rightarrow \mathbf{y}$ : classification, regression Applications: face recognition, gene expression prediction Techniques: kNN, SVM, least squares (+ dimensionality reduction preprocessing)

- Prediction  $\mathbf{x} \rightarrow \mathbf{y}$ : classification, regression Applications: face recognition, gene expression prediction Techniques: kNN, SVM, least squares (+ dimensionality reduction preprocessing)
- $\bullet$  Structure discovery  $\mathbf{x} \to \mathbf{z}$ : find an alternative representation  $\mathbf{z}$  of data  $\mathbf{x}$

- Prediction  $\mathbf{x} \rightarrow \mathbf{y}$ : classification, regression Applications: face recognition, gene expression prediction Techniques: kNN, SVM, least squares (+ dimensionality reduction preprocessing)
- Structure discovery x → z: find an alternative representation z of data x Applications: visualization Techniques: clustering, linear dimensionality reduction

- Prediction  $\mathbf{x} \rightarrow \mathbf{y}$ : classification, regression Applications: face recognition, gene expression prediction Techniques: kNN, SVM, least squares (+ dimensionality reduction preprocessing)
- Structure discovery x → z: find an alternative representation z of data x
   Applications: visualization
   Techniques: clustering, linear dimensionality reduction
- Density estimation  $p(\mathbf{x})$ : model the data

- Prediction  $\mathbf{x} \rightarrow \mathbf{y}$ : classification, regression Applications: face recognition, gene expression prediction Techniques: kNN, SVM, least squares (+ dimensionality reduction preprocessing)
- Structure discovery x → z: find an alternative representation z of data x Applications: visualization Techniques: clustering, linear dimensionality reduction
- Density estimation  $p(\mathbf{x})$ : model the data Applications: anomaly detection, language modeling Techniques: clustering, linear dimensionality reduction

# Basic idea of linear dimensionality reduction



Represent each face as a high-dimensional vector  $\mathbf{x} \in \mathbb{R}^{361}$ 

# Basic idea of linear dimensionality reduction



Represent each face as a high-dimensional vector  $\mathbf{x} \in \mathbb{R}^{361}$ 



 $\mathbf{x} \in \mathbb{R}^{361}$  $\begin{vmatrix} \mathbf{z} = \mathbf{U}^\top \mathbf{x} \\ \mathbf{z} \in \mathbb{R}^{10} \end{vmatrix}$ 

# Basic idea of linear dimensionality reduction



Represent each face as a high-dimensional vector  $\mathbf{x} \in \mathbb{R}^{361}$ 



 $\mathbf{x} \in \mathbb{R}^{361}$  $\begin{vmatrix} \mathbf{z} = \mathbf{U}^\top \mathbf{x} \\ \mathbf{z} \in \mathbb{R}^{10} \end{vmatrix}$ 

How do we choose  ${\bf U}?$ 

# Outline

- Principal component analysis (PCA)
  - Basic principles
  - Case studies
  - Kernel PCA
  - Probabilistic PCA
- Canonical correlation analysis (CCA)
- Fisher discriminant analysis (FDA)
- Summary

# Roadmap



- Principal component analysis (PCA)
  - Basic principles
  - Case studies
  - Kernel PCA
  - Probabilistic PCA
- Canonical correlation analysis (CCA)
- Fisher discriminant analysis (FDA)
- Summary

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

$$\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \cdots \mathbf{x}_n \\ | & | \end{pmatrix} \in \mathbb{R}^{d \times n}$$

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

$$\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \cdots \mathbf{x}_n \\ | & | \end{pmatrix} \in \mathbb{R}^{d imes n}$$

Want to reduce dimensionality from d to k

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

$$\mathbf{X} = \begin{pmatrix} ert & ert \ \mathbf{x}_1 \cdots \mathbf{x}_n \ ert & ert \end{pmatrix} \in \mathbb{R}^{d imes n}$$

Want to reduce dimensionality from d to kChoose k directions  $\mathbf{u}_1, \ldots, \mathbf{u}_k$ 

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

$$\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \cdots \mathbf{x}_n \\ | & | \end{pmatrix} \in \mathbb{R}^{d \times n}$$

Want to reduce dimensionality from d to kChoose k directions  $\mathbf{u}_1, \ldots, \mathbf{u}_k$ 

$$\mathbf{U} = \left(egin{array}{ccc} ert & ert \ \mathbf{u}_1 & \cdots & \mathbf{u}_k \ ert & ert \end{array}
ight) \in \mathbb{R}^{d imes k}$$

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

$$\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \cdots \mathbf{x}_n \\ | & | \end{pmatrix} \in \mathbb{R}^{d \times n}$$

Want to reduce dimensionality from  $d\ {\rm to}\ k$ 

Choose k directions  $\mathbf{u}_1, \ldots, \mathbf{u}_k$ 

$$\mathbf{U} = \left(egin{array}{ccc} ert & ert \ \mathbf{u}_1 & \mathbf{u}_k \ ert & ert \end{array}
ight) \in \mathbb{R}^{d imes k}$$

For each  $\mathbf{u}_j$ , compute "similarity"  $z_j = \mathbf{u}_j^\top \mathbf{x}$ 

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

$$\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \cdots \mathbf{x}_n \\ | & | \end{pmatrix} \in \mathbb{R}^{d \times n}$$

Want to reduce dimensionality from  $d\ {\rm to}\ k$ 

Choose k directions  $\mathbf{u}_1, \ldots, \mathbf{u}_k$ 

$$\mathbf{U} = \left(egin{array}{ccc} ert & ert \ \mathbf{u}_1 \cdots \mathbf{u}_k \ ert & ert \end{array}
ight) \in \mathbb{R}^{d imes k}$$

For each  $\mathbf{u}_j$ , compute "similarity"  $z_j = \mathbf{u}_j^\top \mathbf{x}$ Project  $\mathbf{x}$  down to  $\mathbf{z} = (z_1, \dots, z_k)^\top = \mathbf{U}^\top \mathbf{x}$ 

Given n data points in d dimensions:  $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbb{R}^d$ 

$$\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \cdots \mathbf{x}_n \\ | & | \end{pmatrix} \in \mathbb{R}^{d \times n}$$

Want to reduce dimensionality from  $d\ {\rm to}\ k$ 

Choose k directions  $\mathbf{u}_1, \ldots, \mathbf{u}_k$ 

$$\mathbf{U} = \begin{pmatrix} | & | \\ \mathbf{u}_1 \cdots \mathbf{u}_k \\ | & | \end{pmatrix} \in \mathbb{R}^{d \times k}$$

For each  $\mathbf{u}_j$ , compute "similarity"  $\mathbf{z}_j = \mathbf{u}_j^\top \mathbf{x}$ Project  $\mathbf{x}$  down to  $\mathbf{z} = (\mathbf{z}_1, \dots, \mathbf{z}_k)^\top = \mathbf{U}^\top \mathbf{x}$ How to choose  $\mathbf{U}$ ?

**U** serves two functions:

• Encode:  $\mathbf{z} = \mathbf{U}^{\top}\mathbf{x}$ ,  $z_j = \mathbf{u}_j^{\top}\mathbf{x}$ 

**U** serves two functions:

- Encode:  $\mathbf{z} = \mathbf{U}^{\top}\mathbf{x}, \quad z_j = \mathbf{u}_j^{\top}\mathbf{x}$
- Decode:  $\tilde{\mathbf{x}} = \mathbf{U}\mathbf{z} = \sum_{j=1}^{k} z_j \mathbf{u}_j$

**U** serves two functions:

• Encode:  $\mathbf{z} = \mathbf{U}^{\top}\mathbf{x}$ ,  $z_j = \mathbf{u}_j^{\top}\mathbf{x}$ 

• Decode: 
$$\tilde{\mathbf{x}} = \mathbf{U}\mathbf{z} = \sum_{j=1}^{k} z_j \mathbf{u}_j$$

Want reconstruction error  $\|\mathbf{x} - \tilde{\mathbf{x}}\|$  to be small

**U** serves two functions:

• Encode:  $\mathbf{z} = \mathbf{U}^{\top}\mathbf{x}$ ,  $z_j = \mathbf{u}_j^{\top}\mathbf{x}$ 

• Decode: 
$$\tilde{\mathbf{x}} = \mathbf{U}\mathbf{z} = \sum_{j=1}^{k} z_j \mathbf{u}_j$$

Want reconstruction error  $\|\mathbf{x} - \tilde{\mathbf{x}}\|$  to be small

Objective: minimize total squared reconstruction error



Empirical distribution: uniform over  $\mathbf{x}_1, \ldots, \mathbf{x}_n$ 

Empirical distribution: uniform over  $\mathbf{x}_1, \ldots, \mathbf{x}_n$ Expectation (think sum over data points):

$$\hat{\mathbb{E}}[f(\mathbf{x})] = \frac{1}{n} \sum_{i=1}^{n} f(\mathbf{x}_i)$$

Empirical distribution: uniform over  $\mathbf{x}_1, \ldots, \mathbf{x}_n$ Expectation (think sum over data points):

$$\hat{\mathbb{E}}[f(\mathbf{x})] = \frac{1}{n} \sum_{i=1}^{n} f(\mathbf{x}_i)$$

Variance (think sum of squares if centered):

$$\widehat{\operatorname{var}}[f(\mathbf{x})] + (\widehat{\mathbb{E}}[f(\mathbf{x})])^2 = \widehat{\mathbb{E}}[f(\mathbf{x})^2] = \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i)^2$$

Empirical distribution: uniform over  $\mathbf{x}_1, \ldots, \mathbf{x}_n$ Expectation (think sum over data points):

$$\hat{\mathbb{E}}[f(\mathbf{x})] = \frac{1}{n} \sum_{i=1}^{n} f(\mathbf{x}_i)$$

Variance (think sum of squares if centered):

$$\widehat{\operatorname{var}}[f(\mathbf{x})] + (\widehat{\mathbb{E}}[f(\mathbf{x})])^2 = \widehat{\mathbb{E}}[f(\mathbf{x})^2] = \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i)^2$$

Assume data is centered:  $\hat{\mathbb{E}}[\mathbf{x}] = 0$ 

Empirical distribution: uniform over  $\mathbf{x}_1, \ldots, \mathbf{x}_n$ Expectation (think sum over data points):

$$\hat{\mathbb{E}}[f(\mathbf{x})] = \frac{1}{n} \sum_{i=1}^{n} f(\mathbf{x}_i)$$

Variance (think sum of squares if centered):

$$\widehat{\operatorname{var}}[f(\mathbf{x})] + (\widehat{\mathbb{E}}[f(\mathbf{x})])^2 = \widehat{\mathbb{E}}[f(\mathbf{x})^2] = \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i)^2$$

Assume data is centered:  $\hat{\mathbb{E}}[\mathbf{x}] = 0$  (what's  $\hat{\mathbb{E}}[\mathbf{U}^{\top}\mathbf{x}]$ ?)

Empirical distribution: uniform over  $\mathbf{x}_1, \ldots, \mathbf{x}_n$ Expectation (think sum over data points):

$$\hat{\mathbb{E}}[f(\mathbf{x})] = \frac{1}{n} \sum_{i=1}^{n} f(\mathbf{x}_i)$$

Variance (think sum of squares if centered):

$$\widehat{\operatorname{var}}[f(\mathbf{x})] + (\widehat{\mathbb{E}}[f(\mathbf{x})])^2 = \widehat{\mathbb{E}}[f(\mathbf{x})^2] = \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i)^2$$

Assume data is centered:  $\hat{\mathbb{E}}[\mathbf{x}] = 0$  (what's  $\hat{\mathbb{E}}[\mathbf{U}^{\top}\mathbf{x}]$ ?) Objective: maximize variance of projected data  $\max_{\mathbf{U}\in\mathbb{R}^{d\times k},\mathbf{U}^{\top}\mathbf{U}=I} \hat{\mathbb{E}}[\|\mathbf{U}^{\top}\mathbf{x}\|^2]$








Take expectations; note rotation  $\mathbf{U}$  doesn't affect length:  $\hat{\mathbb{E}}[\|\mathbf{x}\|^2] = \hat{\mathbb{E}}[\|\mathbf{U}^{\top}\mathbf{x}\|^2] + \hat{\mathbb{E}}[\|\mathbf{x} - \mathbf{U}\mathbf{U}^{\top}\mathbf{x}\|^2]$ 



Take expectations; note rotation  $\mathbf{U}$  doesn't affect length:  $\hat{\mathbb{E}}[\|\mathbf{x}\|^2] = \hat{\mathbb{E}}[\|\mathbf{U}^{\top}\mathbf{x}\|^2] + \hat{\mathbb{E}}[\|\mathbf{x} - \mathbf{U}\mathbf{U}^{\top}\mathbf{x}\|^2]$ Minimize reconstruction error  $\leftrightarrow$  Maximize captured variance



Input data:  $\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \dots \mathbf{x}_n \\ | & | \end{pmatrix}$ 



Objective: maximize variance of projected data

Input data:  $\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \dots \mathbf{x}_n \\ | & | \end{pmatrix}$ 



Objective: maximize variance of projected data

$$= \max_{\|\mathbf{u}\|=1} \mathbb{\hat{E}}[(\mathbf{u}^{\top}\mathbf{x})^2]$$

Input data:  $\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \dots \mathbf{x}_n \\ | & | \end{pmatrix}$ 



Objective: maximize variance of projected data

$$= \max_{\|\mathbf{u}\|=1} \hat{\mathbb{E}}[(\mathbf{u}^{\top}\mathbf{x})^2]$$
$$= \max_{\|\mathbf{u}\|=1} \frac{1}{n} \sum_{i=1}^n (\mathbf{u}^{\top}\mathbf{x}_i)^2$$

Input data:

$$\mathbf{X} = \left(egin{array}{cccc} ert & ert & ert \ \mathbf{x}_1 \dots \ \mathbf{x}_n \ ert & ert \end{array}
ight)$$



Objective: maximize variance of projected data

$$= \max_{\|\mathbf{u}\|=1} \hat{\mathbb{E}}[(\mathbf{u}^{\top}\mathbf{x})^2]$$
$$= \max_{\|\mathbf{u}\|=1} \frac{1}{n} \sum_{i=1}^n (\mathbf{u}^{\top}\mathbf{x}_i)^2$$
$$= \max_{\|\mathbf{u}\|=1} \frac{1}{n} \|\mathbf{u}^{\top}\mathbf{X}\|^2$$

Input data:  $\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \dots \mathbf{x}_n \\ | & | \end{pmatrix}$ 



Objective: maximize variance of projected data

$$= \max_{\|\mathbf{u}\|=1} \hat{\mathbb{E}}[(\mathbf{u}^{\top}\mathbf{x})^{2}]$$
$$= \max_{\|\mathbf{u}\|=1} \frac{1}{n} \sum_{i=1}^{n} (\mathbf{u}^{\top}\mathbf{x}_{i})^{2}$$
$$= \max_{\|\mathbf{u}\|=1} \frac{1}{n} \|\mathbf{u}^{\top}\mathbf{X}\|^{2}$$
$$= \max_{\|\mathbf{u}\|=1} \mathbf{u}^{\top} \left(\frac{1}{n}\mathbf{X}\mathbf{X}^{\top}\right) \mathbf{u}$$

Input data: = m $\|\mathbf{u}\|$  $\mathbf{X} = \begin{pmatrix} | & | & | \\ \mathbf{x}_1 \dots \mathbf{x}_n \\ | & | \end{pmatrix} = m$  $\|\mathbf{u}\|$ 



Input data:  $\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \dots \mathbf{x}_n \\ | & | \end{pmatrix}$  Objective: maximize variance of projected data

$$= \max_{\|\mathbf{u}\|=1} \hat{\mathbb{E}}[(\mathbf{u}^{\top}\mathbf{x})^{2}]$$

$$= \max_{\|\mathbf{u}\|=1} \frac{1}{n} \sum_{i=1}^{n} (\mathbf{u}^{\top}\mathbf{x}_{i})^{2}$$

$$= \max_{\|\mathbf{u}\|=1} \frac{1}{n} \|\mathbf{u}^{\top}\mathbf{X}\|^{2}$$

$$= \max_{\|\mathbf{u}\|=1} \mathbf{u}^{\top} \left(\frac{1}{n}\mathbf{X}\mathbf{X}^{\top}\right) \mathbf{u}$$

$$= \text{largest eigenvalue of } C \stackrel{\text{def}}{=} \frac{1}{n} \mathbf{X}\mathbf{X}^{\top}$$

(C is covariance matrix of data)

Principal component analysis (PCA) / Basic principles

 $n_{i}$ 

## How many principal components?

- Similar to question of "How many clusters?"
- Magnitude of eigenvalues indicate fraction of variance captured.

## How many principal components?

- Similar to question of "How many clusters?"
- Magnitude of eigenvalues indicate fraction of variance captured.
- Eigenvalues on a face image dataset:



# How many principal components?

- Similar to question of "How many clusters?"
- Magnitude of eigenvalues indicate fraction of variance captured.
- Eigenvalues on a face image dataset:



- Eigenvalues typically drop off sharply, so don't need that many.
- Of course variance isn't everything...

# Computing PCA

Method 1: eigendecomposition U are eigenvectors of covariance matrix  $C = \frac{1}{n} \mathbf{X} \mathbf{X}^{\top}$ Computing C already takes  $O(nd^2)$  time (very expensive)

# Computing PCA

Method 1: eigendecomposition U are eigenvectors of covariance matrix  $C = \frac{1}{n} \mathbf{X} \mathbf{X}^{\top}$ Computing C already takes  $O(nd^2)$  time (very expensive) Method 2: singular value decomposition (SVD) Find  $\mathbf{X} = \mathbf{U}_{d \times d} \Sigma_{d \times n} \mathbf{V}_{n \times n}^{\top}$ where  $\mathbf{U}^{\top} \mathbf{U} = I_{d \times d}$ ,  $\mathbf{V}^{\top} \mathbf{V} = I_{n \times n}$ ,  $\Sigma$  is diagonal Computing top k singular vectors takes only O(ndk)

# Computing PCA

Method 1: eigendecomposition U are eigenvectors of covariance matrix  $C = \frac{1}{n} \mathbf{X} \mathbf{X}^{\top}$ Computing C already takes  $O(nd^2)$  time (very expensive) Method 2: singular value decomposition (SVD) Find  $\mathbf{X} = \mathbf{U}_{d \times d} \Sigma_{d \times n} \mathbf{V}_{n \times n}^{\top}$ where  $\mathbf{U}^{\top}\mathbf{U} = I_{d \times d}$ ,  $\mathbf{V}^{\top}\mathbf{V} = I_{n \times n}$ ,  $\Sigma$  is diagonal Computing top k singular vectors takes only O(ndk)Relationship between eigendecomposition and SVD: Left singular vectors are principal components ( $C = \mathbf{U}\Sigma^2\mathbf{U}^+$ )

# Roadmap



- Principal component analysis (PCA)
  - Basic principles
  - Case studies
  - Kernel PCA
  - Probabilistic PCA
- Canonical correlation analysis (CCA)
- Fisher discriminant analysis (FDA)
- Summary

# Eigen-faces [Turk and Pentland, 1991]

- $\bullet$  d = number of pixels
- Each  $\mathbf{x}_i \in \mathbb{R}^d$  is a face image
- $\mathbf{x}_{ji}$  = intensity of the *j*-th pixel in image *i*

# Eigen-faces [Turk and Pentland, 1991]

- d =number of pixels
- Each  $\mathbf{x}_i \in \mathbb{R}^d$  is a face image
- $\mathbf{x}_{ji}$  = intensity of the *j*-th pixel in image *i*



# Eigen-faces [Turk and Pentland, 1991]

- $\bullet$  d = number of pixels
- Each  $\mathbf{x}_i \in \mathbb{R}^d$  is a face image
- $\mathbf{x}_{ji}$  = intensity of the *j*-th pixel in image *i*



Idea:  $\mathbf{z}_i$  more "meaningful" representation of *i*-th face than  $\mathbf{x}_i$ Can use  $\mathbf{z}_i$  for nearest-neighbor classification Much faster: O(dk + nk) time instead of O(dn) when  $n, d \gg k$ Why no time savings for linear classifier?

- d = number of words in the vocabulary
- Each  $\mathbf{x}_i \in \mathbb{R}^d$  is a vector of word counts
- $\mathbf{x}_{ji} =$ frequency of word j in document i



- d = number of words in the vocabulary
- Each  $\mathbf{x}_i \in \mathbb{R}^d$  is a vector of word counts
- $\mathbf{x}_{ji} =$ frequency of word j in document i



How to measure similarity between two documents?  $\mathbf{z}_1^\top \mathbf{z}_2$  is probably better than  $\mathbf{x}_1^\top \mathbf{x}_2$ 

- d = number of words in the vocabulary
- Each  $\mathbf{x}_i \in \mathbb{R}^d$  is a vector of word counts
- $\mathbf{x}_{ji} =$ frequency of word j in document i



How to measure similarity between two documents?  $\mathbf{z}_1^\top \mathbf{z}_2$  is probably better than  $\mathbf{x}_1^\top \mathbf{x}_2$ Applications: information retrieval

- $\bullet$  d = number of words in the vocabulary
- Each  $\mathbf{x}_i \in \mathbb{R}^d$  is a vector of word counts
- $\mathbf{x}_{ji} =$ frequency of word j in document i



How to measure similarity between two documents?  $\mathbf{z}_1^\top \mathbf{z}_2$  is probably better than  $\mathbf{x}_1^\top \mathbf{x}_2$ Applications: information retrieval Note: no computational savings; original  $\mathbf{x}$  is already sparse

 $\mathbf{x}_{ji}$  = amount of traffic on link j in the network during each time interval i



 $\mathbf{x}_{ji}$  = amount of traffic on link j in the network during each time interval i



Model assumption: total traffic is sum of flows along a few "paths"

 $\mathbf{x}_{ji}$  = amount of traffic on link j in the network during each time interval i



Model assumption: total traffic is sum of flows along a few "paths" Apply PCA: each principal component intuitively represents a "path"

 $\mathbf{x}_{ji}$  = amount of traffic on link j in the network during each time interval i



Model assumption: total traffic is sum of flows along a few "paths" Apply PCA: each principal component intuitively represents a "path" Anomaly when traffic deviates from first few principal components

 $\mathbf{x}_{ji}$  = amount of traffic on link j in the network during each time interval i



Model assumption: total traffic is sum of flows along a few "paths" Apply PCA: each principal component intuitively represents a "path" Anomaly when traffic deviates from first few principal components



Principal component analysis (PCA) / Case studies

# Unsupervised POS tagging [Schütze, '95]

Part-of-speech (POS) tagging task:

Input: I like reducing the dimensionality of data . Output: NOUN VERB VERB(-ING) DET NOUN PREP NOUN . Unsupervised POS tagging [Schütze, '95]

Part-of-speech (POS) tagging task:

Input: I like reducing the dimensionality of data . Output: NOUN VERB VERB(-ING) DET NOUN PREP NOUN .

Each  $\mathbf{x}_i$  is (the context distribution of) a word.  $\mathbf{x}_{ji}$  is number of times word *i* appeared in context *j* Key idea: words appearing in similar contexts tend to have the same POS tags; so cluster using the contexts of each word type Problem: contexts are too sparse Unsupervised POS tagging [Schütze, '95]

Part-of-speech (POS) tagging task:

Input: I like reducing the dimensionality of data . Output: NOUN VERB VERB(-ING) DET NOUN PREP NOUN .

Each  $\mathbf{x}_i$  is (the context distribution of) a word.  $\mathbf{x}_{ii}$  is number of times word i appeared in context j Key idea: words appearing in similar contexts tend to have the same POS tags; so cluster using the contexts of each word type Problem: contexts are too sparse Solution: run PCA first, then cluster using new representation

Principal component analysis (PCA) / Case studies

# Multi-task learning [Ando & Zhang, '05]

- Have n related tasks (classify documents for various users)
- Each task has a linear classifier with weights  $\mathbf{x}_i$
- Want to share structure between classifiers

# Multi-task learning [Ando & Zhang, '05]

- Have n related tasks (classify documents for various users)
- Each task has a linear classifier with weights  $\mathbf{x}_i$
- Want to share structure between classifiers

#### One step of their procedure:

given n linear classifiers  $\mathbf{x}_1, \ldots, \mathbf{x}_n$ , run PCA to identify shared structure:
## Multi-task learning [Ando & Zhang, '05]

- Have n related tasks (classify documents for various users)
- Each task has a linear classifier with weights  $\mathbf{x}_i$
- Want to share structure between classifiers

## One step of their procedure: given n linear classifiers $\mathbf{x}_1, \ldots, \mathbf{x}_n$ , run PCA to identify shared structure: $\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \ldots \mathbf{x}_n \end{pmatrix} \cong \mathbf{UZ}$

## Multi-task learning [Ando & Zhang, '05]

- Have n related tasks (classify documents for various users)
- Each task has a linear classifier with weights  $\mathbf{x}_i$
- Want to share structure between classifiers

# One step of their procedure: given *n* linear classifiers $\mathbf{x}_1, \ldots, \mathbf{x}_n$ , run PCA to identify shared structure: $\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \ldots \mathbf{x}_n \\ | & | \end{pmatrix} \cong \mathbf{UZ}$

Each principal component is a eigen-classifier

## Multi-task learning [Ando & Zhang, '05]

- Have n related tasks (classify documents for various users)
- Each task has a linear classifier with weights  $\mathbf{x}_i$
- Want to share structure between classifiers

#### One step of their procedure: given n linear classifiers $\mathbf{x}_1, \ldots, \mathbf{x}_n$ , run PCA to identify shared structure:

$$\mathbf{X} = \begin{pmatrix} | & | \\ \mathbf{x}_1 \dots \mathbf{x}_n \\ | & | \end{pmatrix} \cong \mathbf{UZ}$$

Each principal component is a eigen-classifier

# Other step of their procedure: Retrain classifiers, regularizing towards subspace ${\bf U}$

Principal component analysis (PCA) / Case studies

• Intuition: capture variance of data or minimize reconstruction error

- Intuition: capture variance of data or minimize reconstruction error
- Algorithm: find eigendecomposition of covariance matrix or SVD

- Intuition: capture variance of data or minimize reconstruction error
- Algorithm: find eigendecomposition of covariance matrix or SVD
- Impact: reduce storage (from O(nd) to O(nk)), reduce time complexity

- Intuition: capture variance of data or minimize reconstruction error
- Algorithm: find eigendecomposition of covariance matrix or SVD
- Impact: reduce storage (from O(nd) to O(nk)), reduce time complexity
- Advantages: simple, fast

- Intuition: capture variance of data or minimize reconstruction error
- Algorithm: find eigendecomposition of covariance matrix or SVD
- Impact: reduce storage (from O(nd) to O(nk)), reduce time complexity
- Advantages: simple, fast
- Applications: eigen-faces, eigen-documents, network anomaly detection, etc.

## Roadmap



- Principal component analysis (PCA)
  - Basic principles
  - Case studies
  - Kernel PCA
  - Probabilistic PCA
- Canonical correlation analysis (CCA)
- Fisher discriminant analysis (FDA)
- Summary











#### Problem is that PCA subspace is linear: $S = \{ \mathbf{x} = \mathbf{U}\mathbf{z} : \mathbf{z} \in \mathbb{R}^k \}$

Principal component analysis (PCA) / Kernel PCA



## Problem is that PCA subspace is linear: $S = \{ \mathbf{x} = \mathbf{U}\mathbf{z} : \mathbf{z} \in \mathbb{R}^k \}$

In this example:

$$S = \{(x_1, x_2) : x_2 = \frac{u_2}{u_1} x_1\}$$

Principal component analysis (PCA) / Kernel PCA













Representer theorem:

PCA solution is linear combination of  $x_i$ s

Representer theorem:

PCA solution is linear combination of  $\mathbf{x}_i$ s Why?

Recall PCA eigenvalue problem:  $\mathbf{X}\mathbf{X}^{\top}\mathbf{u} = \lambda\mathbf{u}$ 

Representer theorem:

PCA solution is linear combination of  $\mathbf{x}_i$ s Why?

Recall PCA eigenvalue problem:  $\mathbf{X}\mathbf{X}^{\top}\mathbf{u} = \lambda\mathbf{u}$ Notice that  $\mathbf{u} = \mathbf{X}\boldsymbol{\alpha} = \sum_{i=1}^{n} \alpha_i \mathbf{x}_i$  for some weights  $\boldsymbol{\alpha}$ 

Representer theorem:

PCA solution is linear combination of  $\mathbf{x}_i$ s Why?

Recall PCA eigenvalue problem:  $\mathbf{X}\mathbf{X}^{\top}\mathbf{u} = \lambda\mathbf{u}$ Notice that  $\mathbf{u} = \mathbf{X}\boldsymbol{\alpha} = \sum_{i=1}^{n} \alpha_i \mathbf{x}_i$  for some weights  $\boldsymbol{\alpha}$ Analogy with SVMs: weight vector  $\mathbf{w} = \mathbf{X}\boldsymbol{\alpha}$ 

Representer theorem:

PCA solution is linear combination of  $\mathbf{x}_i$ s Why?

Recall PCA eigenvalue problem:  $\mathbf{X}\mathbf{X}^{\top}\mathbf{u} = \lambda\mathbf{u}$ Notice that  $\mathbf{u} = \mathbf{X}\boldsymbol{\alpha} = \sum_{i=1}^{n} \alpha_i \mathbf{x}_i$  for some weights  $\boldsymbol{\alpha}$ Analogy with SVMs: weight vector  $\mathbf{w} = \mathbf{X}\boldsymbol{\alpha}$ 

Key fact:

PCA only needs inner products  $K = \mathbf{X}^{\top} \mathbf{X}$ 

Representer theorem:

PCA solution is linear combination of  $\mathbf{x}_i$ s Why?

Recall PCA eigenvalue problem:  $\mathbf{X}\mathbf{X}^{\top}\mathbf{u} = \lambda\mathbf{u}$ Notice that  $\mathbf{u} = \mathbf{X}\boldsymbol{\alpha} = \sum_{i=1}^{n} \alpha_i \mathbf{x}_i$  for some weights  $\boldsymbol{\alpha}$ Analogy with SVMs: weight vector  $\mathbf{w} = \mathbf{X}\boldsymbol{\alpha}$ 

Key fact:

PCA only needs inner products  $K = \mathbf{X}^{\top} \mathbf{X}$ Why?

Use representer theorem on PCA objective:

$$\max_{\|\mathbf{u}\|=1} \mathbf{u}^{\top} \mathbf{X} \mathbf{X}^{\top} \mathbf{u} = \max_{\boldsymbol{\alpha}^{\top} \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\alpha} = 1} \boldsymbol{\alpha}^{\top} (\mathbf{X}^{\top} \mathbf{X}) (\mathbf{X}^{\top} \mathbf{X}) \boldsymbol{\alpha}$$

Principal component analysis (PCA) / Kernel PCA

Kernel function:  $k(\mathbf{x}_1, \mathbf{x}_2)$  such that K, the kernel matrix formed by  $K_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ , is positive semi-definite

Kernel function:  $k(\mathbf{x}_1, \mathbf{x}_2)$  such that K, the kernel matrix formed by  $K_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ , is positive semi-definite

Examples:

Linear kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = \mathbf{x}_1^\top \mathbf{x}_2$ 

Kernel function:  $k(\mathbf{x}_1, \mathbf{x}_2)$  such that K, the kernel matrix formed by  $K_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ , is positive semi-definite

Examples:

Linear kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = \mathbf{x}_1^\top \mathbf{x}_2$ Polynomial kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = (1 + \mathbf{x}_1^\top \mathbf{x}_2)^2$ 

Kernel function:  $k(\mathbf{x}_1, \mathbf{x}_2)$  such that K, the kernel matrix formed by  $K_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ , is positive semi-definite

Examples:

Linear kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = \mathbf{x}_1^\top \mathbf{x}_2$ Polynomial kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = (1 + \mathbf{x}_1^\top \mathbf{x}_2)^2$ Gaussian (RBF) kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = e^{-\|\mathbf{x}_1 - \mathbf{x}_2\|^2}$ 

Kernel function:  $k(\mathbf{x}_1, \mathbf{x}_2)$  such that K, the kernel matrix formed by  $K_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ , is positive semi-definite

Examples:

Linear kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = \mathbf{x}_1^\top \mathbf{x}_2$ Polynomial kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = (1 + \mathbf{x}_1^\top \mathbf{x}_2)^2$ Gaussian (RBF) kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = e^{-\|\mathbf{x}_1 - \mathbf{x}_2\|^2}$ 

Treat data points  $\mathbf{x}$  as black boxes, only access via k

Kernel function:  $k(\mathbf{x}_1, \mathbf{x}_2)$  such that K, the kernel matrix formed by  $K_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ , is positive semi-definite

Examples:

Linear kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = \mathbf{x}_1^\top \mathbf{x}_2$ Polynomial kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = (1 + \mathbf{x}_1^\top \mathbf{x}_2)^2$ Gaussian (RBF) kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = e^{-\|\mathbf{x}_1 - \mathbf{x}_2\|^2}$ 

Treat data points  ${\bf x}$  as black boxes, only access via k k intuitively measures "similarity" between two inputs

Kernel function:  $k(\mathbf{x}_1, \mathbf{x}_2)$  such that K, the kernel matrix formed by  $K_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ ,

is positive semi-definite

Examples:

Linear kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = \mathbf{x}_1^\top \mathbf{x}_2$ Polynomial kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = (1 + \mathbf{x}_1^\top \mathbf{x}_2)^2$ Gaussian (RBF) kernel:  $k(\mathbf{x}_1, \mathbf{x}_2) = e^{-\|\mathbf{x}_1 - \mathbf{x}_2\|^2}$ 

Treat data points  ${\bf x}$  as black boxes, only access via k k intuitively measures "similarity" between two inputs

Mercer's theorem (using kernels is sensible) Exists high-dimensional feature space  $\phi$  such that  $k(\mathbf{x}_1, \mathbf{x}_2) = \phi(\mathbf{x}_1)^{\top} \phi(\mathbf{x}_2)$  (like quick solution earlier!)

## Solving kernel PCA

Direct method:

Kernel PCA objective:

 $\max_{\boldsymbol{\alpha}^\top K \boldsymbol{\alpha} = 1} \boldsymbol{\alpha}^\top K^2 \boldsymbol{\alpha}$ 

## Solving kernel PCA

Direct method:

Kernel PCA objective:

 $\begin{array}{l} \max_{\boldsymbol{\alpha}^{\top} K \boldsymbol{\alpha} = 1} \boldsymbol{\alpha}^{\top} K^{2} \boldsymbol{\alpha} \\ \Rightarrow \text{ kernel PCA eigenvalue problem: } \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\alpha} = \lambda' \boldsymbol{\alpha} \end{array}$
## Solving kernel PCA

Direct method:

Kernel PCA objective:

 $\begin{array}{l} \max_{\boldsymbol{\alpha}^{\top} K \boldsymbol{\alpha} = 1} \boldsymbol{\alpha}^{\top} K^{2} \boldsymbol{\alpha} \\ \Rightarrow \text{ kernel PCA eigenvalue problem: } \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\alpha} = \lambda' \boldsymbol{\alpha} \end{array}$ 

Modular method (if you don't want to think about kernels): Find vectors  $\mathbf{x}'_1, \ldots, \mathbf{x}'_n$  such that  $\mathbf{x}'_i^\top \mathbf{x}'_i = K_{ij} = \phi(\mathbf{x}_i)^\top \phi(\mathbf{x}_j)$ 

Principal component analysis (PCA) / Kernel PCA

## Solving kernel PCA

Direct method:

Kernel PCA objective:

 $\begin{array}{l} \max_{\boldsymbol{\alpha}^{\top} K \boldsymbol{\alpha} = 1} \boldsymbol{\alpha}^{\top} K^{2} \boldsymbol{\alpha} \\ \Rightarrow \text{ kernel PCA eigenvalue problem: } \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\alpha} = \lambda' \boldsymbol{\alpha} \end{array}$ 

Modular method (if you don't want to think about kernels): Find vectors  $\mathbf{x}'_1, \ldots, \mathbf{x}'_n$  such that  $\mathbf{x}'_i^\top \mathbf{x}'_j = K_{ij} = \phi(\mathbf{x}_i)^\top \phi(\mathbf{x}_j)$ 

Key: use any vectors that preserve inner products

## Solving kernel PCA

Direct method:

Kernel PCA objective:

 $\begin{array}{l} \max_{\boldsymbol{\alpha}^{\top} K \boldsymbol{\alpha} = 1} \boldsymbol{\alpha}^{\top} K^{2} \boldsymbol{\alpha} \\ \Rightarrow \text{ kernel PCA eigenvalue problem: } \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\alpha} = \lambda' \boldsymbol{\alpha} \end{array}$ 

Modular method (if you don't want to think about kernels): Find vectors  $\mathbf{x}'_1, \ldots, \mathbf{x}'_n$  such that  $\mathbf{x}'_i^\top \mathbf{x}'_j = K_{ij} = \phi(\mathbf{x}_i)^\top \phi(\mathbf{x}_j)$ Key: use any vectors that preserve inner products

One possibility is Cholesky decomposition  $K = \mathbf{X}^{\top} \mathbf{X}$ 

# Roadmap



- Principal component analysis (PCA)
  - Basic principles
  - Case studies
  - Kernel PCA
  - Probabilistic PCA
- Canonical correlation analysis (CCA)
- Fisher discriminant analysis (FDA)
- Summary

So far, deal with objective functions:  $\min_{\mathbf{U}} f(\mathbf{X}, \mathbf{U})$ 

So far, deal with objective functions:  $\min_{\mathbf{U}} f(\mathbf{X}, \mathbf{U})$ Probabilistic modeling:  $\max_{\mathbf{U}} p(\mathbf{X} \mid \mathbf{U})$ 

 $\max_{\mathbf{T}} p(\mathbf{X} \mid \mathbf{U})$ 

So far, deal with objective functions:  $\min_{\mathbf{U}} f(\mathbf{X}, \mathbf{U})$ Probabilistic modeling:

Invent a generative story of how data  $\mathbf{X}$  arose Play detective: infer parameters  $\mathbf{U}$  that produced  $\mathbf{X}$ 

 $\max_{\mathbf{T}} p(\mathbf{X} \mid \mathbf{U})$ 

So far, deal with objective functions:  $\min_{\mathbf{U}} f(\mathbf{X}, \mathbf{U})$ 

Probabilistic modeling:

Invent a generative story of how data  ${\bf X}$  arose Play detective: infer parameters  ${\bf U}$  that produced  ${\bf X}$ 

Advantages:

- Model reports estimates of uncertainty
- Natural way to handle missing data

 $\max_{\mathbf{T}} p(\mathbf{X} \mid \mathbf{U})$ 

So far, deal with objective functions:  $\min_{\mathbf{U}} f(\mathbf{X}, \mathbf{U})$ 

Probabilistic modeling:

Invent a generative story of how data  ${\bf X}$  arose Play detective: infer parameters  ${\bf U}$  that produced  ${\bf X}$ 

Advantages:

- Model reports estimates of uncertainty
- Natural way to handle missing data
- Natural way to introduce prior knowledge
- Natural way to incorporate in a larger model

 $\max_{\mathbf{T}} p(\mathbf{X} \mid \mathbf{U})$ 

So far, deal with objective functions:  $\min_{\mathbf{U}} f(\mathbf{X}, \mathbf{U})$ 

Probabilistic modeling:

Invent a generative story of how data  ${\bf X}$  arose Play detective: infer parameters  ${\bf U}$  that produced  ${\bf X}$ 

Advantages:

- Model reports estimates of uncertainty
- Natural way to handle missing data
- Natural way to introduce prior knowledge
- Natural way to incorporate in a larger model

Example from last lecture: k-means  $\Rightarrow$  GMMs

#### Generative story [Tipping and Bishop, 1999]:

For each data point  $i = 1, \ldots, n$ :

#### Generative story [Tipping and Bishop, 1999]:

For each data point i = 1, ..., n: Draw the latent vector:  $\mathbf{z}_i \sim \mathcal{N}(0, I_{k \times k})$ 

#### Generative story [Tipping and Bishop, 1999]:

For each data point i = 1, ..., n: Draw the latent vector:  $\mathbf{z}_i \sim \mathcal{N}(0, I_{k \times k})$ Create the data point:  $\mathbf{x}_i \sim \mathcal{N}(\mathbf{U}\mathbf{z}_i, \sigma^2 I_{d \times d})$ 

Generative story [Tipping and Bishop, 1999]:

For each data point i = 1, ..., n: Draw the latent vector:  $\mathbf{z}_i \sim \mathcal{N}(0, I_{k \times k})$ Create the data point:  $\mathbf{x}_i \sim \mathcal{N}(\mathbf{U}\mathbf{z}_i, \sigma^2 I_{d \times d})$ 

PCA finds the  $\mathbf{U}$  that maximizes the likelihood of the data

Generative story [Tipping and Bishop, 1999]:

For each data point i = 1, ..., n: Draw the latent vector:  $\mathbf{z}_i \sim \mathcal{N}(0, I_{k \times k})$ Create the data point:  $\mathbf{x}_i \sim \mathcal{N}(\mathbf{U}\mathbf{z}_i, \sigma^2 I_{d \times d})$ 

PCA finds the  ${\bf U}$  that maximizes the likelihood of the data

Advantages:

• Handles missing data (important for collaborative filtering)

Generative story [Tipping and Bishop, 1999]:

For each data point i = 1, ..., n: Draw the latent vector:  $\mathbf{z}_i \sim \mathcal{N}(0, I_{k \times k})$ Create the data point:  $\mathbf{x}_i \sim \mathcal{N}(\mathbf{U}\mathbf{z}_i, \sigma^2 I_{d \times d})$ 

PCA finds the  ${\bf U}$  that maximizes the likelihood of the data

Advantages:

- Handles missing data (important for collaborative filtering)
- Extension to factor analysis: allow non-isotropic noise (replace  $\sigma^2 I_{d \times d}$  with arbitrary diagonal matrix)

Motivation: in text analysis,  $\mathbf{X}$  contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this

Motivation: in text analysis,  $\mathbf{X}$  contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this Generative story for pLSA [Hofmann, 1999]:

For each document  $i = 1, \ldots, n$ :

Motivation: in text analysis,  $\mathbf{X}$  contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this Generative story for pLSA [Hofmann, 1999]:

For each document  $i = 1, \ldots, n$ :

Repeat M times (number of word tokens in document):

Motivation: in text analysis,  $\mathbf{X}$  contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this Generative story for pLSA [Hofmann, 1999]:

For each document i = 1, ..., n: Repeat M times (number of word tokens in document): Draw a latent topic:  $\mathbf{z} \sim p(\mathbf{z} \mid i)$ 

Motivation: in text analysis,  $\mathbf{X}$  contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this Generative story for pLSA [Hofmann, 1999]:

For each document i = 1, ..., n: Repeat M times (number of word tokens in document): Draw a latent topic:  $\mathbf{z} \sim p(\mathbf{z} \mid i)$ Choose the word token:  $\mathbf{x} \sim p(\mathbf{x} \mid \mathbf{z})$ 

Motivation: in text analysis,  $\mathbf{X}$  contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this Generative story for pLSA [Hofmann, 1999]:

For each document i = 1, ..., n: Repeat M times (number of word tokens in document): Draw a latent topic:  $\mathbf{z} \sim p(\mathbf{z} \mid i)$ Choose the word token:  $\mathbf{x} \sim p(\mathbf{x} \mid \mathbf{z})$ Set  $\mathbf{x}_{ji}$  to be the number of times word j was chosen

Motivation: in text analysis, **X** contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this Generative story for pLSA [Hofmann, 1999]:

For each document i = 1, ..., n: Repeat M times (number of word tokens in document): Draw a latent topic:  $\mathbf{z} \sim p(\mathbf{z} \mid i)$ Choose the word token:  $\mathbf{x} \sim p(\mathbf{x} \mid \mathbf{z})$ Set  $\mathbf{x}_{ji}$  to be the number of times word j was chosen

Learning using Hard EM (analog of k-means):
 E-step: fix parameters, choose best topics
 M-step: fix topics, optimize parameters
 More sophisticated methods: EM, Latent Dirichlet Allocation

Motivation: in text analysis,  $\mathbf{X}$  contains word counts; PCA (LSA) is bad model as it allows negative counts; pLSA fixes this Generative story for pLSA [Hofmann, 1999]:

For each document  $i = 1, \ldots, n$ :

Repeat M times (number of word tokens in document):

Draw a latent topic:  $\mathbf{z} \sim p(\mathbf{z} \mid i)$ 

Choose the word token:  $\mathbf{x} \sim p(\mathbf{x} \mid \mathbf{z})$ 

Set  $\mathbf{x}_{ji}$  to be the number of times word j was chosen

Learning using Hard EM (analog of k-means):

E-step: fix parameters, choose best topics

M-step: fix topics, optimize parameters

More sophisticated methods: EM, Latent Dirichlet Allocation Comparison to a mixture model for clustering:

Mixture model: assume a single topic for entire document pLSA: allow multiple topics per document

Principal component analysis (PCA) / Probabilistic PCA

# Roadmap



- Principal component analysis (PCA)
  - Basic principles
  - Case studies
  - Kernel PCA
  - Probabilistic PCA
- Canonical correlation analysis (CCA)
- Fisher discriminant analysis (FDA)
- Summary

Often, each data point consists of two views:

- Image retrieval: for each image, have the following:
  - $-\mathbf{x}$ : Pixels (or other visual features)
  - $-\mathbf{y}$ : Text around the image

Often, each data point consists of two views:

- Image retrieval: for each image, have the following:
  - $-\mathbf{x}$ : Pixels (or other visual features)
  - $-\mathbf{y}$ : Text around the image
- Time series:
  - $-\mathbf{x}$ : Signal at time t
  - $-\mathbf{y}$ : Signal at time t+1

Often, each data point consists of two views:

- Image retrieval: for each image, have the following:
  - $-\mathbf{x}$ : Pixels (or other visual features)
  - $-\mathbf{y}$ : Text around the image
- Time series:
  - $-\mathbf{x}$ : Signal at time t
  - $-\mathbf{y}$ : Signal at time t+1
- Two-view learning: divide features into two sets
  - -x: Features of a word/object, etc.
  - $-\mathbf{y}$ : Features of the context in which it appears

Often, each data point consists of two views:

- Image retrieval: for each image, have the following:
  - $-\mathbf{x}$ : Pixels (or other visual features)
  - $-\mathbf{y}$ : Text around the image
- Time series:
  - $-\mathbf{x}$ : Signal at time t
  - $-\mathbf{y}$ : Signal at time t+1
- Two-view learning: divide features into two sets
  - $-\mathbf{x}$ : Features of a word/object, etc.
  - $-\mathbf{y}$ : Features of the context in which it appears

Goal: reduce the dimensionality of the two views jointly

Setup:

Input data:  $(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_n, \mathbf{y}_n)$  (matrices  $\mathbf{X}, \mathbf{Y}$ ) Goal: find pair of projections  $(\mathbf{u}, \mathbf{v})$ 

Setup:

Input data:  $(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_n, \mathbf{y}_n)$  (matrices  $\mathbf{X}, \mathbf{Y}$ ) Goal: find pair of projections  $(\mathbf{u}, \mathbf{v})$ 

In figure,  $\mathbf{x}$  and  $\mathbf{y}$  are paired by brightness



Setup:

Input data:  $(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_n, \mathbf{y}_n)$  (matrices  $\mathbf{X}, \mathbf{Y}$ ) Goal: find pair of projections  $(\mathbf{u}, \mathbf{v})$ 

In figure,  ${\bf x}$  and  ${\bf y}$  are paired by brightness

Dimensionality reduction solutions:



Setup:

Input data:  $(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_n, \mathbf{y}_n)$  (matrices  $\mathbf{X}, \mathbf{Y}$ ) Goal: find pair of projections  $(\mathbf{u}, \mathbf{v})$ 

In figure,  ${\bf x}$  and  ${\bf y}$  are paired by brightness

Dimensionality reduction solutions:



#### From PCA to CCA

PCA on views separately: no covariance term

$$\max_{\mathbf{u},\mathbf{v}} \frac{\mathbf{u}^{\top} \mathbf{X} \mathbf{X}^{\top} \mathbf{u}}{\mathbf{u}^{\top} \mathbf{u}} + \frac{\mathbf{v}^{\top} \mathbf{Y} \mathbf{Y}^{\top} \mathbf{v}}{\mathbf{v}^{\top} \mathbf{v}}$$

# From PCA to CCA

PCA on views separately: no covariance term  $\begin{array}{l} \max_{\mathbf{u},\mathbf{v}} \frac{\mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}}{\mathbf{u}^{\top}\mathbf{u}} + \frac{\mathbf{v}^{\top}\mathbf{Y}\mathbf{Y}^{\top}\mathbf{v}}{\mathbf{v}^{\top}\mathbf{v}} \\
\end{array}$ PCA on concatenation  $(\mathbf{X}^{\top}, \mathbf{Y}^{\top})^{\top}$ : includes covariance term  $\begin{array}{l} \max_{\mathbf{u},\mathbf{v}} \frac{\mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u} + 2\mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v} + \mathbf{v}^{\top}\mathbf{Y}\mathbf{Y}^{\top}\mathbf{v}}{\mathbf{u}^{\top}\mathbf{u} + \mathbf{v}^{\top}\mathbf{v}} \\
\end{array}$ 

# From PCA to CCA

PCA on views separately: no covariance term  $\max_{\mathbf{u},\mathbf{v}} \frac{\mathbf{u}^\top \mathbf{X} \mathbf{X}^\top \mathbf{u}}{\mathbf{u}^\top \mathbf{u}} + \frac{\mathbf{v}^\top \mathbf{Y} \mathbf{Y}^\top \mathbf{v}}{\mathbf{v}^\top \mathbf{v}}$ PCA on concatenation  $(\mathbf{X}^{\top}, \mathbf{Y}^{\top})^{\top}$ : includes covariance term  $\mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u} + 2\mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v} + \mathbf{v}^{\top}\mathbf{Y}\mathbf{Y}^{\top}\mathbf{v}$ max – nax ——— u,v  $\mathbf{u}^{\top}\mathbf{u} + \mathbf{v}^{\top}\mathbf{v}$ Maximum covariance: drop variance terms  $\max_{\mathbf{u},\mathbf{v}} \frac{\mathbf{u}^{\top} \mathbf{X} \mathbf{Y}^{\top} \mathbf{v}}{\sqrt{\mathbf{u}^{\top} \mathbf{u}} \sqrt{\mathbf{v}^{\top} \mathbf{v}}}$
## From PCA to CCA



Canonical correlation analysis (CCA)

Definitions:

Variance:  $\widehat{var}(\mathbf{u}^{\top}\mathbf{x}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}$ 

Definitions:

Variance:  $\widehat{var}(\mathbf{u}^{\top}\mathbf{x}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}$ Covariance:  $\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v}$ 

Definitions:

Variance:  $\widehat{var}(\mathbf{u}^{\top}\mathbf{x}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}$ Covariance:  $\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v}$ Correlation:  $\frac{\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y})}{\sqrt{\widehat{var}(\mathbf{u}^{\top}\mathbf{x})}\sqrt{\widehat{var}(\mathbf{v}^{\top}\mathbf{y})}}$ 

Definitions:

Variance:  $\widehat{var}(\mathbf{u}^{\top}\mathbf{x}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}$ Covariance:  $\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v}$ Correlation:  $\frac{\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y})}{\sqrt{\widehat{var}(\mathbf{u}^{\top}\mathbf{x})}\sqrt{\widehat{var}(\mathbf{v}^{\top}\mathbf{y})}}$ 

Objective: maximize correlation between projected views  $\max_{\mathbf{u},\mathbf{v}} \widehat{\operatorname{corr}}(\mathbf{u}^{\top}\mathbf{x},\mathbf{v}^{\top}\mathbf{y})$ 

Definitions:

Variance: 
$$\widehat{var}(\mathbf{u}^{\top}\mathbf{x}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}$$
  
Covariance:  $\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v}$   
Correlation:  $\frac{\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y})}{\sqrt{\widehat{var}(\mathbf{u}^{\top}\mathbf{x})}\sqrt{\widehat{var}(\mathbf{v}^{\top}\mathbf{y})}}$ 

Objective: maximize correlation between projected views  $\max_{\mathbf{u},\mathbf{v}}\widehat{corr}(\mathbf{u}^{\top}\mathbf{x},\mathbf{v}^{\top}\mathbf{y})$ 

**Properties:** 

• Focus on how variables are related, not how much they vary

Definitions:

Variance: 
$$\widehat{var}(\mathbf{u}^{\top}\mathbf{x}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}$$
  
Covariance:  $\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v}$   
Correlation:  $\frac{\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y})}{\sqrt{\widehat{var}(\mathbf{u}^{\top}\mathbf{x})}\sqrt{\widehat{var}(\mathbf{v}^{\top}\mathbf{y})}}$ 

Objective: maximize correlation between projected views  $\max_{\mathbf{u},\mathbf{v}} \widehat{corr}(\mathbf{u}^{\top}\mathbf{x},\mathbf{v}^{\top}\mathbf{y})$ 

Properties:

- Focus on how variables are related, not how much they vary
- Invariant to any rotation and scaling of data

Definitions:

Variance: 
$$\widehat{var}(\mathbf{u}^{\top}\mathbf{x}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{X}^{\top}\mathbf{u}$$
  
Covariance:  $\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y}) = \mathbf{u}^{\top}\mathbf{X}\mathbf{Y}^{\top}\mathbf{v}$   
Correlation:  $\frac{\widehat{cov}(\mathbf{u}^{\top}\mathbf{x}, \mathbf{v}^{\top}\mathbf{y})}{\sqrt{\widehat{var}(\mathbf{u}^{\top}\mathbf{x})}\sqrt{\widehat{var}(\mathbf{v}^{\top}\mathbf{y})}}$ 

Objective: maximize correlation between projected views  $\max_{\mathbf{u},\mathbf{v}} \widehat{corr}(\mathbf{u}^{\top}\mathbf{x},\mathbf{v}^{\top}\mathbf{y})$ 

**Properties:** 

- Focus on how variables are related, not how much they vary
- Invariant to any rotation and scaling of data

Solved via a generalized eigenvalue problem ( $A\mathbf{w} = \lambda B\mathbf{w}$ )

Canonical correlation analysis (CCA)

Extreme examples of degeneracy:

• If  $\mathbf{x} = A\mathbf{y}$ , then any  $(\mathbf{u}, \mathbf{v})$  with  $\mathbf{u} = A\mathbf{v}$  is optimal (correlation 1)

Extreme examples of degeneracy:

- If  $\mathbf{x} = A\mathbf{y}$ , then any  $(\mathbf{u}, \mathbf{v})$  with  $\mathbf{u} = A\mathbf{v}$  is optimal (correlation 1)
- If x and y are independent, then any (u, v) is optimal (correlation 0)

Extreme examples of degeneracy:

- If  $\mathbf{x} = A\mathbf{y}$ , then any  $(\mathbf{u}, \mathbf{v})$  with  $\mathbf{u} = A\mathbf{v}$  is optimal (correlation 1)
- If x and y are independent, then any (u, v) is optimal (correlation 0)

Problem: if **X** or **Y** has rank *n*, then any  $(\mathbf{u}, \mathbf{v})$  is optimal (correlation 1) with  $\mathbf{u} = \mathbf{X}^{\dagger \top} \mathbf{Y} \mathbf{v} \Rightarrow \text{CCA}$  is meaningless!

Extreme examples of degeneracy:

- If  $\mathbf{x} = A\mathbf{y}$ , then any  $(\mathbf{u}, \mathbf{v})$  with  $\mathbf{u} = A\mathbf{v}$  is optimal (correlation 1)
- If x and y are independent, then any (u, v) is optimal (correlation 0)

**Problem:** if X or Y has rank n, then any  $(\mathbf{u}, \mathbf{v})$  is optimal

(correlation 1) with  $\mathbf{u} = \mathbf{X}^{\dagger \top} \mathbf{Y} \mathbf{v} \Rightarrow \mathsf{CCA}$  is meaningless!

Solution: regularization (interpolate between

maximum covariance and maximum correlation)

$$\max_{\mathbf{u},\mathbf{v}} \frac{\mathbf{u}^{\top} \mathbf{X} \mathbf{Y}^{\top} \mathbf{v}}{\sqrt{\mathbf{u}^{\top} (\mathbf{X} \mathbf{X}^{\top} + \lambda I) \mathbf{u}} \sqrt{\mathbf{v}^{\top} (\mathbf{Y} \mathbf{Y}^{\top} + \lambda I) \mathbf{v}}}$$

Two kernels:  $k_x$  and  $k_y$ 

Two kernels:  $k_x$  and  $k_y$ Direct method:

(some math)

Two kernels:  $k_x$  and  $k_y$ Direct method: (some math)

Modular method:

1. Transform  $\mathbf{x}_i$  into  $\mathbf{x}'_i \in \mathbb{R}^n$  satisfying  $k(\mathbf{x}_i, \mathbf{x}_j) = \mathbf{x}'^{\top}_i \mathbf{x}'_j$  (do same for  $\mathbf{y}$ )

Two kernels:  $k_x$  and  $k_y$ Direct method: (some math)

Modular method:

- 1. Transform  $\mathbf{x}_i$  into  $\mathbf{x}'_i \in \mathbb{R}^n$  satisfying  $k(\mathbf{x}_i, \mathbf{x}_j) = \mathbf{x}'_i^\top \mathbf{x}'_j$  (do same for  $\mathbf{y}$ )
- 2. Perform regular CCA

Two kernels:  $k_x$  and  $k_y$ Direct method: (some math)

Modular method:

- 1. Transform  $\mathbf{x}_i$  into  $\mathbf{x}'_i \in \mathbb{R}^n$  satisfying  $k(\mathbf{x}_i, \mathbf{x}_j) = \mathbf{x}'_i^\top \mathbf{x}'_j$  (do same for  $\mathbf{y}$ )
- 2. Perform regular CCA

Regularization is especially important for kernel CCA!

# Roadmap



- Principal component analysis (PCA)
  - Basic principles
  - Case studies
  - Kernel PCA
  - Probabilistic PCA
- Canonical correlation analysis (CCA)
- Fisher discriminant analysis (FDA)
- Summary

What is the best linear projection?



What is the best linear projection?

PCA solution

What is the best linear projection with these labels?



What is the best linear projection with these labels?



What is the best linear projection with these labels?



Goal: reduce the dimensionality given labels

Idea: want projection to maximize overall interclass variance relative to intraclass variance

What is the best linear projection with these labels?



Goal: reduce the dimensionality given labels

- Idea: want projection to maximize overall interclass variance relative to intraclass variance
- Linear classifiers (logistic regression, SVMs) have similar feel: Find one-dimensional subspace  $\mathbf{w}$ ,
  - e.g., to maximize margin between different classes

What is the best linear projection with these labels?



Goal: reduce the dimensionality given labels

- Idea: want projection to maximize overall interclass variance relative to intraclass variance
- Linear classifiers (logistic regression, SVMs) have similar feel: Find one-dimensional subspace w,
  - e.g., to maximize margin between different classes
- FDA handles multiple classes, allows multiple dimensions

Setup:  $\mathbf{x}_i \in \mathbb{R}^d, \mathbf{y}_i \in \{1, \dots, m\}$ , for  $i = 1, \dots, n$ 

Setup:  $\mathbf{x}_i \in \mathbb{R}^d, \mathbf{y}_i \in \{1, \dots, m\}$ , for  $i = 1, \dots, n$ Objective: maximize  $\frac{\text{interclass variance}}{\text{intraclass variance}} = \frac{\text{total variance}}{\text{intraclass variance}} - 1$ 

Setup:  $\mathbf{x}_i \in \mathbb{R}^d, y_i \in \{1, \dots, m\}$ , for  $i = 1, \dots, n$ Objective: maximize  $\frac{\text{interclass variance}}{\text{intraclass variance}} = \frac{\text{total variance}}{\text{intraclass variance}} - 1$ 

Total variance:  $\frac{1}{n} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}_{i} - \mu))^{2}$ Mean of all points:  $\mu = \frac{1}{n} \sum_{i} \mathbf{x}_{i}$ 

Setup:  $\mathbf{x}_i \in \mathbb{R}^d, y_i \in \{1, \dots, m\}$ , for  $i = 1, \dots, n$ Objective: maximize  $\frac{\text{interclass variance}}{\text{intraclass variance}} = \frac{\text{total variance}}{\text{intraclass variance}} - 1$ 

Total variance:  $\frac{1}{n} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}_{i} - \mu))^{2}$ Mean of all points:  $\mu = \frac{1}{n} \sum_{i} \mathbf{x}_{i}$ 

Intraclass variance:  $\frac{1}{n} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}_{i} - \mu_{\mathbf{y}_{i}}))^{2}$ Mean of points in class y:  $\mu_{y} = \frac{1}{|\{i: \mathbf{y}_{i} = y\}|} \sum_{i: \mathbf{y}_{i} = y} \mathbf{x}_{i}$ 

Setup:  $\mathbf{x}_i \in \mathbb{R}^d, y_i \in \{1, \dots, m\}$ , for  $i = 1, \dots, n$ Objective: maximize  $\frac{\text{interclass variance}}{\text{intraclass variance}} = \frac{\text{total variance}}{\text{intraclass variance}} - 1$ 

Total variance:  $\frac{1}{n} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}_{i} - \mu))^{2}$ Mean of all points:  $\mu = \frac{1}{n} \sum_{i} \mathbf{x}_{i}$ 

Intraclass variance:  $\frac{1}{n} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}_{i} - \mu_{\mathbf{y}_{i}}))^{2}$ Mean of points in class y:  $\mu_{y} = \frac{1}{|\{i: \mathbf{y}_{i} = y\}|} \sum_{i: \mathbf{y}_{i} = y} \mathbf{x}_{i}$ 

Reduces to a generalized eigenvalue problem.

Setup:  $\mathbf{x}_i \in \mathbb{R}^d, y_i \in \{1, \dots, m\}$ , for  $i = 1, \dots, n$ Objective: maximize  $\frac{\text{interclass variance}}{\text{intraclass variance}} = \frac{\text{total variance}}{\text{intraclass variance}} - 1$ 

Total variance:  $\frac{1}{n} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}_{i} - \mu))^{2}$ Mean of all points:  $\mu = \frac{1}{n} \sum_{i} \mathbf{x}_{i}$ 

Intraclass variance:  $\frac{1}{n} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}_{i} - \mu_{\mathbf{y}_{i}}))^{2}$ Mean of points in class y:  $\mu_{y} = \frac{1}{|\{i: \mathbf{y}_{i} = y\}|} \sum_{i: \mathbf{y}_{i} = y} \mathbf{x}_{i}$ 

Reduces to a generalized eigenvalue problem.

Kernel FDA: use modular method

Fisher discriminant analysis (FDA)

Random projections:

Randomly project data onto  $k = O(\log n)$  dimensions

Random projections:

Randomly project data onto  $k = O(\log n)$  dimensions All pairwise distances preserved with high probability  $\|\mathbf{U}^{\top}\mathbf{x}_{i} - \mathbf{U}^{\top}\mathbf{x}_{j}\|^{2} \approx \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2}$  for all i, j

Random projections:

Randomly project data onto  $k = O(\log n)$  dimensions All pairwise distances preserved with high probability  $\|\mathbf{U}^{\top}\mathbf{x}_{i} - \mathbf{U}^{\top}\mathbf{x}_{j}\|^{2} \approx \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2}$  for all i, j

Trivial to implement

#### Random projections:

Randomly project data onto  $k = O(\log n)$  dimensions All pairwise distances preserved with high probability  $\|\mathbf{U}^{\top}\mathbf{x}_{i} - \mathbf{U}^{\top}\mathbf{x}_{j}\|^{2} \approx \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2}$  for all i, jTrivial to implement

Kernel dimensionality reduction:

One type of sufficient dimensionality reduction Find subspace that contains all information about labels

#### Random projections:

Randomly project data onto  $k = O(\log n)$  dimensions All pairwise distances preserved with high probability  $\|\mathbf{U}^{\top}\mathbf{x}_{i} - \mathbf{U}^{\top}\mathbf{x}_{j}\|^{2} \approx \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2}$  for all i, jTrivial to implement

Trivial to implement

#### Kernel dimensionality reduction:

One type of sufficient dimensionality reduction Find subspace that contains all <u>information</u> about labels

 $\mathbf{y} \perp \mathbf{x} \mid \mathbf{U}^{\top} \mathbf{x}$
## Other linear methods

### Random projections:

Randomly project data onto  $k = O(\log n)$  dimensions All pairwise distances preserved with high probability  $\|\mathbf{U}^{\top}\mathbf{x}_{i} - \mathbf{U}^{\top}\mathbf{x}_{j}\|^{2} \approx \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2}$  for all i, jTrivial to implement

Z I II II II II

### Kernel dimensionality reduction:

One type of sufficient dimensionality reduction Find subspace that contains all <u>information</u> about labels

 $\mathbf{y} \perp \mathbf{x} \mid \mathbf{U}^{\top} \mathbf{x}$ 

Capturing information is stronger than capturing variance

## Other linear methods

### Random projections:

Randomly project data onto  $k = O(\log n)$  dimensions All pairwise distances preserved with high probability  $\|\mathbf{U}^{\top}\mathbf{x}_{i} - \mathbf{U}^{\top}\mathbf{x}_{j}\|^{2} \approx \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2}$  for all i, jTrivial to implement

Trivial to implement

### Kernel dimensionality reduction:

One type of sufficient dimensionality reduction Find subspace that contains all <u>information</u> about labels

### $\mathbf{y} \perp\!\!\!\perp \mathbf{x} \mid \mathbf{U}^\top \mathbf{x}$

Capturing information is stronger than capturing variance Hard nonconvex optimization problem

Fisher discriminant analysis (FDA)

Framework:  $\mathbf{z} = \mathbf{U}^{\top} \mathbf{x}, \ \mathbf{x} \cong \mathbf{U} \mathbf{z}$ 

Framework:  $\mathbf{z} = \mathbf{U}^{\top} \mathbf{x}, \ \mathbf{x} \cong \mathbf{U} \mathbf{z}$ 

Criteria for choosing U:

- PCA: maximize projected variance
- CCA: maximize projected correlation
- FDA: maximize projected interclass variance intraclass variance

Framework:  $\mathbf{z} = \mathbf{U}^{\top} \mathbf{x}, \ \mathbf{x} \cong \mathbf{U} \mathbf{z}$ 

Criteria for choosing U:

- PCA: maximize projected variance
- CCA: maximize projected correlation
- FDA: maximize projected interclass variance intraclass variance

Algorithm: generalized eigenvalue problem

Framework:  $\mathbf{z} = \mathbf{U}^{\top} \mathbf{x}, \ \mathbf{x} \cong \mathbf{U} \mathbf{z}$ 

Criteria for choosing U:

- PCA: maximize projected variance
- CCA: maximize projected correlation
- FDA: maximize projected interclass variance intraclass variance

Algorithm: generalized eigenvalue problem Extensions:

non-linear using kernels (using same linear framework) probabilistic, sparse, robust (hard optimization)